

Systems of ODEs

Section 3.3

M294 SP87 P2#5

$$(15) \quad \dot{\underline{x}} = A\underline{x}, \quad A = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}, \quad \underline{x}(0) = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

a. FIRST LOOK FOR EIGENVALUES, SINCE WE ASSUME A SOLN.

$$\underline{x} = e^{\lambda t} \underline{v}$$

$$0 \underline{x} = A e^{\lambda t} \underline{v}$$

$$A e^{\lambda t} \underline{v} = A e^{\lambda t} \underline{v}$$

$$A \underline{v} = \lambda \underline{v}$$

OR EIGENVALUES FROM

$$\det(A - \lambda I) = 0$$

$$\det \begin{pmatrix} 1-\lambda & 2 \\ 2 & 1-\lambda \end{pmatrix} = 0$$

$$(1-\lambda)^2 - 4 = 0$$

$$(1-\lambda) = \pm 2$$

$$\lambda = 3, -1$$

So:

$$\underline{x}_1 = e^{3t} \underline{v}_1, \quad \underline{x}_2 = e^{-t} \underline{v}_2$$

b. NOW WE FIND THE EIGEN VECTORS

$$\text{SINCE } (A - \lambda I) \underline{x} = 0$$

$$\lambda = 3$$

$$\begin{pmatrix} -2 & 2 \\ 2 & -2 \end{pmatrix} \underline{x} = 0$$

$$\begin{pmatrix} -2 & 2 \\ 2 & -2 \end{pmatrix} \underline{v} = 0$$

TRIVIALY

$$\underline{v}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

DOING THE REDUCTION ONCE FOR $\lambda = -1$

$$\begin{pmatrix} -2 & 2 \\ 2 & -2 \end{pmatrix} \begin{array}{c} | \\ 0 \\ 0 \end{array}$$

$$\rightarrow \lambda = -1$$

$$\begin{pmatrix} -2 & 2 \\ 0 & 0 \end{pmatrix} \begin{array}{c} | \\ 0 \\ 0 \end{array}$$

$$\rightarrow \lambda = 1$$

$$\begin{pmatrix} -1 & 1 \\ 0 & 0 \end{pmatrix} \begin{array}{c} | \\ 0 \\ 0 \end{array}$$

$$\begin{pmatrix} -1 & 1 \\ 0 & 0 \end{pmatrix} \begin{array}{c} | \\ 0 \\ 0 \end{array} \text{ - REDUCE FROM}$$

$$\begin{pmatrix} -1 & 1 \\ 0 & 0 \end{pmatrix} \underline{v} = 0$$

$$v_1 + v_2 = 0$$

$$v_1 = -v_2 = \underline{v}$$

$$\underline{v} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\text{SINCE } \lambda = 1$$

$$\underline{v}_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\underline{v}_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\lambda = -1$$

$$\begin{pmatrix} 1-(-1) & 2 \\ 2 & 1-(-1) \end{pmatrix} \underline{x} = 0$$

$$\begin{pmatrix} 2 & 2 \\ 2 & 2 \end{pmatrix} \underline{x} = 0$$

$$\underline{v}_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix} \text{ OR } \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

FOR CONS IN THE REDUCTION AGAIN; OR THE SAME RESULT

c. So NOW

$$\underline{x} = c_1 e^{3t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + c_2 e^{-t} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\underline{x}(0) = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \text{ so}$$

$$\begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} c_1 e^0 + c_2 e^0 \\ c_1 e^0 - c_2 e^0 \end{pmatrix} = \begin{pmatrix} c_1 + c_2 \\ c_1 - c_2 \end{pmatrix}$$

THIS IS IDENTICAL TO YOUR HW!

$$c_1 = 2, c_2 = -1 \text{ [CAN ALSO REVERSE]}$$

$$\underline{x}(2) = \begin{pmatrix} 2e^6 - e^{-2} \\ 2e^6 + e^{-2} \end{pmatrix}$$

M294 SP87 P3 #2

(16) $\dot{x} = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} x$ Writing out components, $\begin{cases} \dot{x}_1 = 2x_1 \\ \dot{x}_2 = 2x_2 \end{cases}$

So $\begin{cases} x_1(t) = c_1 e^{2t} \\ x_2(t) = c_2 e^{2t} \end{cases}$ or $x(t) = c_1 e^{2t} \begin{bmatrix} 1 \\ 0 \end{bmatrix} + c_2 e^{2t} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

Alternate solution:

Find eigenvalues and eigenvectors $\det \begin{bmatrix} 2-\lambda & 0 \\ 0 & 2-\lambda \end{bmatrix} = (2-\lambda)^2$
 so $\lambda = 2, 2$ and $\begin{bmatrix} 2-\lambda & 0 \\ 0 & 2-\lambda \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = 0$ has

two lin. indep. solns, say $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$, whence

$$x(t) = c_1 e^{2t} \begin{bmatrix} 1 \\ 0 \end{bmatrix} + c_2 e^{2t} \begin{bmatrix} 0 \\ 1 \end{bmatrix}.$$

M294 SP87 F #1

(17) $d) 0 = \det[A - \lambda I] = \det \begin{bmatrix} 1-\lambda & 2 \\ 2 & 1-\lambda \end{bmatrix} = (1-\lambda)^2 - 4 = \lambda^2 - 2\lambda - 3 = (\lambda+1)(\lambda-3)$
 $\Rightarrow \lambda = -1, 3$. Say $\lambda = -1 \Rightarrow [A - \lambda I]x = 0 \Rightarrow \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
 $\Rightarrow x = c \begin{bmatrix} -1 \\ 1 \end{bmatrix} \Rightarrow \lambda = -1$ has e-vector $x = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$

M294 SP88 P2 #7

(25)
$$z(t) = \begin{bmatrix} e^{6t} \\ e^{6t} \\ e^{6t} \end{bmatrix}$$

$$\dot{z}(t) = \begin{bmatrix} 6e^{6t} \\ 6e^{6t} \\ 6e^{6t} \end{bmatrix} = 6e^{6t} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = e^{6t} \begin{bmatrix} 6 \\ 6 \\ 6 \end{bmatrix}$$

 compare $\lambda \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ 6 \\ 6 \end{bmatrix}$
 $\therefore \lambda = 6$

