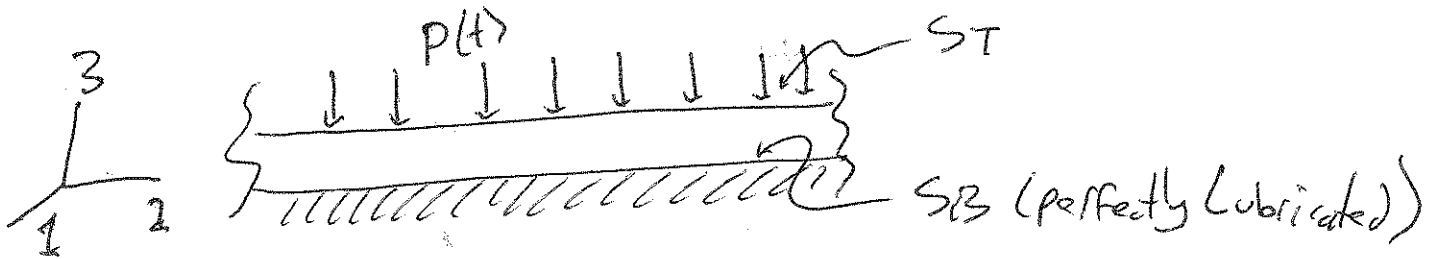


Solid Mechanics.

- ② You have an isotropic elastic material confined at infinity
 s.t. $u_1 = u_2 = 0$ there (see picture). Imagine that a pressure
 is applied on the top $p = p(t)$. Derive the equation
 of motion. ^{for u_3} what is the wave speed.



B.L.S²

ST: $\sigma_{33} = p(t)$, all others 0.

SB: $u_3 = 0$

we'll do it later.

~~from before we saw that σ_{ij} had only~~

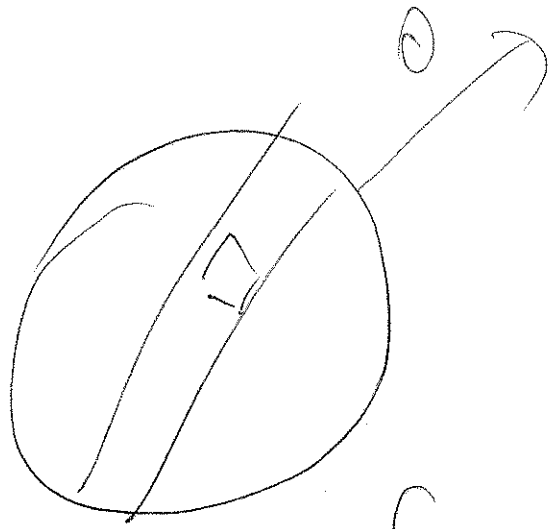
from before, we saw that $u_3 = \frac{p \times x_3}{E}$. Start with

$$\sigma_{ij} + \rho_i = \rho a_i \quad ; \quad \sigma_{33,3} = \rho \ddot{u}_3$$

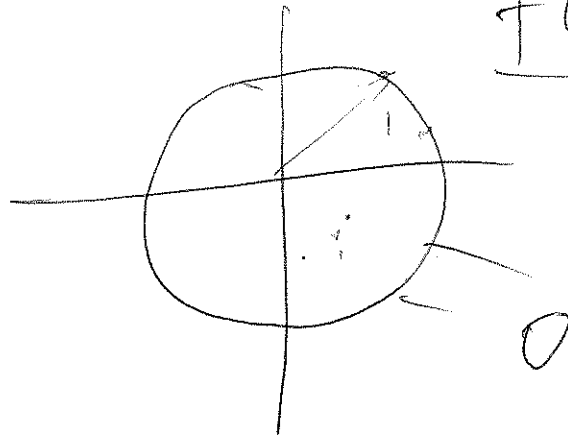
$$\sigma_{33} = \rho_{3,3} = \frac{p(t)}{E}, \quad \sigma_{33} = 2\mu \epsilon_{33} + \lambda \sigma_{kk} \quad ; \quad \epsilon_{kk} = \sigma_{33}$$

$$\sigma_{33} = (2\mu + \lambda) \frac{p(t)}{E}$$

$$e^{e^{i\theta}}$$



$f(z)$



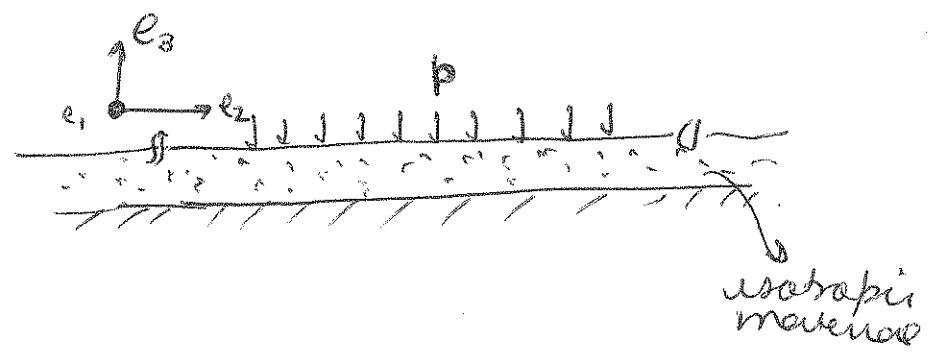
~~$\frac{\pi}{2}$~~

$$\frac{1}{2\pi i} \int_{\gamma} \frac{f(z)}{z-t} dz =$$

$$\frac{P.t.3}{\pi}$$

solid dynamics 2008

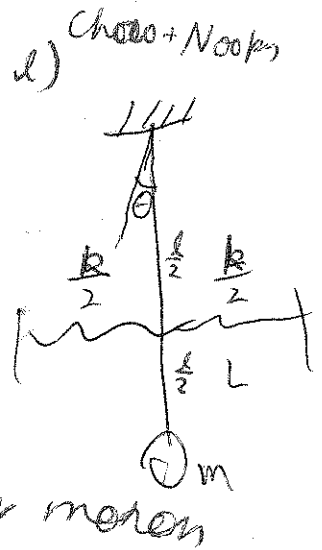
(11)



Exercises 2018

Consider a pendulum (massless rod (length l) with a mass m at end).

midway it has two springs attached to it, each of sp. constant $\frac{k}{2}$



→ using Lagrangian method, to find equation of motion

→ find frequency for small amplitude motion

① Kinetic Energy of the system

$$T = \frac{1}{2} m (\dot{\theta} L)^2 = \frac{1}{2} m \dot{\theta}^2 L^2$$

$$V = 2 \left(\frac{1}{2} \frac{k}{2} \left(\frac{L}{2} \theta \right)^2 \right) + mgL(1 - \cos\theta)$$

$$= \frac{k}{8} L \theta^2 + mgL(1 - \cos\theta)$$

Lagrangian Equations

$$L = T - V = \frac{1}{2} m \dot{\theta}^2 L^2 - \frac{k}{8} L \theta^2 - mgL(1 - \cos\theta)$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) - \frac{\partial L}{\partial \theta} = 0$$

$$m \ddot{\theta} L^2 + \frac{k}{4} L \theta + \sin\theta mgL = 0$$

$$m \ddot{\theta} + \frac{\frac{k}{4} \theta + \theta mg}{L} = 0$$

The frequency is

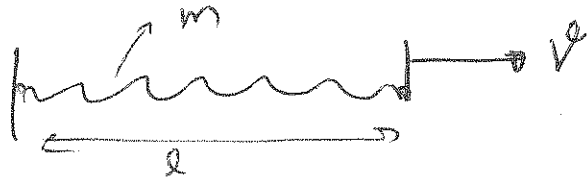
$$\boxed{m \ddot{\theta} + \frac{1}{L} \left(\frac{k}{4} + mg \right) \theta = 0}$$

$$\omega = \sqrt{\frac{1}{Lm} \left(\frac{k}{4} + mg \right)}$$

② if spring has mass what happens?

→ there would be an extra K-E energy term in Lagrangian. due to spring. P.E is same

How to get K-E of spring



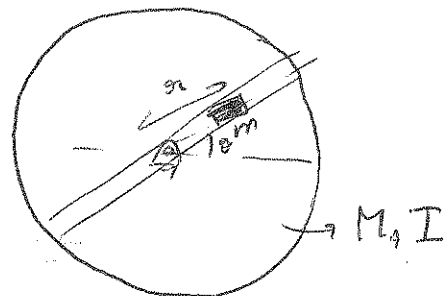
$$K-E = \frac{1}{2} \int dm v^2$$

$$= \frac{1}{2} \int_{x=0}^{x=l} \left(\frac{xv}{l} \right)^2 \frac{m}{l} dx$$

- ? do that yourself

- assume mass is uniformly distributed
- if one end is at velocity v , other end is at 0
- assume linear distribution of velocity along length of spring

Q2 There is a disc hinged frictionlessly at centre. (I, M)
 It has a frictionless groove.
 on which a mass m can
 freely slide



Sh find e.o.m

gen coordinates r, θ

$L = K.E = \frac{1}{2} I \dot{\theta}^2 + \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2)$

e.o.m finally come out

no force on m in \hat{e}_r dir

①

for $\theta = \pi$ $\ddot{r} - r\dot{\theta}^2 = 0$

for $\theta = \theta$ $I\ddot{\theta} + m r^2 \dot{\theta} = \text{const}$

this is same as total angular momentum conserved

②

also there is energy conservation

$\frac{1}{2} I \dot{\theta}^2 + \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) = \text{const} \rightarrow$ ③

does the θ goes to ∞ as $t \rightarrow \infty$ for any of the initial conditions.
 (Typical Prof Ruina style)
 (also in Dynamics 570 HW's).

from ① we see $\ddot{r} = r\dot{\theta}^2$ always pos $\therefore r$ always increase as $t \rightarrow \infty$ $r \rightarrow \infty$

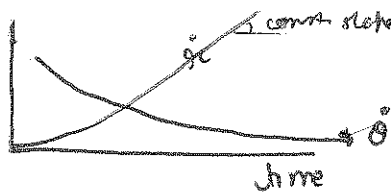
from ② $\dot{\theta} = \frac{\text{const}}{I + m r^2} \therefore$ as $t \rightarrow \infty$ $r \rightarrow \infty$
 $\dot{\theta} \rightarrow 0$

from ③ $\dot{\theta} \rightarrow 0$ this means total energy (which is conserved) goes to \dot{r} motion of particle (disc kinda stops).

\therefore as $t \rightarrow \infty$ $\dot{r} \rightarrow \text{constant}$

with this info. \Rightarrow

from (2)



$$\dot{\theta} = \frac{\text{const}}{I + mr^2} = \frac{k}{I + mr^2}$$

$$\therefore \int_0^{\infty} \dot{\theta} dt = k \int_0^{\infty} \frac{dt}{I + mr^2}$$

$$\theta_{\infty} = k \int_0^a \frac{dt}{I + mr^2} + k \int_a^{\infty} \frac{dt}{I + mr^2}$$

1) if a is some large value of time but still finite, then first integral is finite.

2) in second integral, we can use fact that after large time $\dot{r} = \text{const}$ $r = \text{const} + \text{const } t$
 $r = C_1 + C_2 t$

$$\therefore \text{second integral} = k \int_a^{\infty} \frac{dt}{(I + mC_1^2 + mC_2^2 t^2 + 2mC_1 C_2 t)}$$

now this integral also converges because it is comparable with (remember Maths 101).

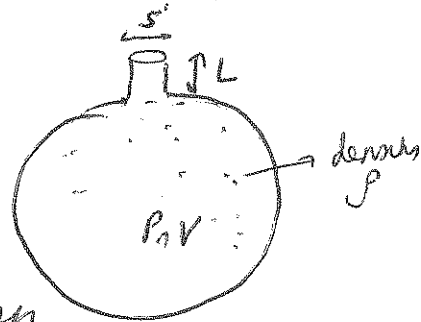
$$\int_a^{\infty} \frac{dt}{t^2} \text{ which converges to } \frac{1}{a}$$

\therefore both integrals converge

hence θ_{∞} is finite

QED!

Q3 Consider a big flask with volume V , filled with air at pressure P . It has a small neck of length l , and cross-section area S . Air follows the law $PV^\gamma = \text{constant}$ when you blow over the neck, a sound comes. find frequency of that sound (after modelling it as a spring mass system).



STATE ASSUMPTIONS

→ big flask's volume and pressure is almost $P_0 V$, it fluctuates a little, because of up and down motion of air in the neck.

