

Your TA, Section # and Section time:

Your name:

# Cornell TAM/ENGRD 2030

No calculators, books or notes allowed.

3 Problems, 90 minutes (+ up to 90 minutes overtime)

# Catch-all Makeup Prelim

May 7, 2011

## How to get the highest score?

Please do these things:

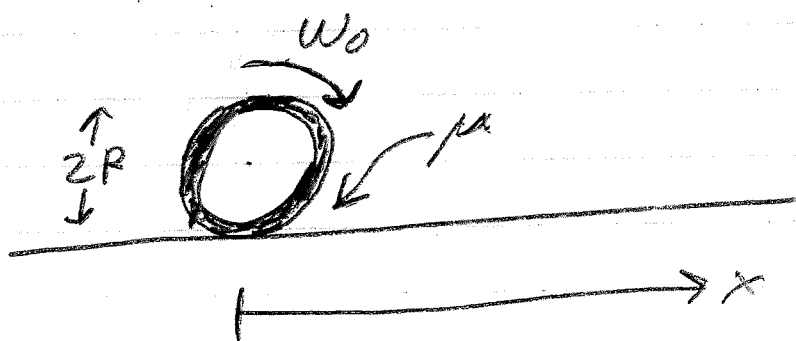
- ↖ • Draw **Free body diagrams** whenever force, moment, linear momentum, or angular momentum balance are used.
- Use correct **vector notation**.
- A+ Be (I) neat, (II) clear and (III) well organized.
- TIDILY REDUCE and **box in** your answers (Don't leave simplifyable algebraic expressions).
- >> Make appropriate Matlab code clear and correct.  
You can use shortcut notation like " $T_7 = 18$ " instead of, say, " $T(7) = 18$ ".  
Small syntax errors will have small penalties.
- ↗ Clearly **define** any needed dimensions ( $\ell, h, d, \dots$ ), coordinates ( $x, y, r, \theta \dots$ ), variables ( $v, m, t, \dots$ ), base vectors ( $\hat{i}, \hat{j}, \hat{e}_r, \hat{e}_\theta, \hat{\lambda}, \hat{n} \dots$ ) and signs ( $\pm$ ) with sketches, equations or words.
- **Justify** your results so a grader can distinguish an informed answer from a guess.
- ☛ If a problem seems *poorly defined*, clearly state any reasonable assumptions (that do not oversimplify the problem).
- ≈ Work for **partial credit** (from 60–100%, depending on the problem)
  - Put your answer is in terms of well defined variables even if you have not substituted in the numerical values.
  - Reduce the problem to a clearly defined set of equations to solve.
  - Provide Matlab code which would generate the desired answer (and explain the nature of the output).
- **Extra sheets.** Put your name on each extra sheet, fold it in, and refer to it at the relevant problem.  
Note the last page is **blank** for your use. Ask for more extra paper if you need it.

Problem 10:        /25

Problem 11:        /25

Problem 12:        /25

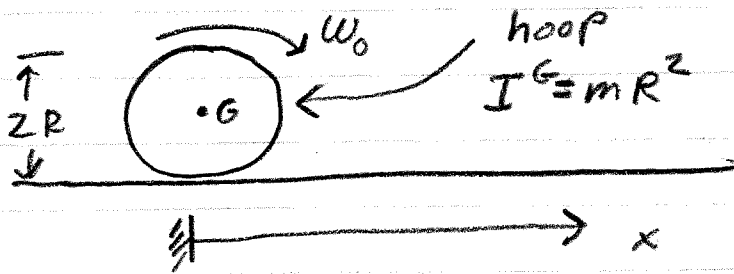
1. A uniform hoop spins and then is dropped onto a horizontal surface. The hoop spins and slides for a while and eventually ends up in pure rolling.



- a) When the cylinder eventually rolls what is its velocity (vel. of C.O.M.)
- b) What, then, is  $\vec{\omega}$ ?
- c) How far does it travel before it enters pure rolling?

# Make-up prob. 1 "Solution"

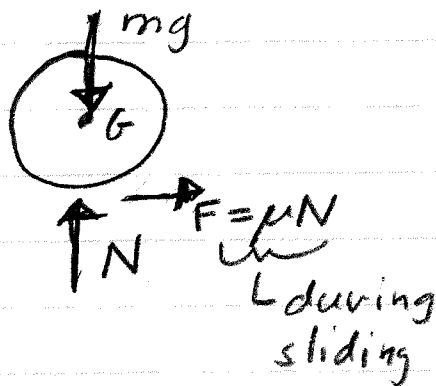
$\hat{j} \uparrow$   
 $\hat{i} \rightarrow$



initially:  
 $\vec{\omega} = -\omega_0 \hat{k}$   
 $\vec{v} = \vec{0}$

Find when & where rolling starts and at what  $v, \omega$ ?