M294 FA90 P2 #3

(42)

n	t	x	y
0	1	1	2
1	1.25	3	8

$$x_n = x_{n-1} + h(5x_{n-1}^2 + t_{n-1}y_{n-1} + t_{n-1}^3)$$

$$y_n = y_{n-1} + h(13x_{n-1}y_{n-1} - 2t_{n-1})$$

$$x_1 = 1 + 0.25(5+2+1) = \underline{3}$$

$$y_1 = 2 + 0.25(13(2) - 2) = \underline{8}$$

b) Separate: $\int \frac{dy}{y^2} = 2 \int \sin x dx$, $-\frac{1}{y} = -2\cos x + c$, $\frac{1}{y} = 2\cos x + c$

$$\Rightarrow y = \frac{1}{2\cos x + c}, \quad y(0) = 1 \Rightarrow 1 = \frac{1}{2(1) + c}, \quad c = -1 \Rightarrow y = \frac{1}{2\cos x - 1}$$

(70) M294 FA92 F #3

let $A = \begin{pmatrix} 1 & 1 \\ 4 & 1 \end{pmatrix}$ then $\det(A - \lambda I) = \lambda^2 - 2\lambda - 3 = (\lambda + 1)(\lambda - 3)$

and $\begin{pmatrix} 1 & 1 \\ 4 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ -2 \end{pmatrix} = -1 \begin{pmatrix} 1 \\ -2 \end{pmatrix}$, $\begin{pmatrix} 1 & 1 \\ 4 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = 3 \begin{pmatrix} 1 \\ 2 \end{pmatrix}$

so $x_h = c_1 \begin{pmatrix} 1 \\ -2 \end{pmatrix} e^{-t} + c_2 \begin{pmatrix} 1 \\ 2 \end{pmatrix} e^{3t}$ solves $Ax_h = x_h'$

Next assume $x_p = \text{constant} \begin{pmatrix} a \\ b \end{pmatrix}$ then $0 = A \begin{pmatrix} a \\ b \end{pmatrix} + \begin{pmatrix} 3 \\ 0 \end{pmatrix}$ forces

$$\begin{cases} a + b = -3 \\ 4a + b = 0 \end{cases}$$

so $a = 1$
 $b = -4$ so

$$x = \begin{pmatrix} 1 \\ -4 \end{pmatrix} + c_1 \begin{pmatrix} 1 \\ -2 \end{pmatrix} e^{-t} + c_2 \begin{pmatrix} 1 \\ 2 \end{pmatrix} e^{3t}$$

(71) M294 FA92 F #6

gen soln $y = c_1 \cos \sqrt{\lambda} x + c_2 \sin \sqrt{\lambda} x$ (if $\lambda > 0$)

$$y'(0) = c_2 \sqrt{\lambda} = 0 \Rightarrow c_2 = 0$$

$$y(1) = c_1 \cos \sqrt{\lambda} \text{ will be } 0 \text{ if } \sqrt{\lambda} = \dots$$

$$y = c_1 \cos\left(\frac{(2n+1)\pi}{2} x\right) \quad n = 0, 1, 2, 3, \dots$$

$$\lambda = \left(\frac{(2n+1)\pi}{2}\right)^2$$

one more case: $\lambda = 0$ gen soln $y = mx + b$ } so

$$y'(0) = m = 0$$

$$y(1) = b = 0$$

72 M294 FA92 F #10

$x(0) = \begin{pmatrix} 2 \\ -4 \\ 0 \end{pmatrix}$ is an eigenvector by problem (3),
 $\lambda = -1$
 $\sqrt{\lambda} = \pm i$

So $x(t) = \begin{pmatrix} 2 \\ -4 \\ 0 \end{pmatrix} (c_1 \cos t + c_2 \sin t)$

then I, C_i give $c_1 = 1; c_2 = 0$

M294 FA93 P3 #2

$$\underline{x}' = \begin{pmatrix} 0 & \omega \\ -\omega & 0 \end{pmatrix} \underline{x}$$

$$102.) a.) \begin{pmatrix} A & -\lambda I \end{pmatrix} \underline{x} = \begin{pmatrix} -\lambda & \omega \\ -\omega & -\lambda \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$e \text{ values } \lambda^2 + \omega^2 = 0 \Rightarrow \underline{\lambda_1 = i\omega}$$

$$\lambda_1 = i\omega$$

$$\begin{pmatrix} -i\omega & \omega \\ -\omega & -i\omega \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \Rightarrow -i\omega x_1 + \omega x_2 = 0 \Rightarrow x_1 = -i x_2$$

$$\lambda_2 = -i\omega$$

$$\begin{pmatrix} i\omega & \omega \\ -\omega & i\omega \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \Rightarrow i\omega x_1 - \omega x_2 = 0 \Rightarrow x_1 = i x_2$$

$$b.) \underline{x}^{(1)} = \begin{pmatrix} -i \\ 1 \end{pmatrix} e^{i\omega t}$$

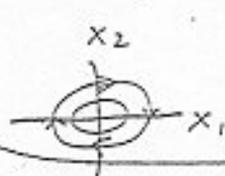
$$\underline{x}^{(2)} = C_2 \begin{pmatrix} i \\ 1 \end{pmatrix} e^{-i\omega t}$$

$$\underline{x}^{(1)} = \begin{pmatrix} -i \\ 1 \end{pmatrix} (\cos \omega t + i \sin \omega t) = \begin{pmatrix} \sin \omega t \\ \cos \omega t \end{pmatrix} + i \begin{pmatrix} -\cos \omega t \\ \sin \omega t \end{pmatrix}$$