→ wavelength of the motion is small (I don't know what exactly it helps in ask Sachse)

→ model the system, what is 'moving mass', and what is the 'spring constant'.

i) so mass which is moving is the air in neck.

$$m = \rho L S$$

ii) spring effect comes from fluctuations in large flask due to movement of air column.

if air column moves down by x

• volume decreases to $V - Sx$

• new $PV^\gamma = \text{const}$

$$\Rightarrow \frac{\Delta P}{P} + \gamma \frac{\Delta V}{V} = 0$$

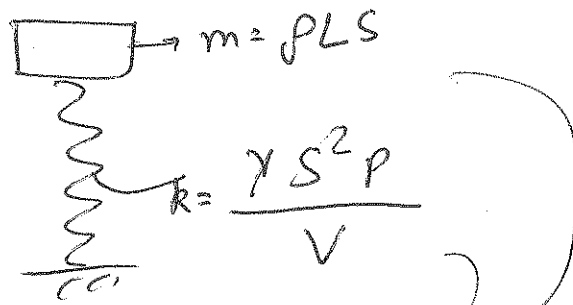
$$\therefore \Delta P = -\frac{\gamma P \Delta V}{V} = -\frac{\gamma P}{V} (-Sx)$$

• this generates a force upwards

$$F = S \Delta P = \frac{S^2 \gamma P}{V} x$$

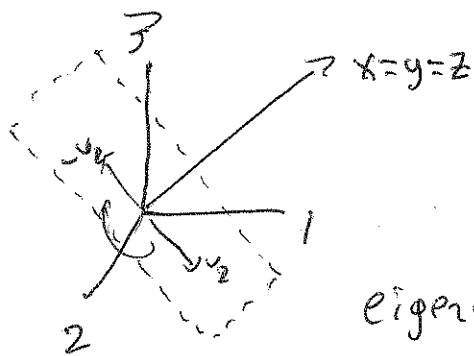
spring constant

m model is



∴ frequency of motion = $\sqrt{\frac{k}{m}}$

- ① The Linear Transform L rotates vectors in 3space^{180°} about the line $x=y=z$. Find the eigenvectors and eigenvalues of L . Write L as a matrix.



a) Note that vectors on the line $x=y=z$ get mapped onto themselves.

thus $\vec{v}_1 = \frac{1}{\sqrt{3}}(\hat{e}_1 + \hat{e}_2 + \hat{e}_3)$ is an eigenvector with eigenvalue of 1.

Next, note that vectors in the plane \perp to $x=y=z$ & passing through the origin get mapped to their opposite. Thus the e-value is

① -1 , and we need 2 evectors to span the plane.

let $\vec{v}'_2 = \hat{e}_1$, $\vec{v}'_3 = \hat{e}_3$, use gram-schmidt to find \vec{v}_2 & \vec{v}_3

b) in the basis V , $L = \begin{bmatrix} 1 & & \\ & -1 & \\ & & -1 \end{bmatrix} \rightarrow [L]^e = [R]^T [L]^N [R]$

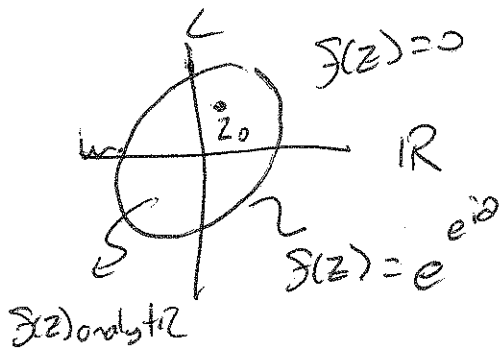
with $R^T = \begin{bmatrix} \left[\vec{v}_1 \right]^e & \left[\vec{v}_2 \right]^e & \left[\vec{v}_3 \right]^e \end{bmatrix}$

2008

David

②

Can you find a function s.t. $f(z) = e^{e^{i\theta}}$ on the unit circle, $f(z) = 0$ outside the unit circle and $f(z)$ is analytic inside the unit circle?



We know that for any point inside the unit circle,

$$f(z_0) = \frac{1}{2\pi i} \oint_C \frac{f(z)}{z - z_0}$$

if $f(z)$ is analytic on the domain enclosed by the simple closed curve, positively oriented C . Take $C =$ unit

Circle. $z = e^{i\theta}$
 $dz = ie^{i\theta} d\theta$
 \rightarrow

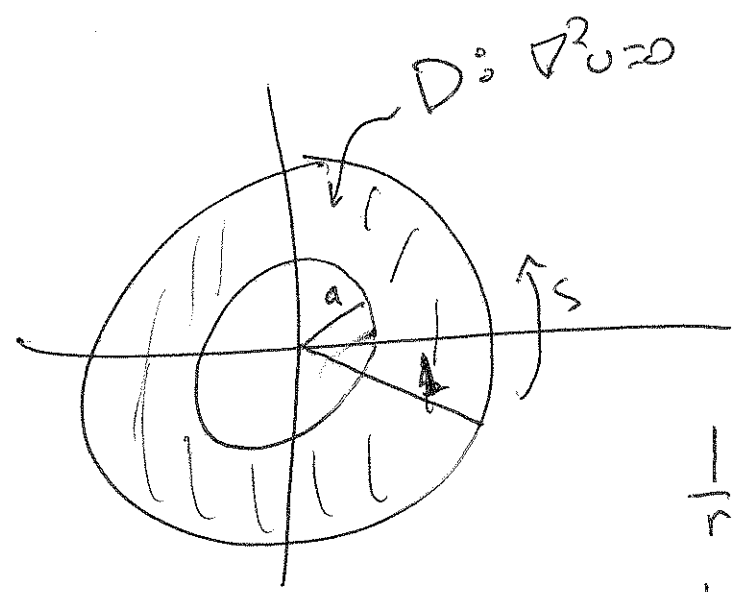
$$f(z) = \frac{1}{2\pi i} \int_0^{2\pi} \frac{e^{e^{i\theta}} ie^{i\theta} d\theta}{e^{i\theta} - z}$$

Note that if z_0 is outside the unit circle, $g(z) = \frac{f(z)}{z - z_0}$

is analytic, thus $f(z) = \frac{1}{2\pi i} \oint_C g(z) dz = 0$.

③ let $\nabla(u) = 0$ on the annulus bound by concentric circles of radii $a > 0$. let ~~$U(b, \theta) = 0$~~
 $U(b, \theta) = 0, \frac{\partial U}{\partial s}(b, \theta) = 0$ where s is the curvilinear coordinate giving distance around the circle. Solve for u .

Note $u = u(r, \theta) \rightarrow \nabla^2 u = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2}$



$U(b, \theta) = 0$

$\frac{\partial U}{\partial s}(b, \theta) = 0$

$U(r, \theta) = U(r)$ by symmetry.

$\frac{1}{r} \frac{d}{dr} (r U'(r)) + \frac{1}{r^2} \cdot 0 = 0$

$\frac{1}{r} (r U''(r) + U'(r)) = 0$

$U''(r) + \frac{1}{r} U'(r) = 0 \quad (1)$

note general solution to (1) is $C_1 - C_2 \ln(r)$

$U = C_1 - C_2 \ln(r)$

B.C.'s $U(b, \theta) = 0 \rightarrow C_1 = 0$

$\frac{\partial U}{\partial s}(b, \theta) = \frac{\partial U}{\partial \theta} = 0 \rightarrow$

not unique
 sol. $U = C_2 \ln(r)$
 for any C_2

① A body is acted on by a drag force, which is $F_D \propto v^n$ $n=0, 1, 2$ & v is the velocity

(i) Discuss examples for various values of n

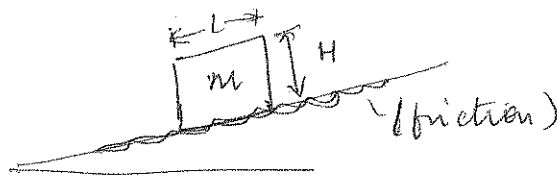
(ii) Is energy conserved?

(iii) Is momentum conserved?

(iv) Find time and distance covered by the body before as it comes to rest.

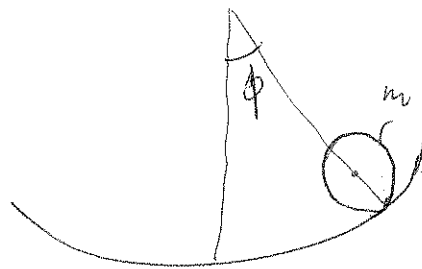
(Cady)

②



Discuss dynamics (Rand)

③



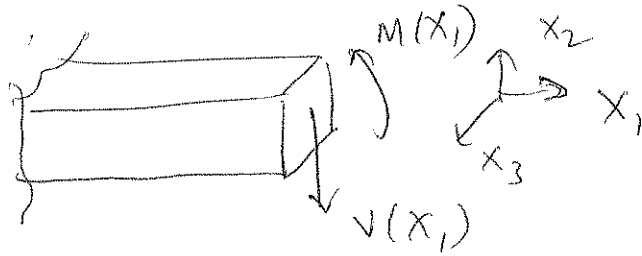
Find equations of motion for any one case

(i) The arc is frictionless

(ii) The body rolls without slipping

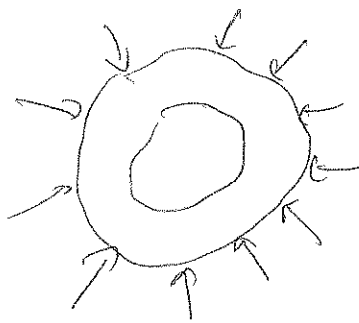
(Healy)

1



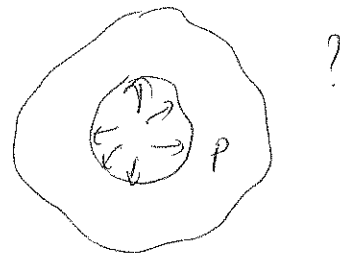
Find $\sigma_{12}(x_1, x_2, x_3)$ using continuum mechanics approach (Zehnder)

2



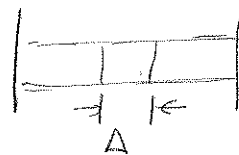
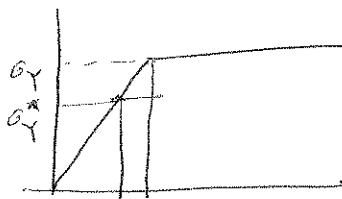
(Stress distribution known for this case)

Find stress distribution for



(Hint: Superposition) (Jenkins)

3



A rod is stressed to σ_Y (yield point) and strain is $\epsilon_0 = \sigma_Y / E$. ~~Now~~ & clamped as shown. Now, a small part (Δ) the stress drops to σ_Y^* . Find increase in length of this part.

(Phoenix)

① Solve

$$xy'' + y' + xy = 0 \quad (\text{Bessel's eq. of first kind!})$$

(Rand)

② Solve $\int_{-\infty}^{\infty} \frac{\cos x}{(x-4)} dx$ (Rand)

③ Write any PDE you know and solve it analytically.
Give different methods. (Weng)

④ $z = x + iy$
 $w(z) = u + iv$

$$u = u(x, y)$$

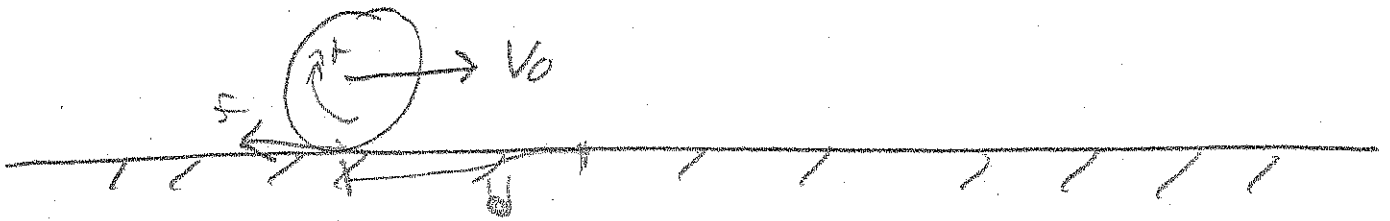
$$v = v(x, y)$$

Given $\nabla^2 \phi = 0 = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = 0$

Prove $\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = 0$

(Mukherjee)

○ A ball is released on a flat floor



How far does it slide before it is only rolling?

