

## 2.4 Coordinates

**MATH 294 SPRING 1987 PRELIM 3 # 9**

**2.4.1** For problems (a) - (c) use the bases  $B$  and  $B'$  below:

$$B = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\} \text{ and } B' = \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}.$$

- Given that  $[\vec{v}]_B = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$  what is  $[\vec{v}]_{B'}$ ?
- Using the standard relation between  $\mathfrak{R}^2$  and points on the plane make a sketch with the point  $\vec{v}$  clearly marked. Also mark the point  $\vec{w}$ , where  $[\vec{w}]_B = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$ .
- Draw the line defined by the points  $\vec{v}$  and  $\vec{w}$ . Do the points on this line represent a subspace of  $\mathfrak{R}^2$ ?

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**2.4.2** A general vector  $\vec{v}$  in  $\mathfrak{R}^2$  is  $\vec{v} = b_1\vec{v}_1 + b_2\vec{v}_2 = b'_1\vec{v}'_1 + b'_2\vec{v}'_2$ , where

$$\vec{v}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \vec{v}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \vec{v}'_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \vec{v}'_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}.$$

Find a matrix  ${}_{B'}[I]_B$  so that  $\begin{pmatrix} b'_1 \\ b'_2 \end{pmatrix} = {}_{B'}[I]_B \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$  for all vectors  $\vec{v}$  in  $\mathfrak{R}^2$ .

**MATH 293 SPRING 1993 FINAL # 5**

**2.4.3 a)** Determine the matrix  $H_{E,E}$  which represents reflection of vectors in  $\mathfrak{R}^2$  about the y-axis in the standard basis  $E = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$ . Verify your answer by evaluating the expression

$$H_{E,E} \begin{pmatrix} x \\ y \end{pmatrix}.$$

- Now consider a basis  $B$  which is obtained by rotating each vector of the standard basis by 90 degrees in a counterclockwise direction. Find the change-of-basis matrices  $(B : E)$  and  $(E : B)$ .
- Find  $H_{B,B}$  from the formula  $H_{B,B} = (E : B)H_{E,E}(B : E)$ .
- It is claimed that  $H_{B,B}$  is equal to the matrix  $H_{E,E}$  which represents a reflection about the x-axis in the standard basis. Do you agree? Give geometrical reasons for your answer by drawing a suitable picture.

**MATH 293 FALL 1995 PRELIM 3 # 2**

**2.4.4** Consider the vector space  $\mathfrak{R}^3$  and the three bases:

$$\text{the standard basis } E = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\},$$

$$\text{the basis } B = \left\{ \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \right\}, \text{ and}$$

$$\text{the basis } C = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\}.$$

- a) Given the  $E$  coordinates of a vector  $\vec{x}$ ,  $[\vec{x}]_E = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$ , find  $[x]_C$ .
- b) Given the  $B$  coordinates of a vector  $\vec{y}$ ,  $[\vec{y}]_B = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$ , find the coefficients  $y_j$  in  $\vec{y} = y_1\vec{e}_1 + y_2\vec{e}_2 + y_3\vec{e}_3$ .
- c) Find the change-of-coordinates matrix  ${}_C P_B$  whose columns consist of the  $C$  coordinate vectors of the basis vectors of  $B$ .

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**2.4.5** Let

$$B = \left\{ \begin{bmatrix} -1 \\ 8 \end{bmatrix}, \begin{bmatrix} 1 \\ -5 \end{bmatrix} \right\}, C = \left\{ \begin{bmatrix} 1 \\ 4 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}.$$

- a) Find the change of coordinate matrix from  $B$  to  $C$ .
- b) Find the change of coordinate matrix from  $C$  to  $B$ .

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**2.4.6** Let

$$B = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \end{bmatrix} \right\}, C = \left\{ \begin{bmatrix} 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \end{bmatrix} \right\}.$$

Then the change of coordinates matrix from coordinates with respect to the basis  $C$  to coordinates with respect to the basis  $B$  is

- a)  $\begin{pmatrix} 2 & -2 \\ 0 & 2 \end{pmatrix}$
- b)  $\begin{pmatrix} -4 & 4 \\ 0 & -4 \end{pmatrix}$
- c)  $\begin{pmatrix} 0 & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$
- d)  $\begin{pmatrix} 0 & 4 \\ 4 & 4 \end{pmatrix}$
- e) none of the above

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**2.4.7** You are given a vector space  $V$  with an inner product  $\langle, \rangle$  and an orthogonal basis  $B = \{\vec{b}_1, \vec{b}_2, \vec{b}_3, \vec{b}_4, \vec{b}_5\}$  for  $V$  for which  $\|\vec{b}_i\| = 2, i = 1, \dots, 5$ . Suppose that  $\vec{v}$  is in  $V$  and

$$\langle \vec{v}, \vec{b}_1 \rangle = \langle \vec{v}, \vec{b}_2 \rangle = 0$$

$$\langle \vec{v}, \vec{b}_4 \rangle = 3, \langle \vec{v}, \vec{b}_4 \rangle = 4, \langle \vec{v}, \vec{b}_5 \rangle = 5$$