So the real valued solution is

$$\underline{x} = C_1 \begin{pmatrix} \sin \omega t \\ \cos \omega t \end{pmatrix} + C_2 \begin{pmatrix} -\cos \omega t \\ \sin \omega t \end{pmatrix}$$

$$c.) \text{ Critical Points at } \begin{cases} x_1' = \omega x_2 = 0 \\ x_2' = -\omega x_1 = 0 \end{cases} \Rightarrow \begin{cases} x_2 = 0 \\ x_1 = 0 \end{cases}$$



$$\begin{matrix} @ x_2 = 1 & x_1' > 0 & \therefore \rightarrow \\ x_1 = 1 & x_2' < 0 & \downarrow \end{matrix}$$

Solutions are stable \rightarrow know direction of spin

$$d.) \underline{x}' = \begin{pmatrix} 0 & \omega \\ -\omega & 0 \end{pmatrix} \underline{x} = \begin{pmatrix} x_1' \\ x_2' \end{pmatrix} = \begin{pmatrix} \omega x_2 \\ -\omega x_1 \end{pmatrix}$$

$$x_1' = \omega x_2$$

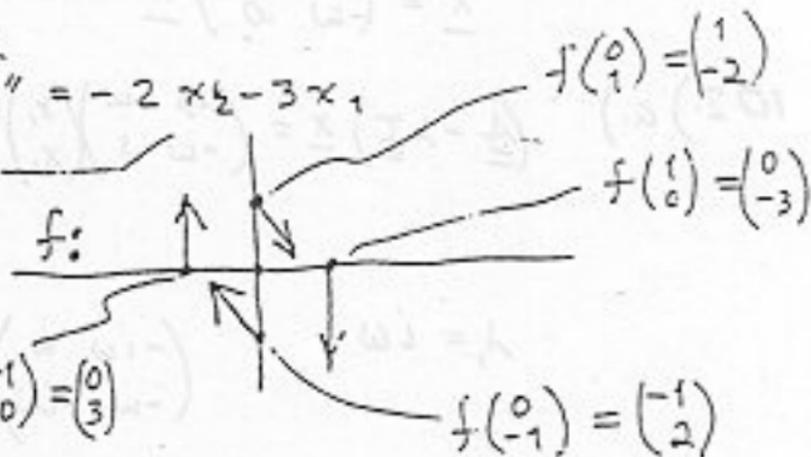
$$x_2' = \omega x_1' = \omega(-\omega x_1) = -\omega^2 x_1$$

$$\underline{x_1'' + \omega^2 x_1 = 0}$$

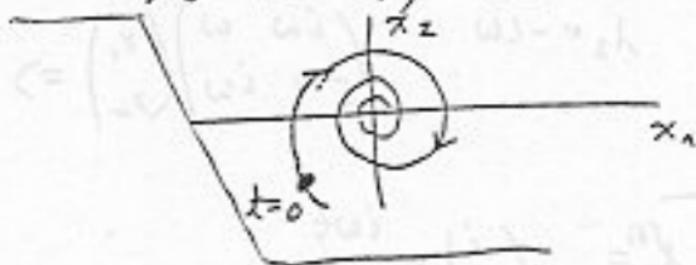
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- b) let $x_1 = y$, $x_2 = y'$, then $x'_1 = x_2$
 $x'_2 = y'' = -2x_2 - 3x_1$

So $x' = \begin{pmatrix} 0 & 1 \\ -3 & -2 \end{pmatrix} x = f(x)$



- c) for the initial conditions in (a),
 $x(0) = \begin{pmatrix} -1 \\ -1 \end{pmatrix}$ so $x(t)$ starts here, follows f , and $\rightarrow 0$ as $t \rightarrow \infty$

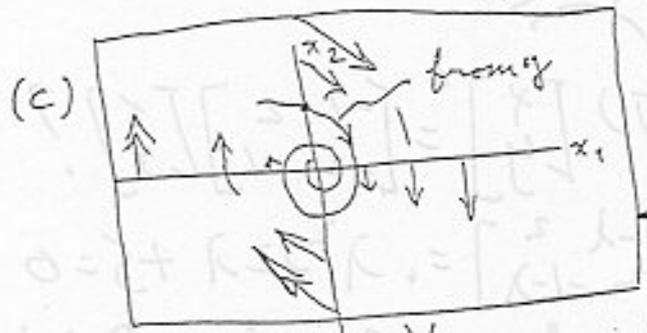


(a) $y = e^{-t} \sin t$
 $y' = -y + e^{-t} \cos t$ $y'' = -y' - e^{-t} \cos t - y = -y' - (y' + y)$
 $y'' + 2y' + 2y = 0$

(b) let $x_1 = y$, $x_2 = y'$ then $\begin{cases} x_1' = x_2 \\ x_2' = -2x_1 - 2x_2 \end{cases}$

or $x' = \begin{pmatrix} 0 & 1 \\ -2 & -2 \end{pmatrix} x$

$\det(A - \lambda) = \lambda^2 + 2\lambda + 2$ $\lambda = -1 \pm i$
 $A - (-1+i) = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$ $A \begin{pmatrix} -1 \\ 1-i \end{pmatrix} = (-1+i) \begin{pmatrix} -1 \\ 1-i \end{pmatrix}$



$y(0) = 0$
 $y'(0) = 1$

← plotting several $A \begin{pmatrix} x_1 \\ 0 \end{pmatrix}$ and $A \begin{pmatrix} 0 \\ x_2 \end{pmatrix}$

(d) let $x^{(1)} = \begin{pmatrix} -1 \\ 1-i \end{pmatrix} e^{(-1+i)t} = e^{-t} \begin{pmatrix} -(\cos t + i \sin t) \\ \cos t + i \sin t - i \cos t + \sin t \end{pmatrix}$

then $\text{Re } x^{(1)} = e^{-t} \begin{pmatrix} -\cos t \\ \cos t + \sin t \end{pmatrix}$ and $\text{Im } x^{(1)} = e^{-t} \begin{pmatrix} \sin t \\ \sin t - \cos t \end{pmatrix}$

are solns $x(t) = c_1 e^{-t} \begin{pmatrix} -\cos t \\ \cos t + \sin t \end{pmatrix} + c_2 e^{-t} \begin{pmatrix} \sin t \\ \sin t - \cos t \end{pmatrix}$