Make any reasonable assumptions.

$$a = -\frac{\mu mg}{m}$$

$$a = \frac{\mu mg R}{\frac{2}{5} m R^2} = \frac{5\mu g}{2R}$$

$$\omega(t) R = v(t)$$

$$[\omega(0) + \alpha t] R = [v(0) + at]$$

$$\frac{5\mu g t}{2} = v_0 - \mu g t$$

$$\frac{7}{2} \mu g t = v_0 \quad t = \frac{2v_0}{7\mu g}$$

$$d = v(0)t + \frac{1}{2} a t^2$$

$$= v_0 \frac{2v_0}{7\mu g} - \frac{\mu g}{2} \frac{4}{49} \frac{v_0^2}{\mu^2 g^2}$$

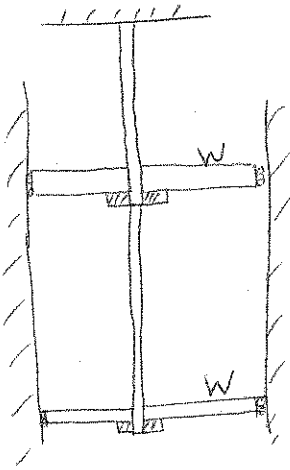
$$= \frac{2v_0^2}{7\mu g} \left[1 - \frac{1}{7} \right] = \frac{12}{49} \frac{v_0^2}{\mu g}$$

SOLID MECHANICS

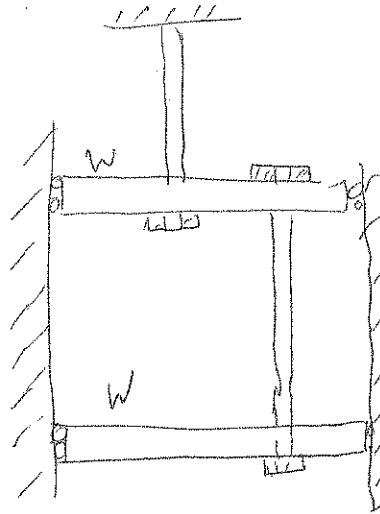
Q summer '06

Manish
~~Byin Bxian~~
Joshua

Q)



What is the practical problem in this design



Make FBD and argue what might happen?

✓) Why is a plane required to define traction. What is stress tensor and how it is related to traction. How do you get it (derivation)?

✓) What is modulus?
What is E (Young's mod.) how do you find it?
What is G (shear mod.) how do you find it?
What is ν (Poisson ratio) how do you find it?
What is strain?
the relation between ϵ & σ
definition of E, ν , bulk mod.

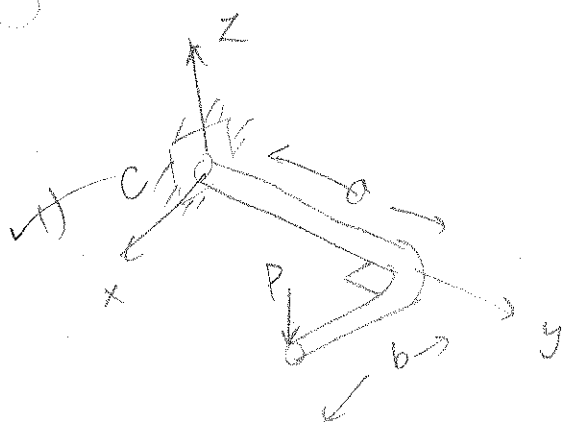
Solid Mechanics

Jan 2006

Carlos

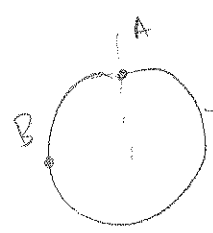
Crik

Sanjay



a) Find reactions at the support.

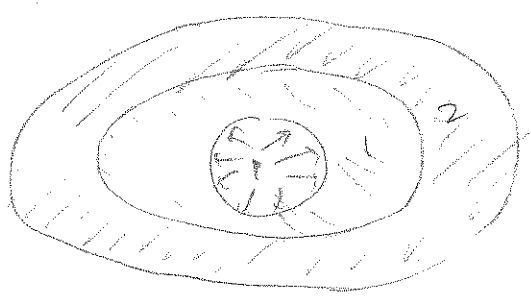
b)



cross-section @ the support 'C'

Find stress (linear) at A and B.

√2)



Two elliptical plates joined as shown.

plate ① has a circular hole
plate ② elliptical (obviously)

describe boundary and interface conditions (no need to solve)

Carlos
Erik
Sanjay

1) Define (any of) the following terms.

1) Cauchy-Riemann eq^{ns}

2) Christoffel Symbols

3) Nonlinearity

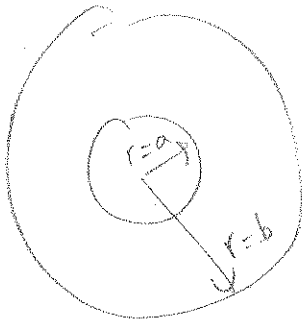
4) Eigenvectors

5) Infinitesimals

2) Solve

$$\frac{d^2 u}{dr^2} + \frac{2du}{r dr} - \frac{A}{r^2} u = 0$$

$$\left. \frac{du}{dr} \right|_{r=a} = -1, \quad u(r=b) = 0$$



3) Evaluate

$$\oint_{|z|=2} \frac{e^{\frac{1}{z-1}}}{z} dz$$

$|z|=2$

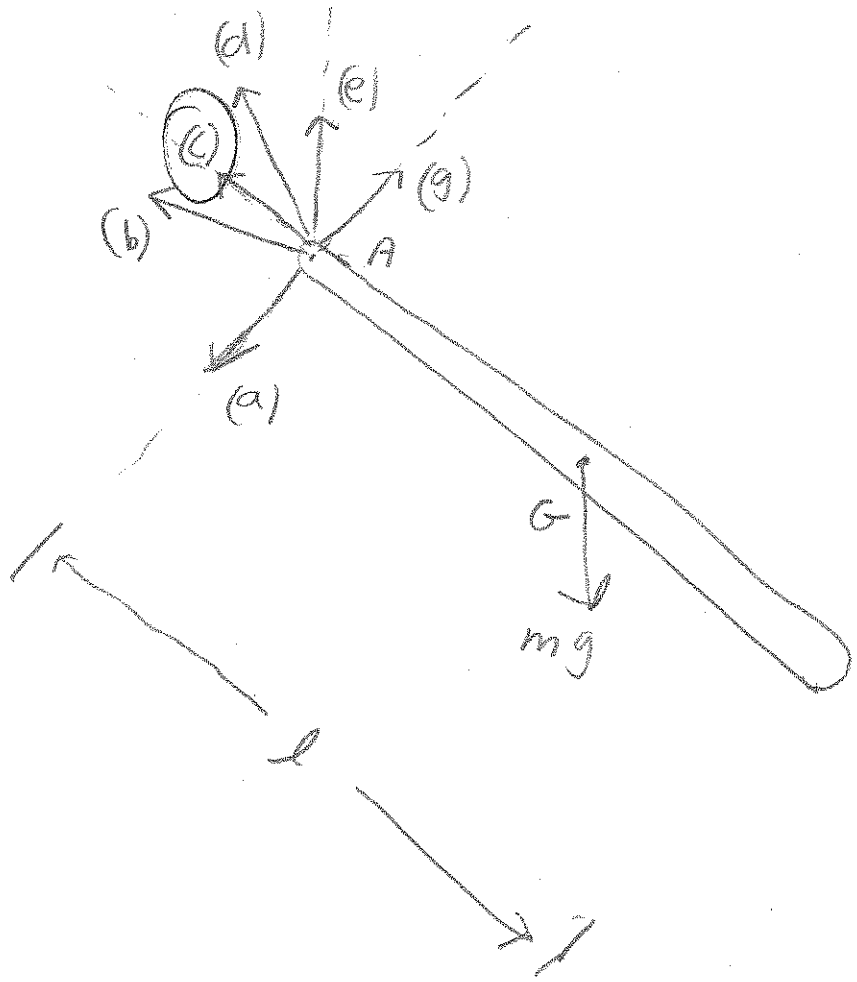


A swinging rod

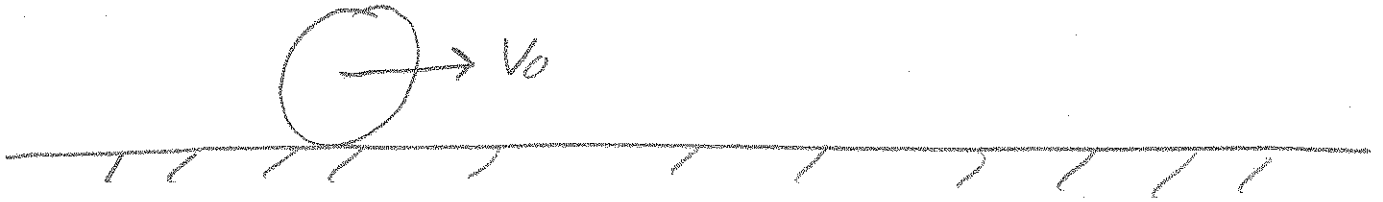
✓ given l, m, g & release angle
 $= \theta_0 = \pi/2$
(Uniform mass distribution)



At $\theta = \pi/4$ which is correct
reaction force at A : a, b, c, g, e or g?



✓ A ball is released on a flat floor



How far does it slide before it is only rolling?

Make any reasonable assumptions.

Applied Math

Jan 2006

Carlos
Erik
Sanjay

1) Define (any of) the following terms.

1) Cauchy-Riemann eq^{ns}

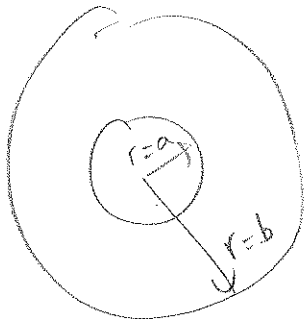
2) Christoffel Symbols

3) Nonlinearity

4) Eigenvectors

5) Infinitesimals

2) Solve $\frac{d^2 u}{dr^2} + \frac{2du}{r dr} - \frac{A}{r^2} u = 0$ $\left. \frac{du}{dr} \right|_{r=a} = -1$; $u(r=b) = 0$



3) Evaluate $\oint_{|z|=2} \frac{e^{\frac{1}{z-1}}}{z} dz$

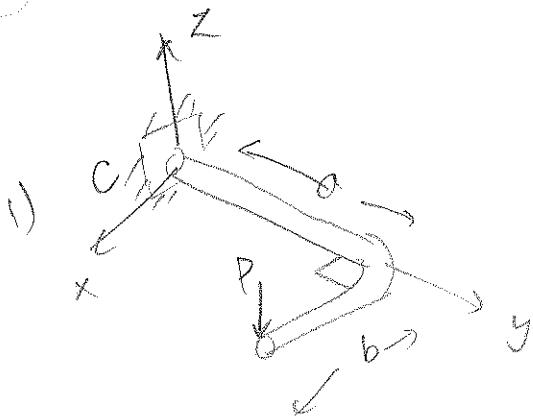
Solid Mechanics

Jan 2006

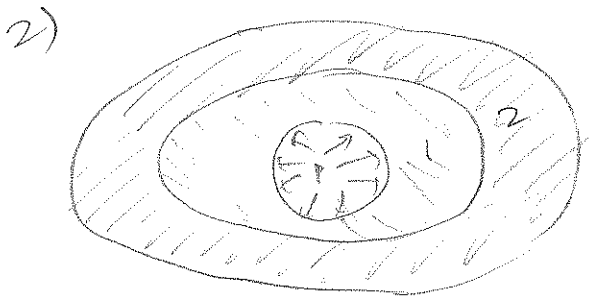
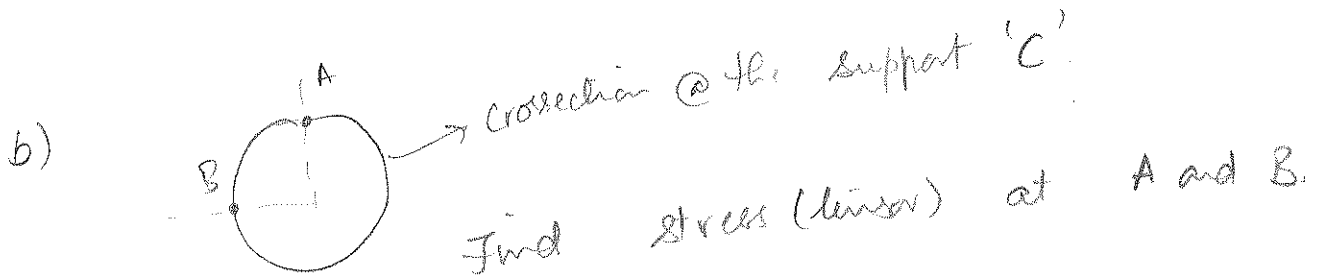
Carlos

Crik

Sanjay



a) Find reactions at the support



Two elliptical plates joined as shown.

plate ① has a circular hole
plate ② elliptical (obviously)

describe boundary and interface conditions (no need to solve)