FBD



$$\left\{ \sum \vec{F} = m\vec{a} \right\} \cdot \hat{j} \Rightarrow \boxed{N = mg}$$

$$\Rightarrow \boxed{F = \mu mg}$$

Signs:  $\omega = +$   
 $v_x = +$

$$\underline{AMB/G} \Rightarrow \sum \vec{M}_{/G} = \vec{H}_{/G} \Rightarrow R\mu mg = I_G \dot{\omega} \quad (1)$$

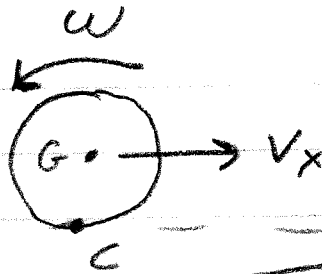
$$\underline{LMB} \cdot \hat{i} \Rightarrow F = ma_x \Rightarrow \mu mg = m \dot{v}_x \quad (2)$$

$$(1) \Rightarrow \omega = -\omega_0 + \frac{R\mu mg}{I_G} t = -\omega_0 + \frac{\mu g}{R} t$$

$$(2) \Rightarrow v_x = \mu g t \quad \Rightarrow \omega = -\omega_0 + \frac{v_x}{R} \quad (3)$$

1, (cont'd)

Rolling:



$$v_c = 0 \Rightarrow v_x + \omega R = 0 \Rightarrow \boxed{\omega = -v_x/R} \quad (4)$$

Sliding turns to rolling when (3) & (4) agree:

$$\Rightarrow \frac{-v_x}{R} = -\omega_0 + \frac{v_x}{R} \Rightarrow \boxed{v_x = \frac{\omega_0 R}{2}} \quad (a)$$

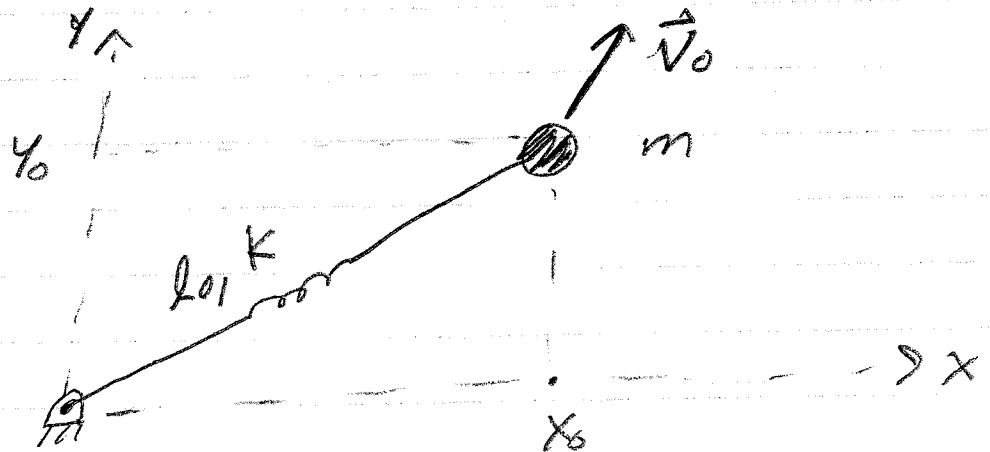
$$\Rightarrow \boxed{\omega = \frac{-\omega_0}{2}} \quad (b)$$

At transition to rolling:

$$v_x = \mu g t = \omega_0 R / 2 \Rightarrow t = \frac{\omega_0 R}{2\mu g}$$

$$x = \cancel{x_0} + \mu g t^2 / 2 = \frac{\mu g}{2} \left( \frac{\omega_0 R}{2\mu g} \right)^2 = \boxed{\frac{\omega_0^2 R^2}{8\mu g}} \quad (c)$$

2) Neglect gravity, 2D.