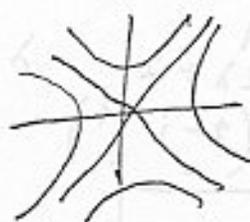
$x(0) = c_1 \begin{pmatrix} -1 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} 0 \\ -1 \end{pmatrix} \stackrel{\text{want}}{=} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ so $c_1 = 1$
 $c_2 = 2$

$x = -1 e^{-t} \begin{pmatrix} -\cos t \\ \cos t + \sin t \end{pmatrix} - 2 e^{-t} \begin{pmatrix} \sin t \\ \sin t - \cos t \end{pmatrix}$

(a) Phase portrait of (i) $\begin{bmatrix} x \\ y \end{bmatrix}' = \begin{bmatrix} -1 & 2 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = ?$

Eigenvalues: $\det \begin{bmatrix} -1-\lambda & 2 \\ 2 & -1-\lambda \end{bmatrix} = \lambda^2 + 2\lambda - 3 = 0, (\lambda+3)(\lambda-1) = 0$

$\lambda = 1, \lambda = -3$. 2 Real, different signs.
"Saddle Point"



must be γ

(b) Phase portrait of (ii) $\begin{bmatrix} x \\ y \end{bmatrix}' = \begin{bmatrix} -1 & 2 \\ -2 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = ?$

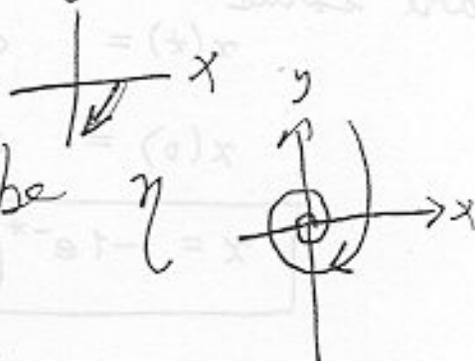
Eigenvalues: $\det \begin{bmatrix} -1-\lambda & 2 \\ -2 & -1-\lambda \end{bmatrix} = \lambda^2 + 2\lambda + 5 = 0$

$\lambda = -1 \pm \frac{1}{2}\sqrt{4-20} = -1 \pm 2i$. Complex. Rotation.

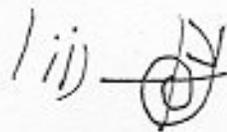
Non-zero real part. Spiral. $\text{Re } \lambda < 0$ inward spiral.

Which orientation of spiral? If $x=1, y=0$

Then $x' = -1, y' = -2$



Check Chart. It's gotta be η



Need Eigenvectors for.

$$(A-I)\xi = \begin{bmatrix} -2 & 2 \\ 2 & -2 \end{bmatrix} \xi = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \left\{ \begin{array}{l} \xi_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \\ \xi_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix} \end{array} \right.$$

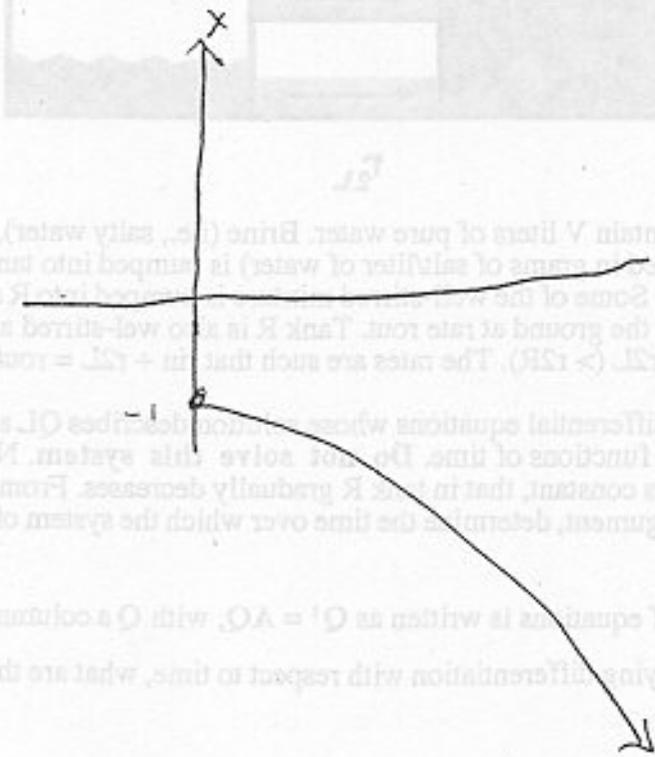
(i) Not all trajectories go towards one. (ii) all go to (0)

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d) general solution = $Ae^t \begin{bmatrix} 1 \\ 1 \end{bmatrix} + Be^{-3t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$.

$$\begin{bmatrix} x \\ y \end{bmatrix} = -\frac{1}{2} e^t \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \frac{1}{2} e^{-3t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

e) $x(t) = -\frac{1}{2} e^t - \frac{1}{2} e^{-3t}$

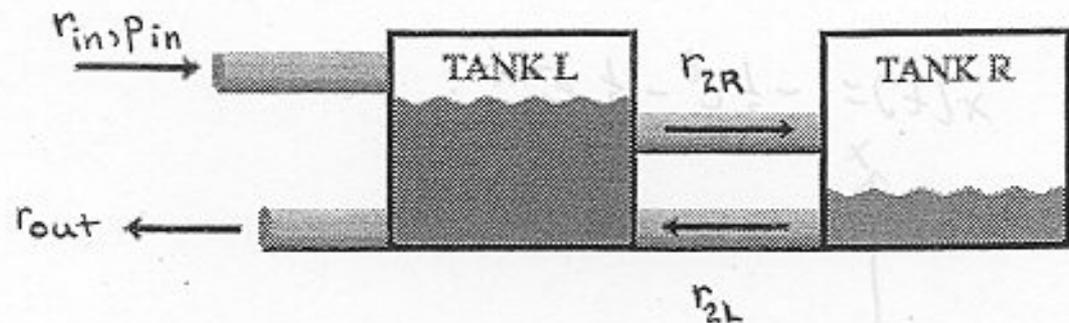


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Solve $x' = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} x$, $x(0) = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}$.