(3) Anti plane shear. → displacements

Given $u_1 = 0; u_2 = 0; u_3 = u_3(x_1, x_2)$

Body forces

$$b_1 = 0; b_2 = 0; b_3 = b_3(x_1, x_2)$$

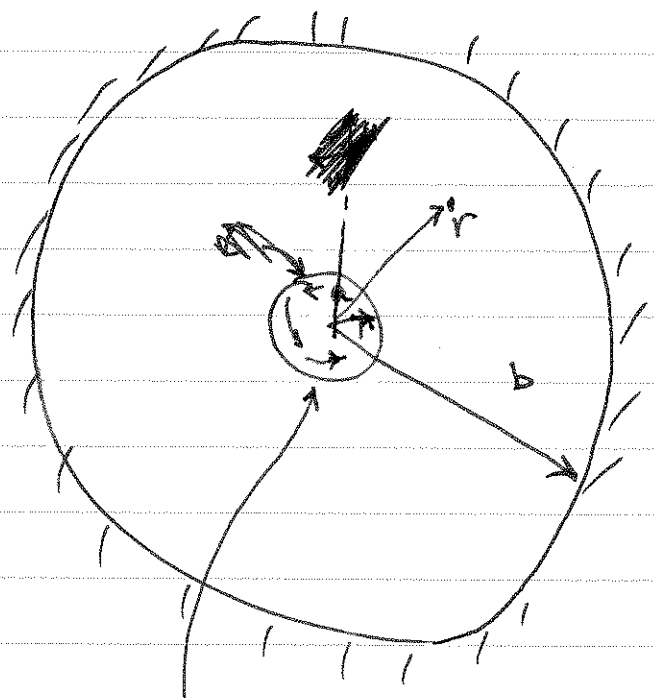
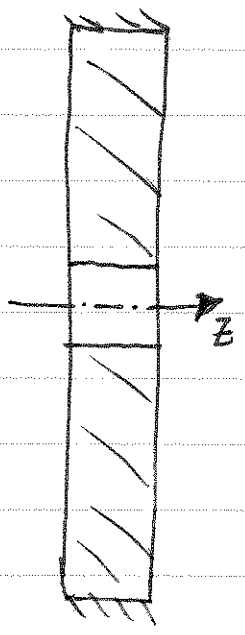
⇒ Set up the equations governing u_3

(Ans $\nabla^2 u_3 = -pb_3$) } use constitutive & equilibrium eqns

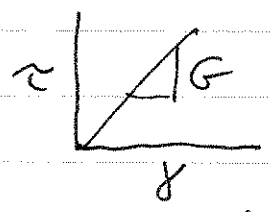
3

side view

front view (or top view)

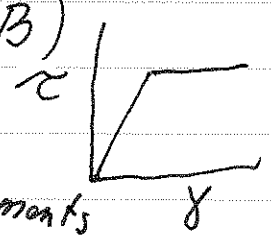


A)



Assume small displacements

B)



Shear, ~~stress~~ τ , applied on inner radius, $r=a$

Torque applied to inner rigid disk ^{or radius a}, causing shear stress τ traction,

- Find shear stress as function of r
- Find shear strain " " " r
- Find rotation of inner disk (of radius a)

Hints :

$$\gamma_{r\theta} = r \frac{\partial u_r}{\partial \theta} + \frac{\partial u_\theta}{\partial r} - u_\theta / r$$
~~$$\gamma_{r\theta} = r \frac{d\theta}{dr} + \frac{du}{dr} - \frac{u}{r}$$~~

u_r is r -component

u_θ is θ -component

3

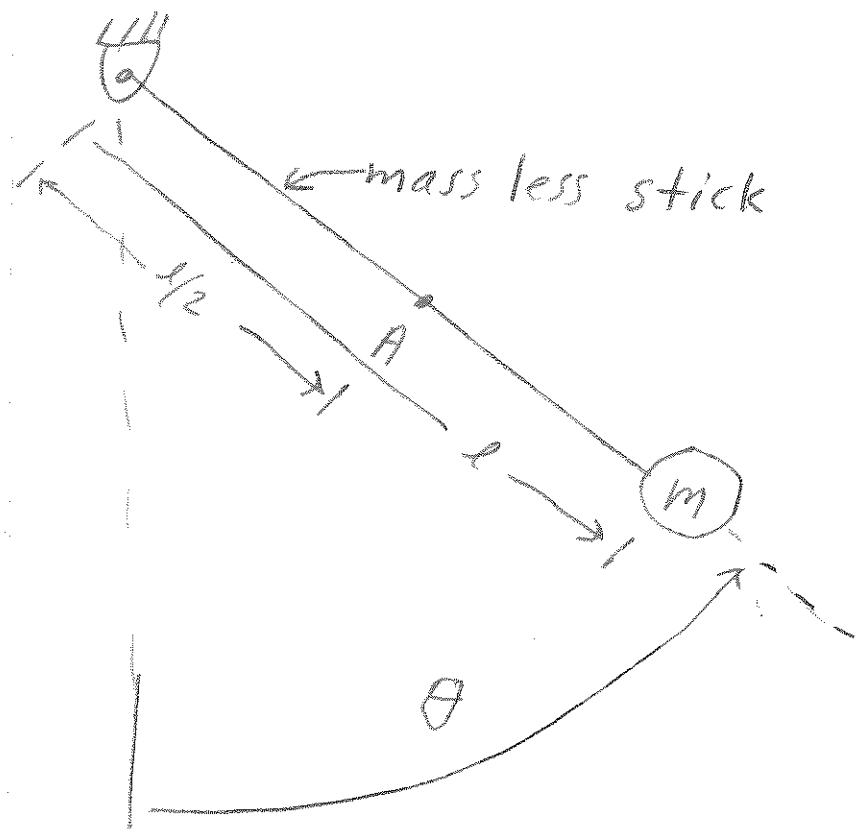
Suppose an $n \times n$ matrix A has real entries, and satisfies

$$A^T = -A.$$

Discuss the relationship between

$A\underline{v}$ and \underline{v} , for an arbitrary vector \underline{v} .

Simple pendulum; given m, g, l
Released from rest at $\theta_0 = \pi/2$.

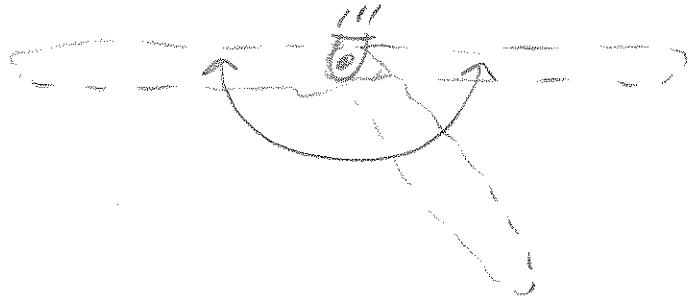


- a) Just at release ($t=0^+$) what is acceleration of pt. A?
- b) At $\theta = 0$ what is tension in rod?
- c) What is the period of oscillation?

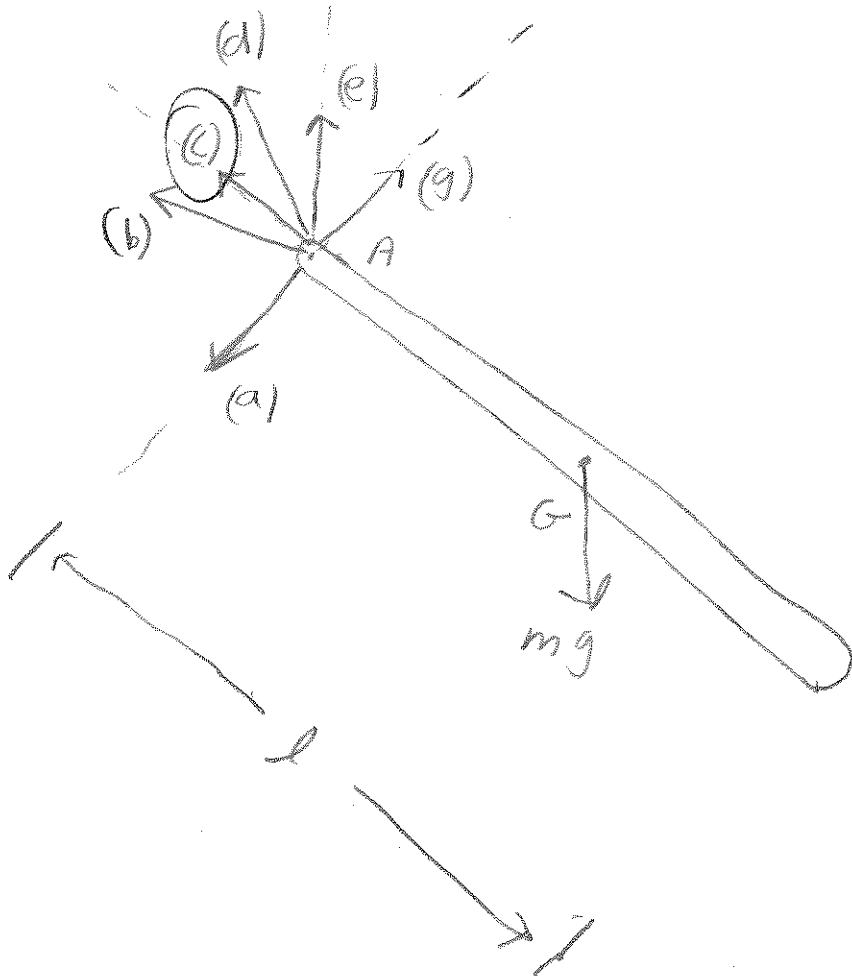
A swinging rod

given l, m, g & release angle
 $= \theta_0 = \pi/2$

(Uniform mass distribution)



At $\theta = \pi/4$ which is correct
reaction force at A : a, b, c, g, e or g?



A ball is released on a flat floor

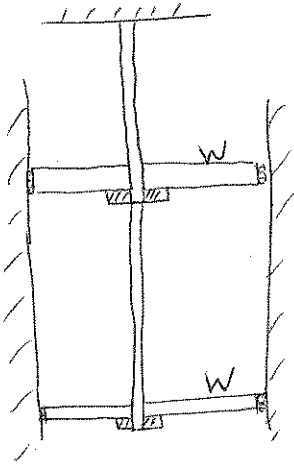


How far does it slide before it is only rolling?

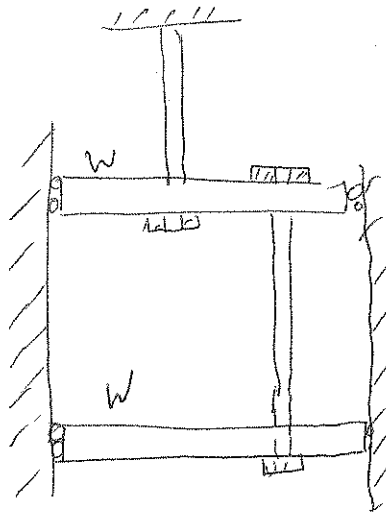
Make any reasonable assumptions.

Manish
~~Bryan~~ Brian
 Joshua

Q)



What is the practical problem in this design



Make FBD and argue what might happen?

Q) Why is a plane required to define traction. What is stress tensor and how it is related to traction. How do you get it (derivation)?

Q) What is modulus?
 What is E (Young's mod.) how do you find it?
 What is G (shear mod.) how do you find it?
 What is ν (Poisson's ratio) how do you find it?

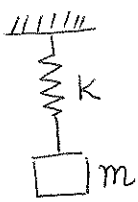
What is strain?

the relation between E & σ

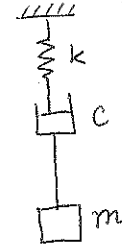
definition of E, ν , bulk mod.

Manish
Brian ~~Bryan~~
Joshua

Q)



(a)



(b)

(a) Find the equⁿ of motion of the mass

for 1) $kx = F$ and

2) $F = kx(1-x)$

compare the two situations will 2) be a periodic motion

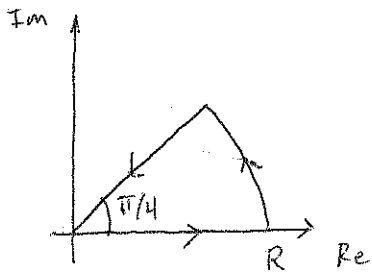
(b) what effect does the damper have on the motion of m . derive the equation

Q) A stone is dropped from the top of empire state bld. ($h = 1250$ ft) find the distance it falls away from the base (due to rotation of earth)

ANS 4"

Q) derive the equⁿ of motion for a rocket with initial mass m_0 , emission rate $= r$ (constant) and the discharge has relative velocity u w^ot rocket.