Given

$$m = 3 \text{ kg}$$

$$l_0 = 2 \text{ m}$$

$$k = 100 \text{ N/m}$$

$$\vec{r}_0 = 5 \text{ m } \hat{i} + 4 \text{ m } \hat{j}$$

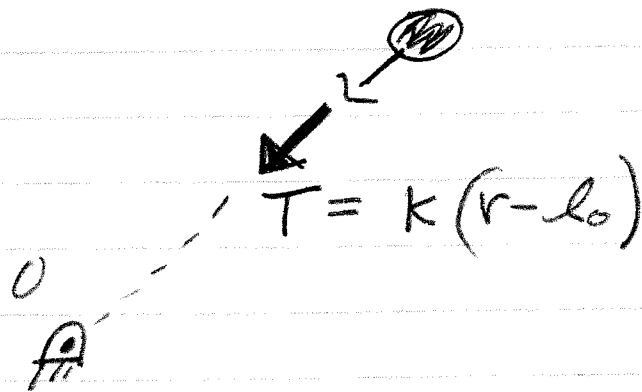
$$\vec{v}_0 = 6 \text{ m/s } \hat{j}$$

Write matlab code to find  $x(t=3s)$ .

2) "Solution"

$$\hat{e}_r = \vec{r}/r$$

FBD



LMB:  $\Sigma \vec{F} = m\vec{a}$

$$T = k(r - l_0) \quad \begin{matrix} \uparrow \\ \uparrow \\ \uparrow \end{matrix} \quad \begin{matrix} -T \hat{e}_r = m \ddot{\vec{r}} \\ \uparrow \\ \uparrow \end{matrix} \quad \begin{matrix} \uparrow \\ \uparrow \end{matrix} \quad \begin{matrix} (\dot{v}_x \hat{i} + \dot{v}_y \hat{j}) \\ \frac{x \hat{i} + y \hat{j}}{\sqrt{x^2 + y^2}} \end{matrix}$$

The diagram shows the force  $T = k(r - l_0)$  acting on the mass. The force vector is  $-T \hat{e}_r$ , which is equal to  $m \ddot{\vec{r}}$ . The position vector is  $\frac{x \hat{i} + y \hat{j}}{\sqrt{x^2 + y^2}}$  and the velocity vector is  $(\dot{v}_x \hat{i} + \dot{v}_y \hat{j})$ .

(Matlab code on next page)  $\rightarrow$

2)(cont'd)

## MATLAB CODE

```
function makeupprob2()
```

```
r0 = [5; 4]; v0 = [0; 6]; z0 = [r0; v0];  
tspan = [0 3];
```

```
[t zarray] = ode45(@myrhs, tspan, z0);
```

```
lastx = zarray(:, 1); % THE ANSWER
```

```
end
```

one  
text  
file

```
function zdot = myrhs(t, z)
```

```
m = 3; L = 2; K = 100;
```

```
r = z(1:2); v = z(3:4); magr = norm(r);
```

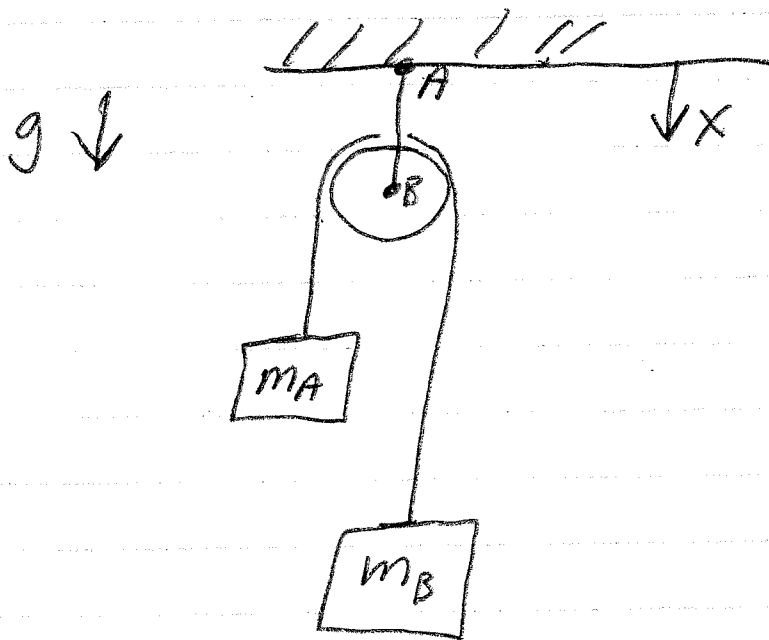
```
rdot = v;
```

```
vdot = -(1/m) * K * (magr - L) * r / magr; % 2 ODEs  
% 2 more ODEs
```

```
zdot = [rdot; vdot];
```

```
end
```

3) In terms of  $m_A$ ,  $m_B$  &  $g$   
find the tension in cable AB.