Sketch the solution curve given parametrically by $x_1(t)$, $x_2(t)$, $x_3(t)$.

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Initially tanks L and R each contain V liters of pure water. Brine (i.e., salty water), with a concentration p_{in} (e.g., measured in grams of salt/liter of water) is pumped into tank L at the rate of r_{in} (measured in liters/minute). Some of the well-stirred mixture is pumped into R at the rate r_{2R} , while some more is pumped out onto the ground at rate r_{out} . Tank R is also well-stirred and its contents are fed back into tank L at the rate r_{2L} ($> r_{2R}$). The rates are such that $r_{in} + r_{2L} = r_{out} + r_{2R}$.

(20 pts.) Set up the system of differential equations whose solution describes Q_L and Q_R , the amounts of salt in the tanks, as functions of time. **Do not solve this system.** Note that, while the amount of liquid in tank L stays constant, that in tank R gradually decreases. From both a mathematical and a physical argument, determine the time over which the system of differential equations is valid.

(10 pts.) If the above system of equations is written as $Q' = AQ$, with Q a column vector (containing elements Q_L and Q_R) and $'$ signifying differentiation with respect to time, what are the elements of the 2×2 matrix A ?

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Consider the following systems of first order differential equations

(i)
$$\begin{aligned}x' &= -x + 2y \\y' &= 2x - y\end{aligned}$$

(ii)
$$\begin{aligned}x' &= -x + 2y \\y' &= -2x - y\end{aligned}$$

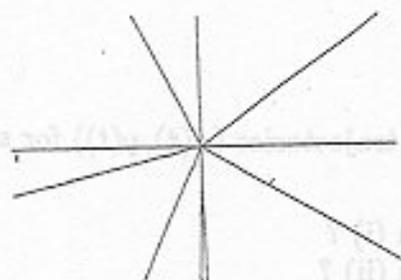
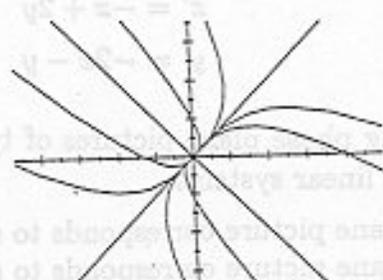
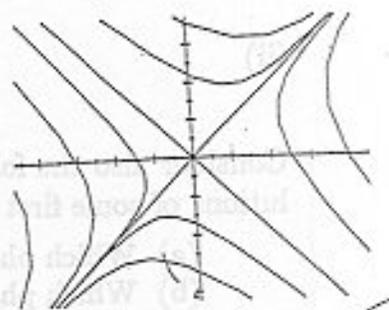
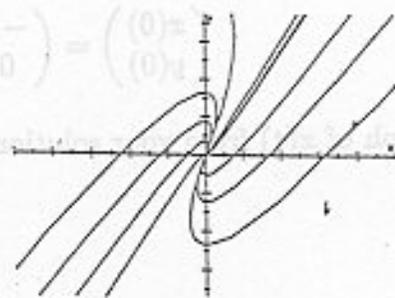
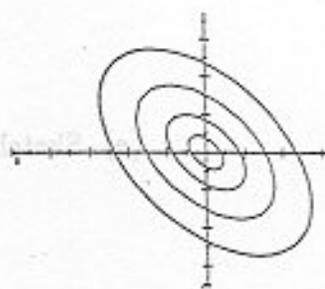
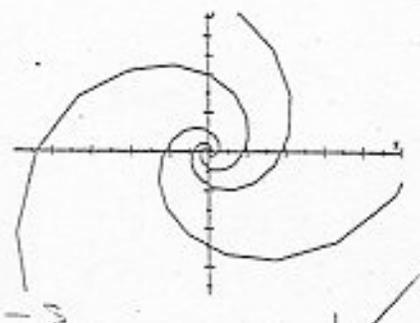
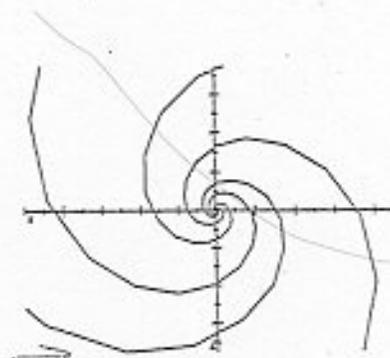
Consider also the following phase plane pictures of typical trajectories $(x(t), y(t))$ for solutions of some first order linear systems.

- Which phase plane picture corresponds to system (i) ?
- Which phase plane picture corresponds to system (ii) ?
- Sketch your chosen pictures in your exam book, placing "arrowheads" on the trajectories to indicate the direction in which the solutions move (along the trajectories) as $t \rightarrow \infty$. For each system, state whether all solutions approach one particular solution as $t \rightarrow \infty$.
- Give the solution to system (i) satisfying the initial condition

$$\begin{pmatrix} x(0) \\ y(0) \end{pmatrix} = \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

- Sketch the graph of $x(t)$ from your solution to (d) (in the (t, x) -plane).