1) Use e^{ix^2} and contour in fig. A to evaluate $\int_0^{\infty} \cos(x^2) dx$



$$\int_0^{\infty} \sin(x^2) dx$$

$$2) \frac{x^{100}}{(x-1)(x-2)\dots(x-101)} = \frac{A_1}{x-1} + \frac{A_2}{x-2} + \dots + \frac{A_{101}}{x-101}$$

Find A_n

3) $L(A) = A + A^T$ A is $n \times n$ real matrix

a) find eigenvalues of L

4) a) Find Taylor's expansion of $f(x)$ about $x=a$

b) give t. expansion of two functions (say $\sin x, e^x$)

c) $f_{b^+}(x) - f_{b^-}(x) = h$ $b \in [a, c]$

find expansion of f about a .

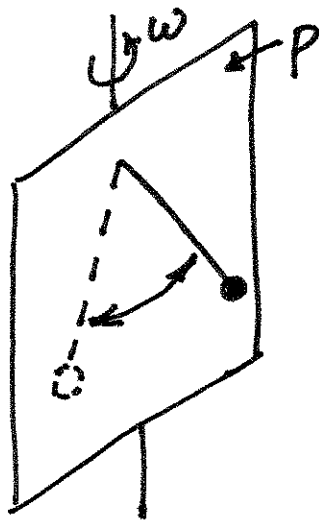
Moment-free motion of a rigid body

Let the moment of inertia relative to body fixed xyz axes be

$$\begin{aligned}\bar{\mathbf{I}} &= I_1 \hat{i}\hat{i} + I_2 \hat{j}\hat{j} + I_3 \hat{k}\hat{k} \\ &= \begin{bmatrix} I_1 & 0 & 0 \\ 0 & I_2 & 0 \\ 0 & 0 & I_3 \end{bmatrix}\end{aligned}$$

Let $\bar{\omega} = \omega_1 \hat{i} + \omega_2 \hat{j} + \omega_3 \hat{k}$ be the angular velocity of the body relative to an inertial frame.

1. Obtain the eqs of motion governing $\omega_i(t)$.
2. Use these to explain why uniform rotation about the middle moment of inertia is unstable.



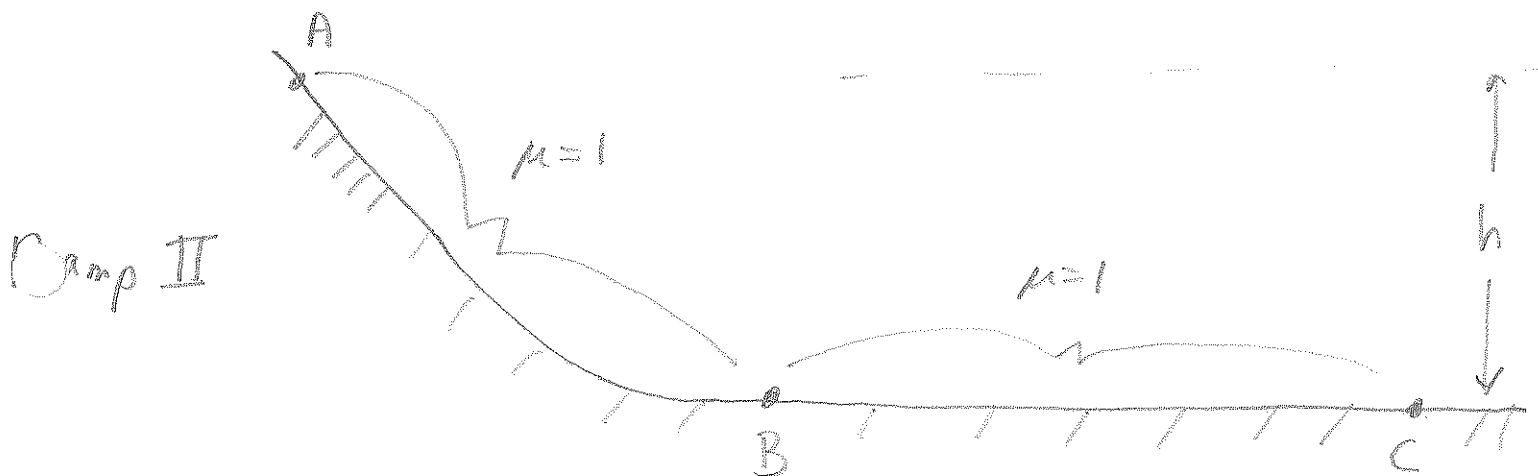
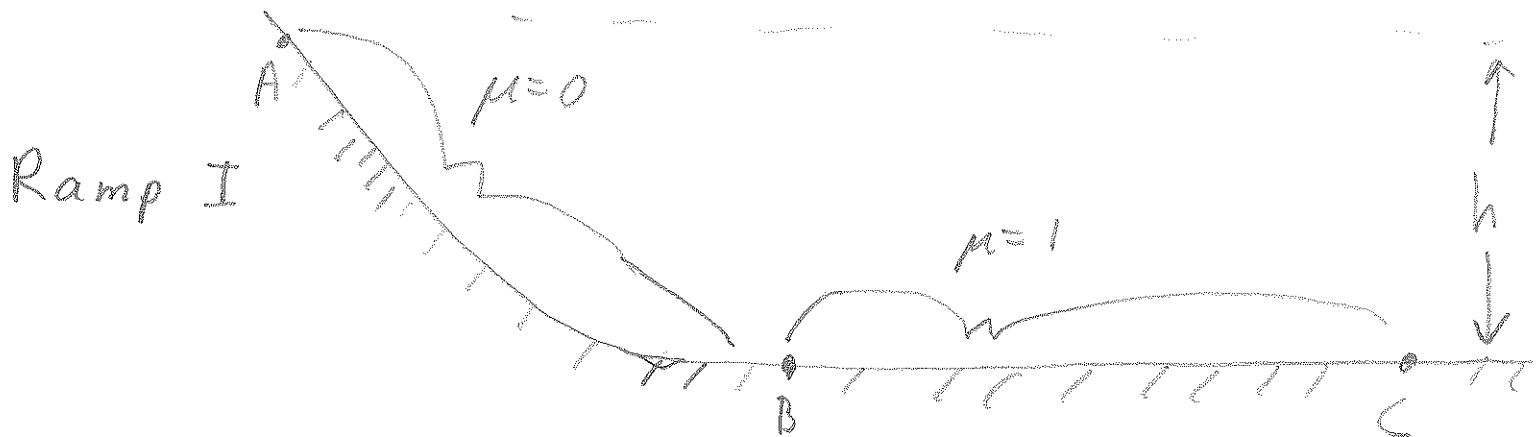
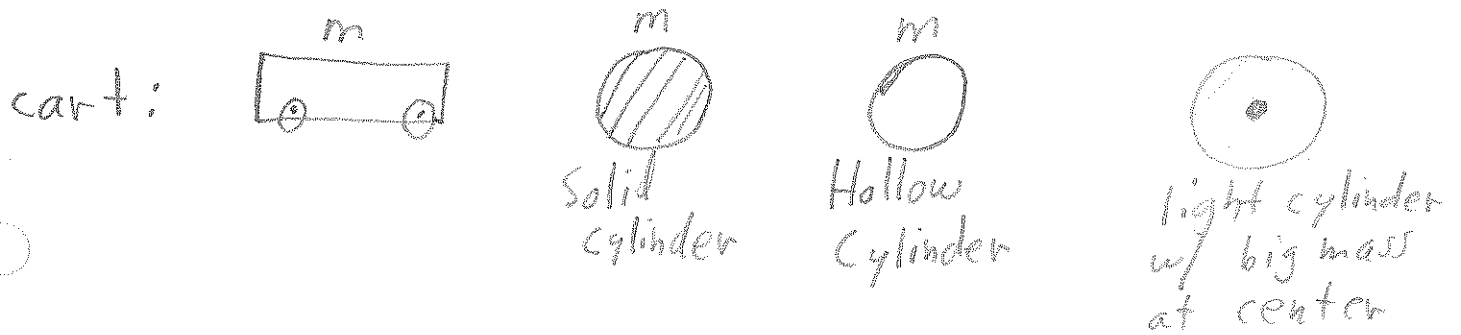
A plane pendulum is restricted to move in plane P . Plane P is forced to rotate about a vertical axis at fixed angular speed ω .

1. How many degrees of freedom does this problem have?
2. Use Lagrange's equations to derive the equation(s) of motion for this system.

Which object will travel from B to C
fastest? slowest?

Objects released from rest at A.

Answer for ramp I & ramp II.



○ Define any four of the terms below and illustrate your definition with an example:

Centripetal acceleration

Inertia

Harmonic oscillator

Linear momentum

○ Nutation

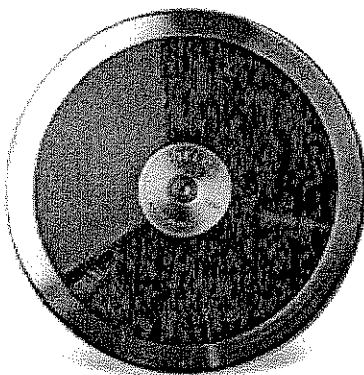
Free body diagram

An Olympic Question:

Write out the equations that describe the motion of a discus (a heavy spinning disk) after it leaves the competitor's hand. Start with the simplest possible assumptions. What is the motion?

Discuss how this model may be made more realistic. What new features will appear in the motion? How do these features arise in the solution.

Orbit Hi-Spin Discus 1k



Model Number: T82

~~Retail Price: \$193.70~~
Our Price: \$149.00

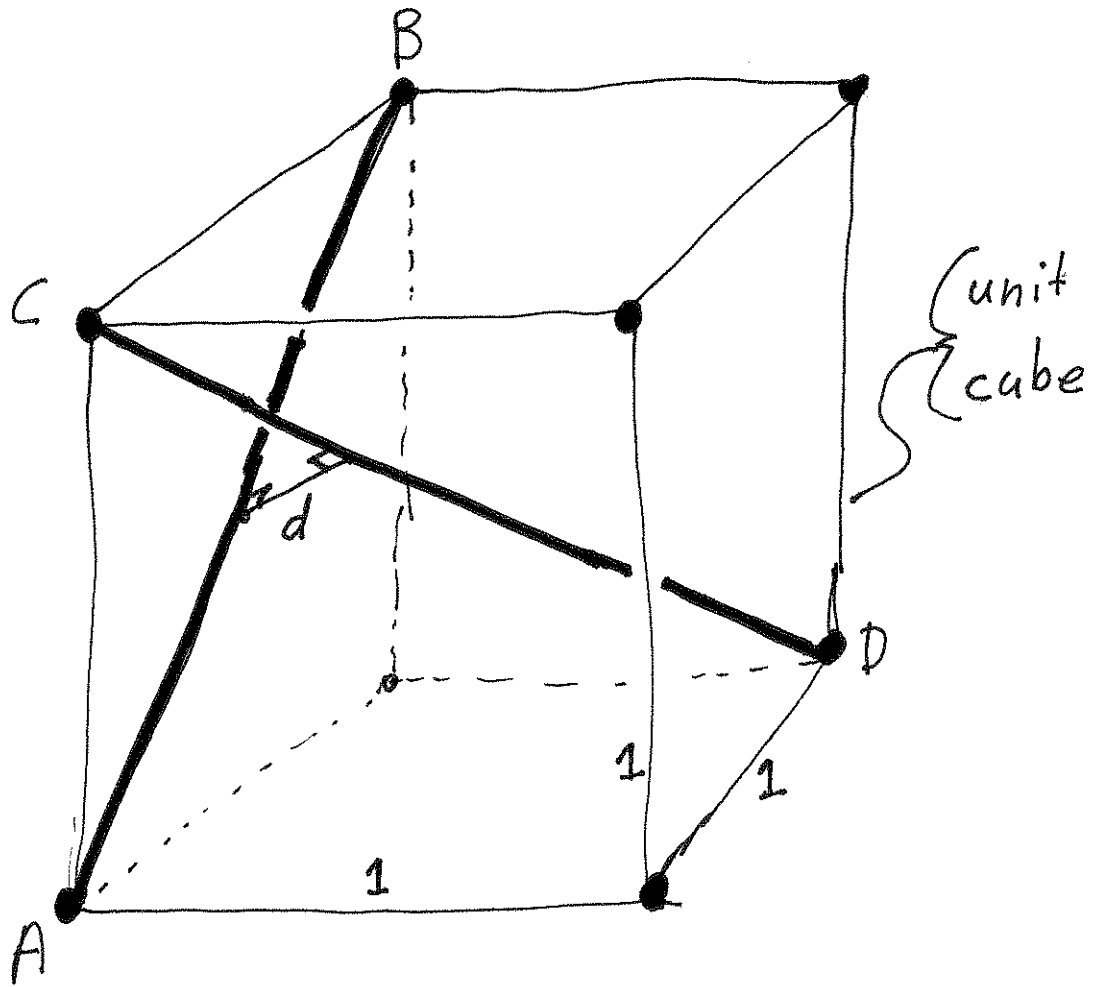
Designed for championship performance, this discus has a rim weight of 80-85% and is the preferred discus of top class throwers. High-impact resistant black ABS side plates, combined with a stainless steel rim, make this one of the best discus in the world.