Find the coordinates of  $\vec{v}$  with respect to the basis  $B$  i.e. find  $c_1, c_2, c_3, c_4, c_5$  such that

$$\vec{v} = c_1\vec{b}_1 + c_2\vec{b}_2 + c_3\vec{b}_3 + c_4\vec{b}_4 + c_5\vec{b}_5$$

**MATH 294 SPRING 1998 PRELIM 3 # 3**

**2.4.8** Let  $T : \wp_1 \rightarrow \wp_3$  be defined by

$$T[p(t)] = t^2 p(t)$$

and take

$$B = \{1, 1 + t\}$$

to be the basis of  $\wp_3$ .

a) Find the matrix of  $T$  relative to the bases  $B$  and  $C$ .

b) Use this matrix to find  $T[2 + t]$ .

c) Let  $E = \{1, t\}$  be the standard basis for  $\wp_1$ . Let  $[\vec{x}]_B$  be the coordinate vector of  $\vec{x}$  in  $\wp_1$  relative to the basis  $B$ , and let  $[\vec{x}]_E$  be the coordinate vector of  $\vec{x}$  relative to the basis  $E$ . What is the change of coordinate matrix  $P$  such that

$$P[\vec{x}]_B = [\vec{x}]_E.$$

[Note: The result of part c) does not depend on the results of parts a) or b)]

**MATH 294 SPRING 1998 Final # 4**

**2.4.9** In  $P^2$ , Find the change-of-coordinate matrix from the basis

$$B = \{1 - 2t + t^2, 3 - 5t, 2t + 3t^2\}$$

to the standard basis

$$E = \{1, t, t^2\}.$$

Then write  $t^2$  as a linear combination of the polynomials in  $B$ , i.e. give the coordinates of  $t^2$  with respect to the basis  $B$ .

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**2.4.10** Besides the standard basis  $\varepsilon$  here are two bases for  $\mathfrak{R}^2$ :

$$B = \left\{ \underbrace{\begin{bmatrix} 1 \\ 1 \end{bmatrix}}_{b_1}, \underbrace{\begin{bmatrix} -1 \\ 1 \end{bmatrix}}_{b_2} \right\}, C = \left\{ \underbrace{\begin{bmatrix} 2 \\ 4 \end{bmatrix}}_{c_1}, \underbrace{\begin{bmatrix} -4 \\ 4 \end{bmatrix}}_{c_2} \right\}$$

- a) What vectors  $\vec{x}$  are represented by  $[\vec{x}]_B = \begin{bmatrix} 2 \\ 14 \end{bmatrix}$  and  $[\vec{x}]_C = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$ ?
- b) Find a single tidy formula to find the components  $\begin{bmatrix} d \\ e \end{bmatrix}$  of a vector  $\vec{x}$  in the basis  $B$  if you are given the components  $\begin{bmatrix} f \\ g \end{bmatrix}$  of  $\vec{x}$  in the basis  $C$ .
- c) A student claims that the desired formula is  $\begin{bmatrix} d \\ e \end{bmatrix} = \begin{bmatrix} 5 & -2 \\ 5 & 1 \end{bmatrix} \begin{bmatrix} f \\ g \end{bmatrix}$ . Does this formula make the right prediction for the component vector  $[\vec{x}]_C = \begin{bmatrix} f \\ g \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$ ?

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**2.4.11** Let  $A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$ .

- a) Find orthogonal eigenvectors  $\{\vec{v}_1, \vec{v}_2\}$  of  $A$ . [Hint: do not go on to parts d-e below until you have double checked that you have found two orthogonal unit vectors that are eigenvectors of  $A$ .]
- b) Use the eigenvectors above to diagonalize  $A$ .
- c) Make a clear sketch that shows the standard basis vectors  $\{\vec{e}_1, \vec{e}_2\}$  of  $\mathfrak{R}^2$  and the eigenvectors  $\{\vec{v}_1, \vec{v}_2\}$  of  $A$ .
- d) Give a geometric interpretation of the change of coordinates matrix,  $P$ , that maps coordinates of a vector with respect to the eigen basis to coordinates with respect to the standard basis.
- e) Let  $\vec{b} = \begin{bmatrix} 3 \\ 5 \end{bmatrix}$ . Using orthogonal projection express  $\vec{b}$  in terms of  $\{\vec{v}_1, \vec{v}_2\}$  the eigenvectors of  $A$ .