First-Order Menagerie

 α  β  γ  δ  ϵ  ζ  η  θ

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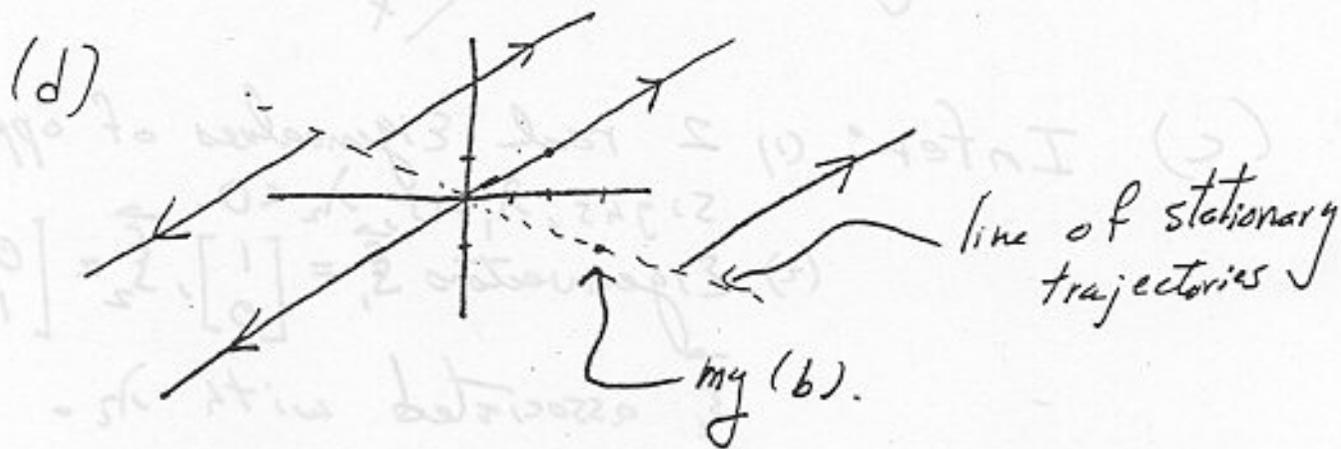
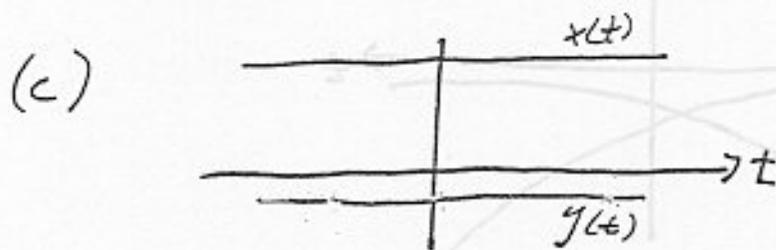
$$(a) \det \begin{bmatrix} 2-\lambda & 6 \\ 1 & 3-\lambda \end{bmatrix} = \lambda^2 - 5\lambda = 0, \lambda = 5, \lambda = 0.$$

$$\vec{\xi}_5: \begin{bmatrix} -3 & 6 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} \xi_1 \\ \xi_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \xi_1 - 2\xi_2 = 0 \quad \vec{\xi}_5 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}.$$

$$\vec{\xi}_0: \begin{bmatrix} 2 & 6 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} \xi_1 \\ \xi_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \xi_1 + 3\xi_2 = 0 \quad \vec{\xi}_0 = \begin{bmatrix} 3 \\ -1 \end{bmatrix}.$$

$$\text{Solutions: } e^{5t} \begin{bmatrix} 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ -1 \end{bmatrix}$$

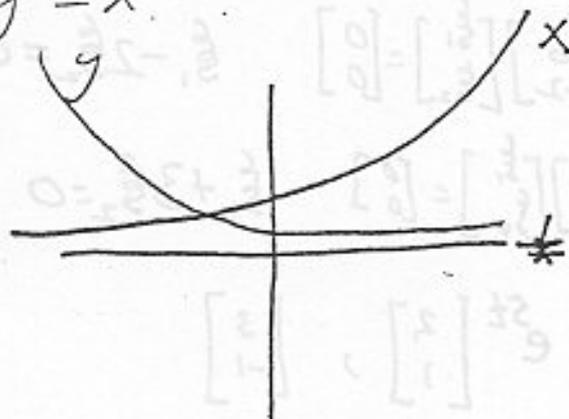
$$(b) \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \end{bmatrix}$$



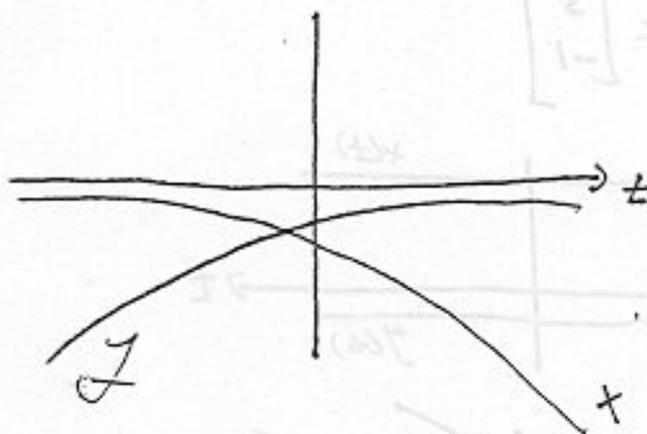
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$$y' - 3y = x$$

(a)



(b)



- (c) Infer: (1) 2 real Eigenvalues of opposite signs, $\lambda_1 > 0$, $\lambda_2 < 0$.
 (2) Eigenvectors $\vec{\xi}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, $\vec{\xi}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$
 $\vec{\xi}_1$ associated with λ_2 .

(d) $\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$

4. There are no oscillatory solutions.

93 M294 FA95 P2 #3

let $x_1 = y$, $x_2 = y'$. then $x_2' = y'' = -3y' - y - y^3 = -3x_2$

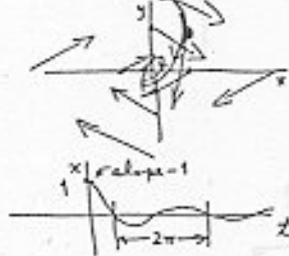
$$\text{for } \begin{cases} x_1' = x_2 \\ x_2' = -3x_2 - x_1 - x_1^3 \end{cases} \text{ other correct answers are possible}$$

94 M294 FA95 P3 #1

$$e^{(2+i)t} \begin{pmatrix} 1+i \\ i \end{pmatrix} = e^{-2t} \begin{pmatrix} \cos t + i \sin t + i \cos t - \sin t \\ i \cos t - \sin t \end{pmatrix}$$

$$= e^{-2t} \begin{pmatrix} \cos t - \sin t \\ -\sin t \end{pmatrix} + i e^{-2t} \begin{pmatrix} \cos t + \sin t \\ \cos t \end{pmatrix}$$