Discus Videos

Chat used

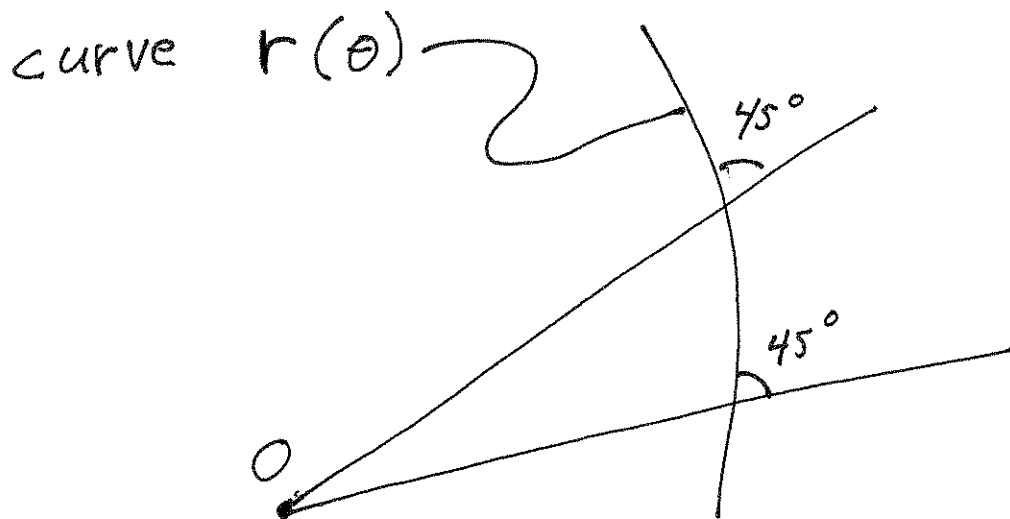
○ What is the distance between line segment AB and line segment CD ?



$$d = ?$$

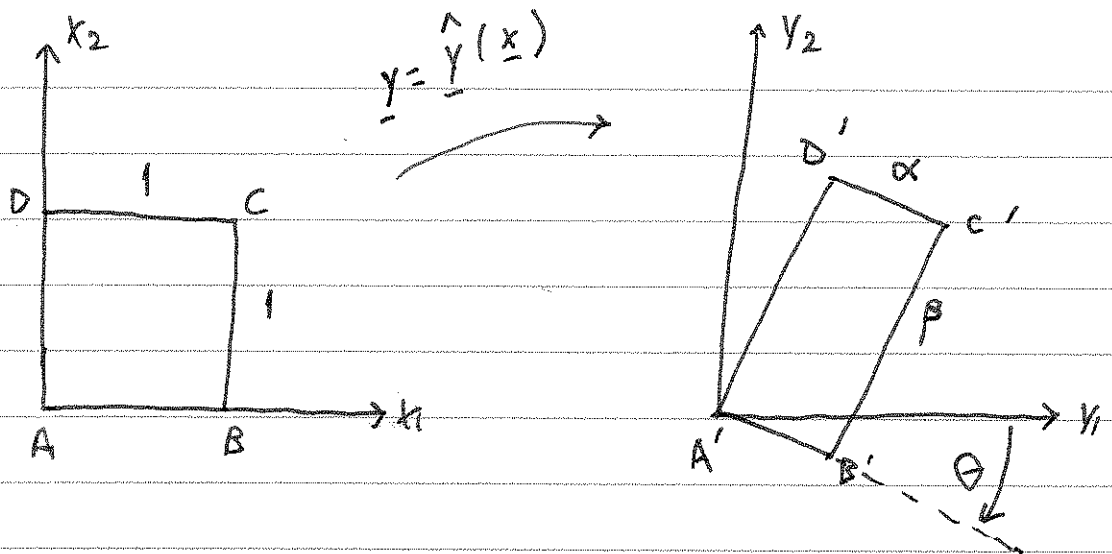
2

Find the curve $r(\theta)$ that makes a 45° angle with every radial line from the origin.



- Any such $r(\theta)$.
- Most general $r(\theta)$.

①



Find F, G, U

What are principal stretches?

Principal directions?

② Alternate form

Using balance of linear momentum,
Derive the equations of motion
for a ^{solid} body B with surface \mathcal{S} .

~~Describe quantities~~

What, exactly, are traction,
stress, and how are they related?

~~Write down the~~

②

~~Starting from N~~

Consider a body B of volume V and surface ~~area~~ \mathcal{S} .¹ Based on Newton's second law, Write down the equations of motion in \oint integral form over the whole body. Now find a local form of this equation valid at any point in the body.

Do you know how to write the virtual work principle?

4

Show

$$\int_0^{\infty} \frac{\cos x}{\sqrt{x}} dx = \frac{1}{\sqrt{2}} \int_0^{\infty} \frac{e^{-t}}{\sqrt{t}} dt$$

(not used)

Consider the equation

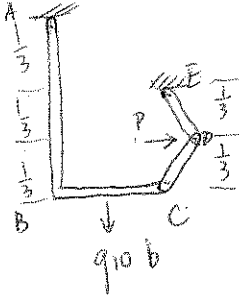
$$2f(x) + \frac{d}{dx} f(x) + \int_0^x f(x') dx' = 0.$$

a) Find a solution.

b) Find the most general solution.

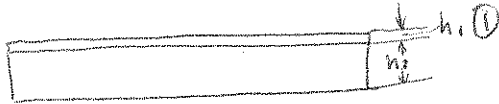
Solid Mechanics: Committee: Zender, Baker, Papanlia, Sachse

Question 1:



Find the force P which makes $\overset{A}{\underset{B}{\text{L}}}_C$ stay that way.

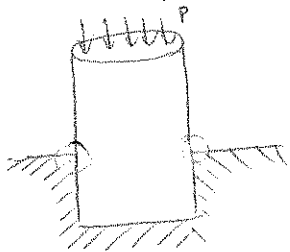
Question 2:



A large substrate with a thin layer (film) on the top. These 2 materials have different Thermal expansion Coefficients. When temperature changes, find the relationship of the curvature and the stress in the top layer

② what if $h_1 \ll h_2$

Question 3:



① find the stress field.

② which part will yield first, the top part or the bottom part.

Mathematics

Committee: Hui, Rand*, Mukherjee, Cady

Question 1: $F(z) = u(x, y) + i v(x, y)$ is analytic on domain Ω . There are two curve families $u(x, y) = c$ & $v(x, y) = c$. They intersected ~~at~~ at pt $z_0(x_0, y_0)$. Show the two ~~from~~ curve families are \perp to each other.

Question 2: ① $A = \begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix}$ Find R s.t. RAR^{-1} is a diagonal ~~tensor~~ matrix

② what's wrong with $\begin{pmatrix} 7 & 1 \\ 9 & 1 \end{pmatrix}$, why?

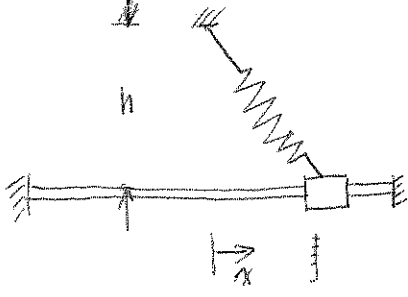
Question 3: f is defined as $f = \underline{A} \underline{V} \cdot \underline{V}$ \underline{A} is a symmetric tensor. $\underline{V} \in \mathbb{R}^n$
 Show that $\min_{\|\underline{V}\|=1} (f) = \min(\lambda_1, \lambda_2, \dots, \lambda_n)$ λ_i are the eigenvalues of \underline{A} .

Question 4: $y = f(x)$.

please find $\frac{d}{dy} \frac{dy}{dx}$ in terms of $\frac{d}{dx}$ derivative of \mathbb{R}

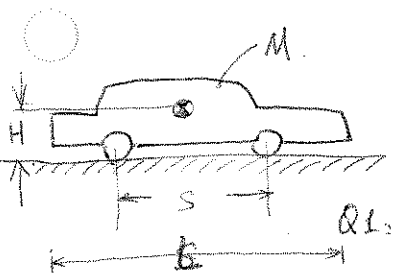
DYNAMICS Committee: Ruina, Burns, Healey* Phoenix

Question 1:



1. if $h > l$, write the motion equation(s).
2. if x is small, describe the motion.
3. if $h < l$, what happens?

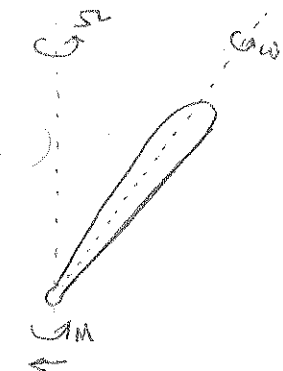
Question 2:



The wheels roll without friction on their axes. The friction parameter of the ground is μ . You can choose Front or Rear wheel to be the driven wheel. what is the ^{maximum} ~~minimum~~ acceleration of the car. (Note: assume non-driven wheel pure-rolling for on the

Q2: Which dimensions might affect the ^{maximum} acceleration: H, L, S, or M?

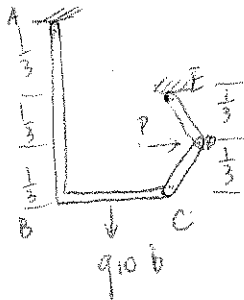
Question 3:



a baseball bat rotates with constant Ω & ω as shown on the left. (1) Find the moment on the bottom. (magnitude and direction) (2) " " Force needed.

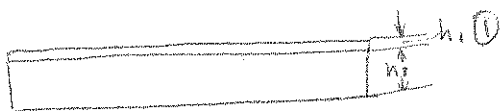
Solid Mechanics: Committee: Zender, Baker, Papoulia, Sachse

Question 1:



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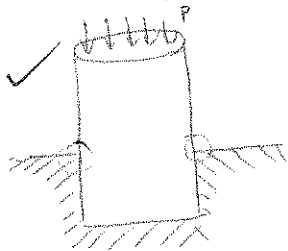
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Question 3: ~~★~~



① find the stress field

② which part will yield first, the top part or the bottom part.

Mathematics

Committee: Hui, Rand*, Mukherjee, Cady

Question 1: $F(z) = u(x,y) + iv(x,y)$ is analytic on domain Ω . There are two curve families $u(x,y)=c$ & $v(x,y)=c$. They intersected ~~at~~ at pt $z_0(x_0, y_0)$. Show the two ~~from~~ curve families are \perp to each other.

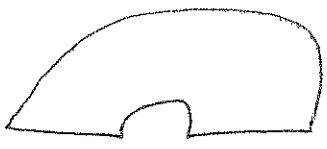
Question 2: ① $A = \begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix}$ Find R s.t. RAR^{-1} is a diagonal ~~tensor~~ Matrix

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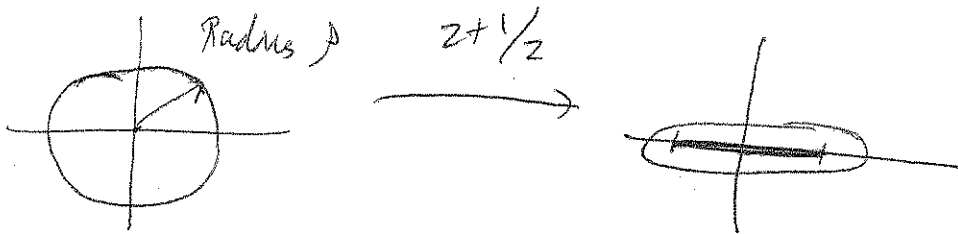
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 Show that $\min_{\|\underline{v}\|=1} f = \min(\lambda_1, \lambda_2, -\lambda_2)$ λ_i are the eigenvalues of A

Question 4: $y = f(x)$
 please find $\frac{d}{dy} \frac{dy}{dx}$ in terms of ~~the~~ derivative of $\frac{dy}{dx}$

Qualifying Exam - Aug 23, 2002 - MATHEMATICS

1. $\int_{-\infty}^{\infty} \frac{\sin x}{x} dx$ 

(or)



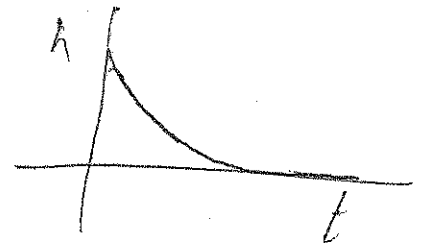
2. $h(t) - h_0 = -a \int_0^t dt \sqrt{h(t)}$

a) Is the eqn. Linear or Non-Linear?

