Jerry Pratt  
Dynamic Walking 2017  

Mini-Abstract:  
1) Question to Answer: How to combine natural looking, efficient walking and mathematically precise control.  
2) Approach: Figure out why mathematically precise controllers tend to have unnatural walking and why natural looking walkers are mathematically imprecise. Then see if we can bridge the gap.  
3) Answers so far: None. Work in progress. Hope to have something by June.  

URL of previous talk:  