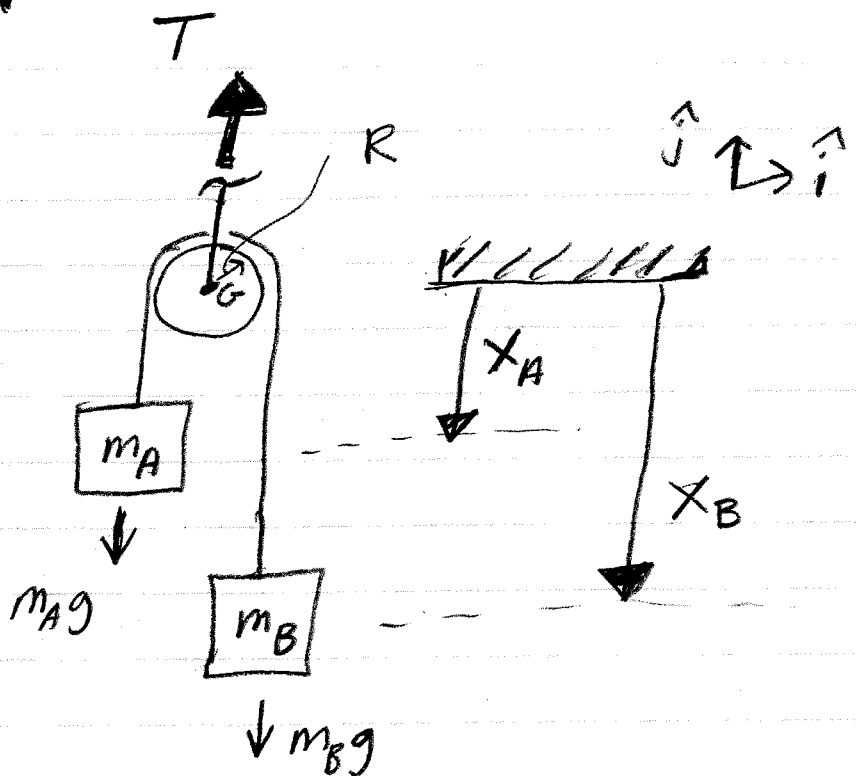
### 3) "Solution"

FBD

Kinematics:

$$\ddot{x}_A = -\ddot{x}_B$$

String length = const



AMB/G:  $\left\{ \sum \vec{M}_{/G} = \vec{H}_{/G} \right\} \cdot \vec{k}$

$$gR(m_A - m_B) = R(m_A \ddot{x}_A - m_B \ddot{x}_B)$$

$$\uparrow \ddot{x}_B = -\ddot{x}_A$$

$$\Rightarrow \ddot{x}_A = \frac{gR(m_A - m_B)}{R(m_A + m_B)} = g \left( \frac{m_A - m_B}{m_A + m_B} \right)$$

$$\Rightarrow \ddot{x}_B = -g \left( \frac{m_A - m_B}{m_A + m_B} \right)$$

LMB:  $\left\{ \sum \vec{F} = \sum m_i \vec{a}_i \right\} \cdot \vec{j}$

$$T - m_A g - m_B g = -m_A \ddot{x}_A - m_B \ddot{x}_B$$

3) cont'd

$$T = (m_A + m_B)g - (m_A - m_B) \frac{m_A - m_B}{m_A + m_B} g$$

$$= \frac{(m_A + m_B)^2 - (m_A - m_B)^2}{m_A + m_B} g$$

$$T_{AB} = \frac{4m_A m_B g}{m_A + m_B}$$

Checks

$$\begin{array}{l} m_A = 0 \Rightarrow T_{AB} = 0 \\ m_B = 0 \Rightarrow T_{AB} = 0 \end{array} \left. \vphantom{\begin{array}{l} m_A = 0 \\ m_B = 0 \end{array}} \right\} \begin{array}{l} \text{free } \checkmark \\ \text{fall} \end{array}$$

$$m = m_A = m_B \Rightarrow T_{AB} = 2mg \quad \text{statics } \checkmark$$