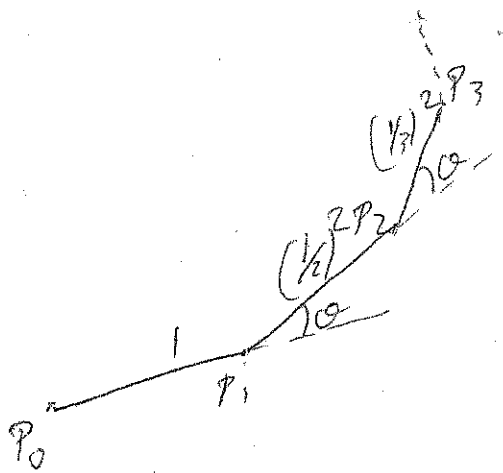
b) Equivalent Differential eqn.?

c) Sketch $h(t)$ without solving

d) Numerical Scheme



3.



$p_n \rightarrow ?$ as $n \rightarrow \infty$

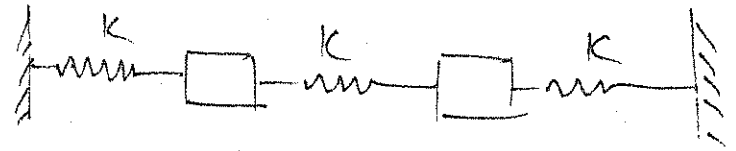
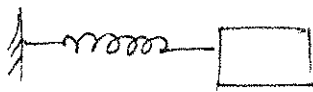
$$\sum \frac{e^{in\theta}}{n^2}$$



Dynamics

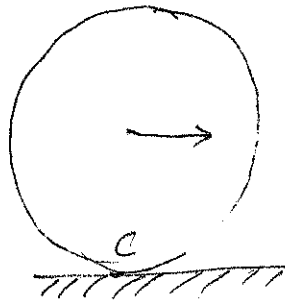
08/23/2002

Q1)



What is resonance, natural frequency, normal modes...

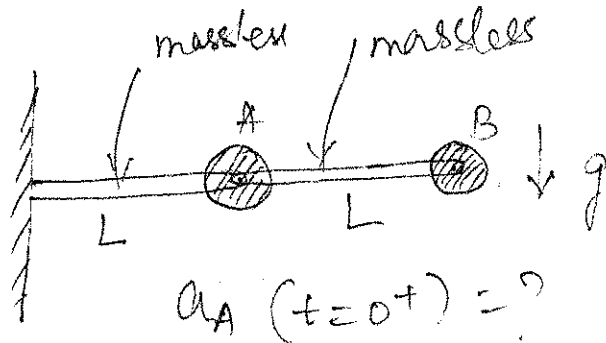
Q2)



v_0, a_0

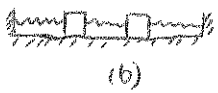
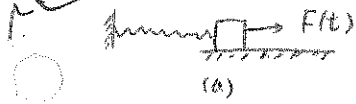
find ω, a_c, v_c etc

Q3)

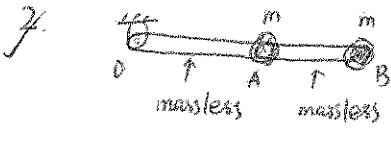


$a_A (t=0^+) = ?$

Dynamics

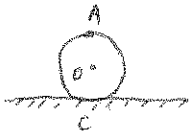


- ① Explain what is natural frequency? what is resonance?
- ② what is natural modes? where are the natural modes of (b)? what are the frequencies of the natural modes?



g

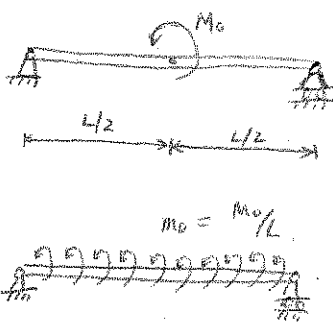
Double Pendulum, released from the current position. what are the accelerations of A and B?



Given v_0 α_0

- ① Find v_c α_c ?
- ② Find v_A α_A ?
- ③ If there is wind coming from right, all the masses concentrates in A. what are the forces acting on A? what is total force?

Solid Mechanics



- ① Find the distribution of shear force and moment in the beam, and draw them.
- ② what if there is a distributed moment $m_0 = \frac{M_0}{L}$?

2. what is stress? what is traction? what is the difference between stress in solid and stress in fluid? Find the stresses in the fluid:

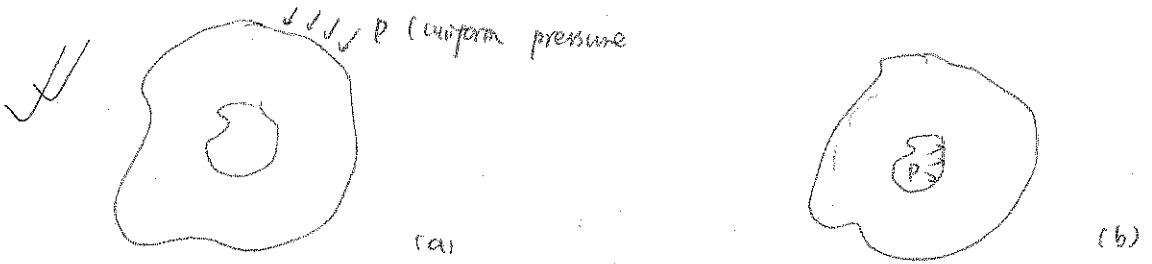


Solid Mechanics (Cont'd)

08/23/2002

$$\text{circle with } P \uparrow + \text{circle} = \text{circle} = \text{circle with } P \uparrow + \text{circle with } P \uparrow ?$$

2



- Give stresses in (a). Can you find stresses in (b)? (how many solutions?)
- What if the material is not homogeneous - isotropic?

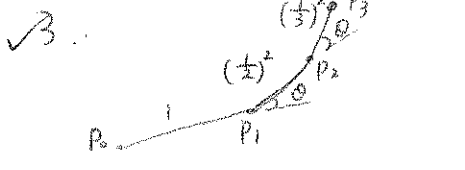
Math 1.

1. Conformal Mapping $\xi(z) = z + \frac{1}{z}$, where z is a circle with radius ρ .

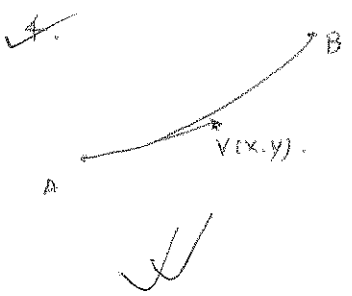
- Find $\xi(z)$ and draw it. What if $\rho=1$? $\rho \neq 1$?
- At which points $\xi(z)$ is not conformal?

2. Integral equation $h(t) = h_0 - a_0 \int_0^t \sqrt{h(\tau)} d\tau$ ($h_0, a_0 > 0$)

- Can you write down the D.E formulation?
- Draw a sketch of $h(t)$.
- Any numerical method to solve this problem?

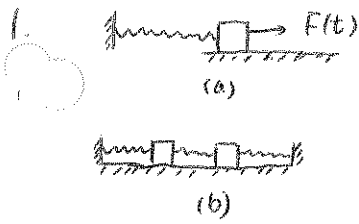


- Will P_n converge or not?
- If it converges, what's the limit?

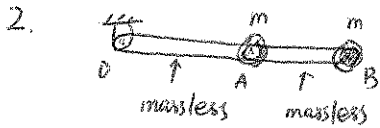


Given $v(x,y)$. Find out the path between A and B which minimize the time needed to travel from A to B.

Dynamics

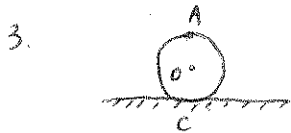


- ① Explain what is natural frequency? what is resonance?
- ② what is natural modes? where are the natural modes of (b)? what are the frequencies of the natural modes?



Double Pendulum, released from the current position. what are the accelerations of A and B?

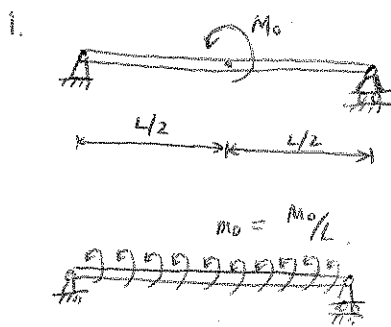
by



Given $\underline{v}_0, \underline{\omega}_0$.

- ① Find $\underline{v}_c, \underline{a}_c$?
- ② Find $\underline{v}_A, \underline{\omega}_A$?
- ③ If there is wind coming from right, all the masses concentrates in A. what are the forces acting on A? what is total force?

Solid Mechanics



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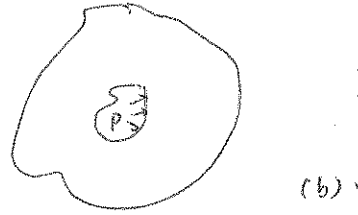
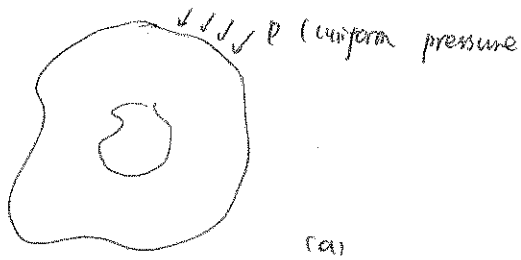
2. what is stress? what is traction? what is the difference between stress in solid and stress in fluid? Find the stresses in the fluid:





Solid Mechanics (Cont'd)

2



- ① Give stresses in (a). Can you find stresses in (b)? (how many solutions?)
- ② What if the material is not homogeneous, isotropic?

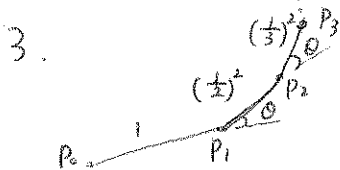
Math

1. Conformal Mapping $\xi(z) = z + \frac{1}{z}$, where z is a circle with radius ρ .

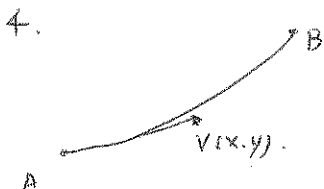
- ① Find $\xi(z)$ and draw it. What if $\rho=1$? $\rho \neq 1$?
- ② At which points $\xi(z)$ is not conformal?

2. Integral equation $h(t) = h_0 - a_0 \int_0^t \sqrt{h(\tau)} d\tau$ ($h_0, a_0 > 0$).

- ① Can you write down the D.E formulation?
- ② draw a sketch of $h(t)$.
- ③ Any numerical method to solve this problem?



- ① Will P_n converge or not?
- ② If it converges, what's the limit?



4. Given $v(x,y)$. Find out the path between A and B which minimize the time needed to travel from A to B.



Applied Math

8/24/01

(Rand)

✓ (5) State the Fredholm Alternative.

(1) $\sin A = A - \frac{A^3}{3!} \dots$

A is a matrix.

Given $A = \frac{\pi}{4} \begin{pmatrix} 7 & -3 \\ -3 & 10 \end{pmatrix}$

(Carlos Castillo-Chavez)

Find $\sin A$ in closed form.

(2) PDE. $\frac{\partial u(x,t)}{\partial x} = c \frac{\partial u(x,t)}{\partial t}$ ~~is~~ defined (Wang)

on $x \in [0, 1]$ given periodic boundary conditions

~~is~~ so that $u(x+1, t) = u(x, t)$, initial condition

$u(x, 0) = \sin 2\pi x$. Solve for $u(x, t)$.

What is the nature of the solution?

(3) Given $f(z) = u(x, y) + i v(x, y)$ is analytic (Wang)

Consider the level curves $u(x, y) = C_1$
 $v(x, y) = C_2$

Show that the level curves are orthogonal.

(4) $\frac{d\phi}{dt} + p(t)\phi = s(t)$ $p(t), s(t)$ given (Cady)

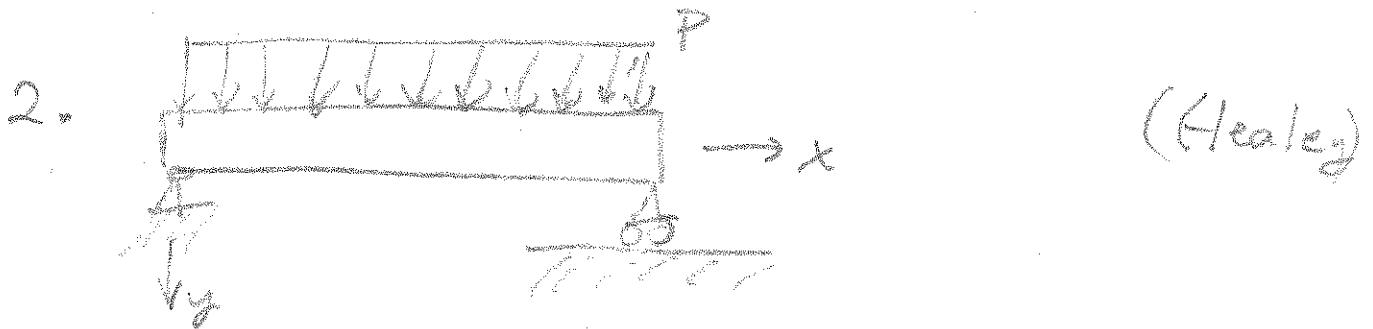
What else, if anything, is necessary to solve?