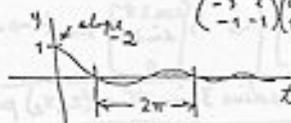
\therefore gen. soln $\begin{pmatrix} x \\ y \end{pmatrix} = c_1 e^{-2t} \begin{pmatrix} \cos t - \sin t \\ -\sin t \end{pmatrix} + c_2 e^{-2t} \begin{pmatrix} \cos t + \sin t \\ \cos t \end{pmatrix}$ inward spiral



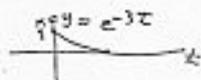
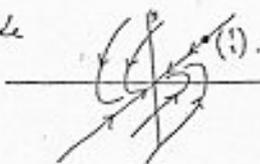
$$\begin{pmatrix} x'(0) \\ y'(0) \end{pmatrix} = \begin{pmatrix} -3 & 2 \\ -1 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ -2 \end{pmatrix}$$

plot other field vectors: $\begin{pmatrix} -3 & 2 \\ -1 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -3 \\ -1 \end{pmatrix}$

$$\begin{pmatrix} -3 & 2 \\ -1 & -1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

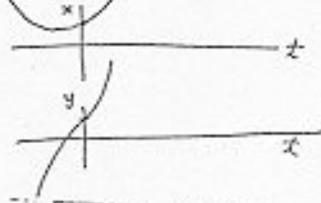
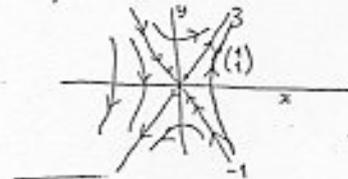


b) This is a node



general soln is of the form $(u \pm v)e^{-3t}$ where $v = c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ and $\left(\begin{pmatrix} 1 & -4 \\ a & -7 \end{pmatrix} - (-3)I \right) u = v$.

(c) gen soln is $c_1 e^{-t} \begin{pmatrix} -1 \\ 2 \end{pmatrix} + c_2 e^{3t} \begin{pmatrix} 1 \\ 2 \end{pmatrix}$. Since one eigenvalue is positive and one is negative, this is a saddle



95 M294 FA95 F #3

$$A = \begin{bmatrix} 0 & -2 & 0 \\ 2 & 0 & 0 \\ 0 & 0 & -5 \end{bmatrix} \quad \det(A - \lambda I) = (-5 - \lambda) \det \begin{pmatrix} \lambda & -2 \\ 2 & -\lambda \end{pmatrix}$$

$$= (-5 - \lambda)(\lambda^2 + 2)$$

$$= -(\lambda + 5)(\lambda + 2i)(\lambda - 2i)$$

eigenvalues: $(A - 2iI)u = \begin{bmatrix} -2i & -2 & 0 \\ 2 & -2i & 0 \\ 0 & 0 & -5 - 2i \end{bmatrix} u = 0$ if $u_3 = 0$ and $u_2 = -iu_1$

take $u = \begin{bmatrix} 1 \\ -i \\ 0 \end{bmatrix}$

then since A is real, $A \begin{bmatrix} 1 \\ i \\ 0 \end{bmatrix} = -2i \begin{bmatrix} 1 \\ i \\ 0 \end{bmatrix}$ call it v

$(A - 5I)w = \begin{bmatrix} -5 & -2 & 0 \\ 2 & -5 & 0 \\ 0 & 0 & 0 \end{bmatrix} w$ so take $w = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ then $Aw = -5w$

(a) gen soln to $x' = Ax$ is $x(t) = c_1 e^{2it} \begin{bmatrix} 1 \\ -i \\ 0 \end{bmatrix} + c_2 e^{-2it} \begin{bmatrix} 1 \\ i \\ 0 \end{bmatrix} + c_3 e^{-5t} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$
or, using real solutions,

$$x(t) = a_1 \begin{bmatrix} \cos 2t \\ \sin 2t \\ 0 \end{bmatrix} + a_2 \begin{bmatrix} \sin 2t \\ -\cos 2t \\ 0 \end{bmatrix} + a_3 e^{-5t} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \begin{bmatrix} \cos 2t + i \sin 2t \\ \sin 2t - i \cos 2t \\ 0 \end{bmatrix}$$

(b) $x(0) = a_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + a_2 \begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix} + a_3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix}$ if $a_1 = 3$
 $a_2 = 0$
 $a_3 = 1$

$$x(t) = 3 \begin{bmatrix} \cos 2t \\ \sin 2t \\ 0 \end{bmatrix} + e^{-5t} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \sim 3 \begin{bmatrix} \cos 2t \\ \sin 2t \\ 0 \end{bmatrix} \text{ as } t \rightarrow \infty \text{ so this}$$

curve approaches a circle of radius 3 in the (x_1, x_2) plane

96 M294 SP96 P3 #1

$$\text{Let } A = \begin{bmatrix} -1 & 2 \\ -2 & -1 \end{bmatrix}.$$

Using $\lambda = -1 + 2i$, $(A - \lambda I)v = \begin{bmatrix} -2i & 2 \\ -2 & -2i \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$ is 0 if $2v_2 = 2iv_1$. So take $v = \begin{bmatrix} 1 \\ i \end{bmatrix}$. Then $A \begin{bmatrix} 1 \\ i \end{bmatrix} = (-1 + 2i) \begin{bmatrix} 1 \\ i \end{bmatrix}$

and

$$ve^{\lambda t} = \begin{bmatrix} 1 \\ i \end{bmatrix} e^{(-1+2i)t} = e^{-t} \begin{bmatrix} \cos(2t) \\ -\sin(2t) \end{bmatrix} + i e^{-t} \begin{bmatrix} \sin(2t) \\ \cos(2t) \end{bmatrix}$$

So gen. soln is

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 e^{-t} \begin{bmatrix} \cos(2t) \\ -\sin(2t) \end{bmatrix} + c_2 e^{-t} \begin{bmatrix} \sin(2t) \\ \cos(2t) \end{bmatrix}$$

