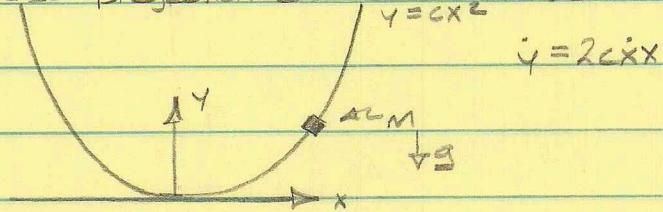


(30 min) 22a. A point-mass sliding along a parabolic nice curve of $y = cx^2$, derive equations of motion using Lagrange eq.

Use projection on the x -axis as the generalized coordinate.



$L = T - U$ where T is total kinetic energy and U is total

$$\frac{d}{dt} \left(\frac{\delta L}{\delta q} \right) - \frac{\delta L}{\delta q} = 0 \quad T = \frac{1}{2} m v^2 = \frac{1}{2} m \sqrt{\dot{x}^2 + \dot{y}^2}^2 = \frac{1}{2} m (\dot{x}^2 + \dot{y}^2)$$

$$U = mgy = mgcx^2$$

$$L = \frac{1}{2} m (\dot{x}^2 + \dot{y}^2) - \frac{1}{2} mgcx^2 = \frac{1}{2} m \dot{x}^2 + \frac{1}{2} m (2c \dot{x} x)^2 - mgcx^2 \\ = \frac{1}{2} m \dot{x}^2 + 2mc^2 \dot{x}^2 x^2 - mgcx^2 = \dot{x}^2 \left(\frac{1}{2} m + 2mc^2 x^2 \right) - mgcx^2$$

$$\frac{\delta L}{\delta \dot{x}} = 2\dot{x} \left(\frac{1}{2} m + 2mc^2 x^2 \right) = \dot{x} m (1 + 4c^2 x^2)$$

$$\frac{\delta L}{\delta x} = 4mc^2 \dot{x}^2 x - 2mgcx$$

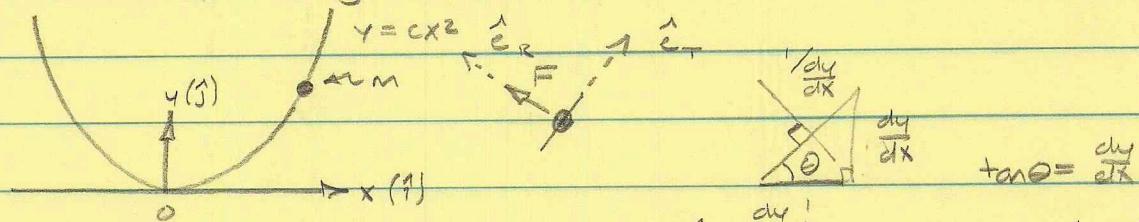
$$\frac{d}{dt} (\dot{x} m (1 + 4c^2 x^2)) - 4mc^2 \dot{x}^2 x + 2mgcx = 0$$

$$\ddot{x}m (1 + 4c^2 x^2) + \dot{x}m (8c^2 \dot{x} x) - 4mc^2 \dot{x}^2 x + 2mgcx = 0$$

$$\ddot{x}m (1 + 4c^2 x^2) + 8mc^2 x \dot{x}^2 - 4mc^2 \dot{x}^2 x + 2mgcx = 0$$

$$\boxed{\ddot{x} (1 + 4c^2 x^2) + 4c^2 x \dot{x}^2 + 2gcx = 0} \quad \checkmark$$

(45 min) 22b. Same setup, using Newton's laws.



$$\tan \theta = \frac{dy}{dx}$$

$$\theta = \tan^{-1}\left(\frac{dy}{dx}\right)$$

$$\hat{e}_T = \frac{\hat{i} + \frac{dy}{dx}\hat{j}}{\sqrt{1 + \left(\frac{dy}{dx}\right)^2}}$$

$$\hat{e}_R = \frac{-\hat{i} + \frac{1}{\frac{dy}{dx}}\hat{j}}{\sqrt{1 + \left(\frac{dy}{dx}\right)^2}}$$

Linear momentum balance:

$$\sum \vec{F} = m\vec{a} \quad \frac{dy}{dx} = 2cx$$

$$\hat{e}_T(-mg\hat{j} + F\hat{e}_R = m\vec{a})$$

$$-mg\hat{j} \cdot \hat{e}_T = m\vec{a} \cdot \hat{e}_T = m(\ddot{x}\hat{i} + \ddot{y}\hat{j}) \cdot \hat{e}_T$$

$$\frac{-2mgcx}{\sqrt{1 + (2cx\dot{x})^2}} = \frac{m\ddot{x}}{\sqrt{1 + (2cx\dot{x})^2}} + \frac{m\ddot{y} \cdot 2cx}{\sqrt{1 + (2cx\dot{x})^2}}$$

$$-2mgcx = m\ddot{x} + 2gcx\ddot{y} \quad \ddot{y} = \frac{d}{dt}(y) = \frac{d}{dt}(2cx\dot{x})$$

$$-2gcx = \ddot{x} + 2cx \cdot [2c(\dot{x}^2 + \dot{x}\dot{x})] = \ddot{x} + 2c(\dot{x}^2 + \dot{x}\dot{x})$$

$$-2gcx = \ddot{x} + 2cx[2c\dot{x}^2 + 2c\dot{x}\dot{x}] = \ddot{x} + 4c^2x\dot{x}^2 + 4c^2x^2\dot{x}$$

$$-2gcx = \ddot{x}(1 + 4c^2x^2) + 4c^2x\dot{x}^2$$

$$\boxed{\ddot{x}(1 + 4c^2x^2) + 4c^2x\dot{x}^2 + 2gcx = 0}$$

✓

(5 min) 22c. Find frequency for small vibrations in terms of m, g, c.

Assume that all non-linear terms go to zero for small vibrations

$$\ddot{x}(1 + 4c^2x^2) + 4c^2x\dot{x}^2 + 2gcx = 0 \rightarrow \ddot{x} + 2gcx = 0$$

$$\rightarrow \omega_n = \sqrt{2gc}$$