

Jerry Pratt
Dynamic Walking 2017

Mini-Abstract:

- 1) Question to Answer: How to combine natural looking, efficient walking and mathematically precise control.
- 2) Approach: Figure out why mathematically precise controllers tend to have unnatural walking and why natural looking walkers are mathematically imprecise. Then see if we can bridge the gap.
- 3) Answers so far: None. Work in progress. Hope to have something by June.

URL of previous talk:

<http://video.mit.edu/watch/dynamic-walking-2010-jerry-pratt-humanoid-disturbance-recovery-with-limited-available-footholds-6031/>