This an inward spiral; to see which way it goes try the point $\begin{bmatrix} 4 \\ 5 \end{bmatrix}$ say, where $A \begin{bmatrix} 4 \\ 5 \end{bmatrix} = \begin{bmatrix} 6 \\ -13 \end{bmatrix}$

so it is clockwise.

$$\begin{bmatrix} x(0) \\ y(0) \end{bmatrix} = \begin{bmatrix} 4 \\ 5 \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix} \text{ so } c_1 = 4 \\ c_2 = 5$$

critical point
is $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = 4e^{-t} \begin{bmatrix} \cos(2t) \\ -\sin(2t) \end{bmatrix} + 5e^{-t} \begin{bmatrix} \sin(2t) \\ \cos(2t) \end{bmatrix}$$

M294 FA96 P2 #3

98) Solution By Hand Write $z = \begin{bmatrix} x \\ y \end{bmatrix}$ then $z' = Az$, $A = \begin{bmatrix} 3 & 4 \\ -4 & 3 \end{bmatrix}$

let $(A - \lambda I) = (3 - \lambda)^2 + 4^2$ is 0 if $3 - \lambda = \pm 4i$ so $\lambda = 3 \pm 4i$

for $\lambda = 3 + 4i$: $(A - \lambda I)v = \begin{bmatrix} -4i & 4 \\ -4 & 4i \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$ is 0 if $-4iv_1 + 4v_2 = 0$
 $v_2 = iv_1$

set $v = \begin{bmatrix} 1 \\ i \end{bmatrix}$ check: $\begin{bmatrix} 3 & 4 \\ -4 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ i \end{bmatrix} \neq (3 + 4i) \begin{bmatrix} 1 \\ i \end{bmatrix}$ ✓

for $\lambda = 3 - 4i$: replace i by $-i$ and find

$$\begin{bmatrix} 3 & 4 \\ -4 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ -i \end{bmatrix} = (3 - 4i) \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

Then

OR

$$e^{(3+4i)t} \begin{bmatrix} 1 \\ i \end{bmatrix} = e^{3t} \begin{bmatrix} \cos 4t + i \sin 4t \\ i \cos 4t - \sin 4t \end{bmatrix} \quad z(t) = a_1 e^{(3+4i)t} \begin{bmatrix} 1 \\ i \end{bmatrix} + a_2 e^{(3-4i)t} \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

So $z(t) = e^{3t} \left(c_1 \begin{bmatrix} \cos 4t \\ -\sin 4t \end{bmatrix} + c_2 \begin{bmatrix} \sin 4t \\ \cos 4t \end{bmatrix} \right)$

$$z(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

$$z(t) = e^{3t} \begin{bmatrix} \cos 4t \\ -\sin 4t \end{bmatrix}$$

$$y(3) = -e^9 \sin(12)$$

$$z(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} a_1 + a_2 \\ ia_1 - ia_2 \end{bmatrix} \rightarrow a_1 = 0$$

$$\therefore a_1 = a_2 = \frac{1}{2}$$

$$z(t) = \frac{1}{2} e^{(3+4i)t} \begin{bmatrix} 1 \\ i \end{bmatrix} + \frac{1}{2} e^{(3-4i)t} \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

$$y(3) = \frac{1}{2} e^{9+12i} (i) + \frac{1}{2} e^{9-12i} (-i)$$

check this if you have time

these are the same

3) Solution by MATLAB

rhs.m $\left\{ \begin{array}{l} \text{function } zdot = \text{rhs}(z) \\ zdot(1) = 3*z(1) + 4*z(2); \\ zdot(2) = -4*z(1) + 3*z(2); \\ \% z(1) \text{ means } x, z(2) \text{ means } y \end{array} \right.$

$[t, z] = \text{ode23}('rhs', 0, 3, [1, 0]);$ % z is now a list of vectors
 $z(\text{length}(z))(2)$ % and you want the y coordinate of the % last one.

99 M294 FA96 P3 #1

$$\underline{x}' = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \underline{x}$$

or

$$\begin{pmatrix} x_1' \\ x_2' \end{pmatrix} = \begin{pmatrix} -x_2 \\ x_1 \end{pmatrix}$$

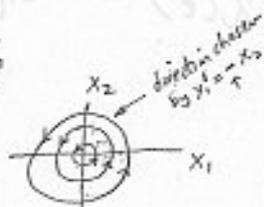
$$\therefore x_1' = -x_2 \text{ and } x_2' = x_1$$

$$\therefore x_1'' + x_1 = 0$$

$$\text{Eigenvalues } \det \begin{pmatrix} 0-\lambda & -1 \\ 1 & 0-\lambda \end{pmatrix} = \lambda^2 + 1 = 0 \Rightarrow \lambda = \pm i$$

Critical point at $x_2 = 0$
 $x_1 = 0$ i.e., origin

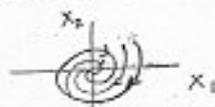
Point is a center & is stable.



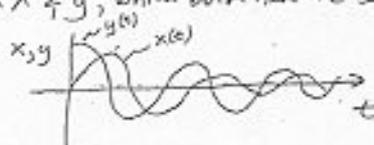
$$\text{Eigenvalues } \det \begin{pmatrix} \epsilon-\lambda & -1 \\ 1 & \epsilon-\lambda \end{pmatrix} = (\epsilon-\lambda)^2 + 1 = 0 \Rightarrow \epsilon-\lambda = \pm i$$

$$\therefore \lambda = \epsilon \pm i$$

Origin is still critical point, but now a spiral point. It will be stable if $\epsilon < 0$, unstable if $\epsilon > 0$.



These represent decaying oscillations in both x & y , which both have the same amplitude and period. y leads x by 90° ($\frac{1}{2}$ period) in phase.



100 M293 FA96 P3 #4

$$(a) \left. \begin{matrix} x(5-y) = 0 \\ y(5-x) = 0 \end{matrix} \right\} \text{ give } \boxed{(x, y) = (0, 0) \text{ or } (x, y) = (5, 5)}$$

only THE SECOND graph has these critical points, and they are BOTH UNSTABLE because in both cases there are solutions trying to get away