What is conserved?

Can you set this up as an integral eq?

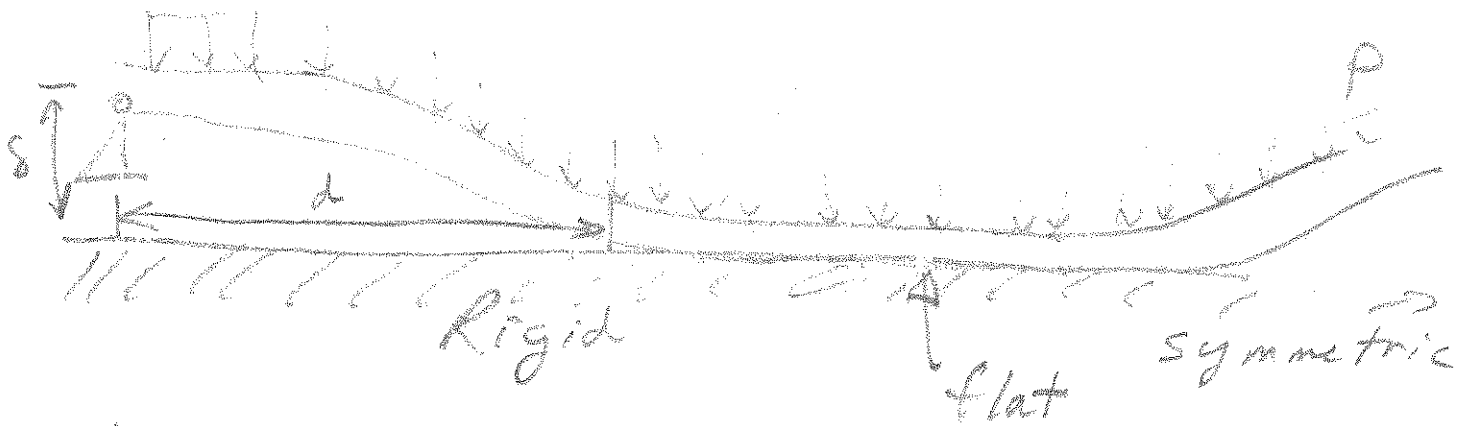
How to solve numerically?

1. What is stress? What is shear stress? what is normal stress?
Write stress/strain constitutive law for lin. elast. isotropic solid. Do the same for an incompressible fluid. How do you define strain for small displacements?



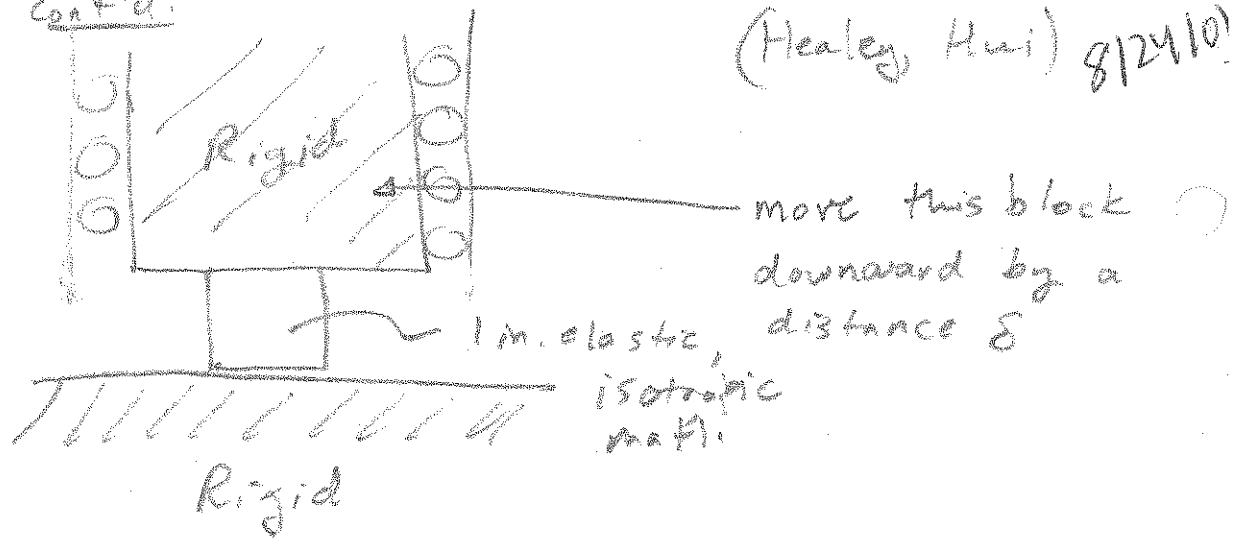
✓ Solve for $y(x)$.

Now also consider p large enough such that



Now state BC.'s such that we can solve the problem for $y(x)$ (and d).

3.



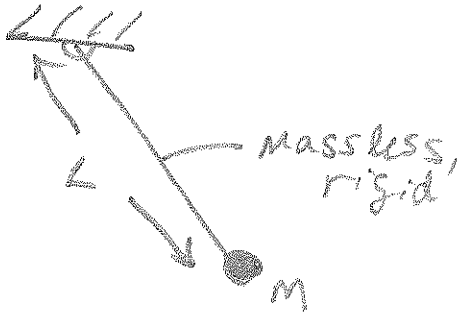
Set up everything you need to solve the problem
 (possibly stress-strain, strain-disp., equil, compatibility,
 boundary conditions)

- for two cases:
- i) top and bottom surfaces perfectly lubricated
 - ii) top and bottom surfaces glued

What will the deformed block look like in each case. What if $\nu = 0$?
 (Poisson ratio)

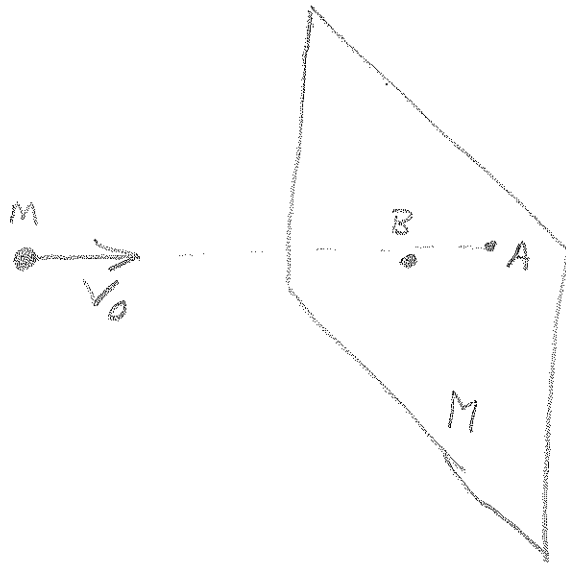
Dynamics

1. Derive eq(s) w/ Lagrange: (Burns)



Describe 2 other ways to derive eq(s) of motion.

2.

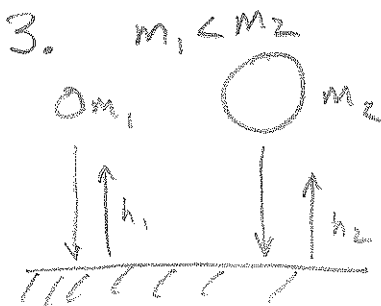


(Ruina)
Particle collides and sticks at A.

Is L conserved?
Is A conserved?
Is E conserved?

About what points?
for what systems? (particle, plate, or particle + plate)

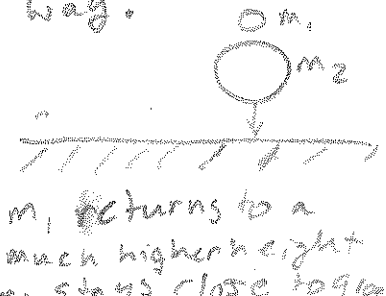
Setup the problem to solve for the subsequent motion.



When m_1 and m_2 bounce they return to heights h_1, h_2 respectively. (Approximately the same.)

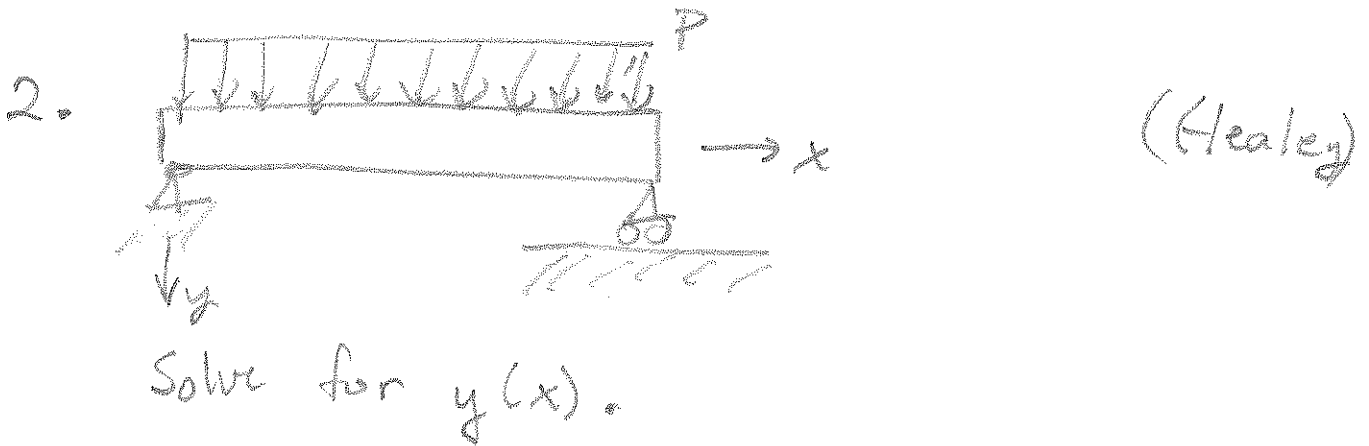
Explain \rightarrow

(Zehnder)
When dropped this way:

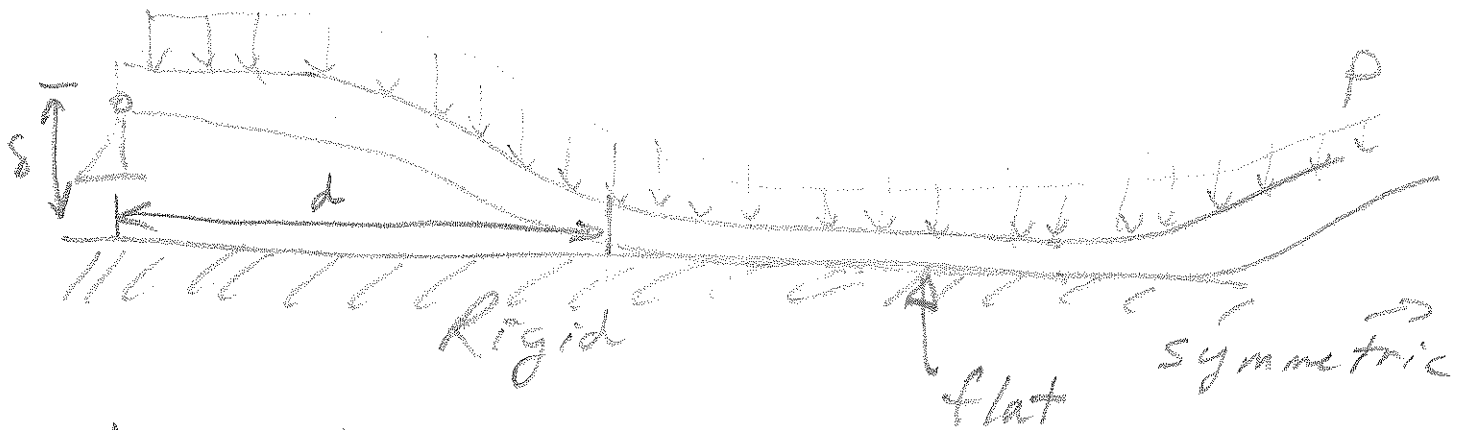




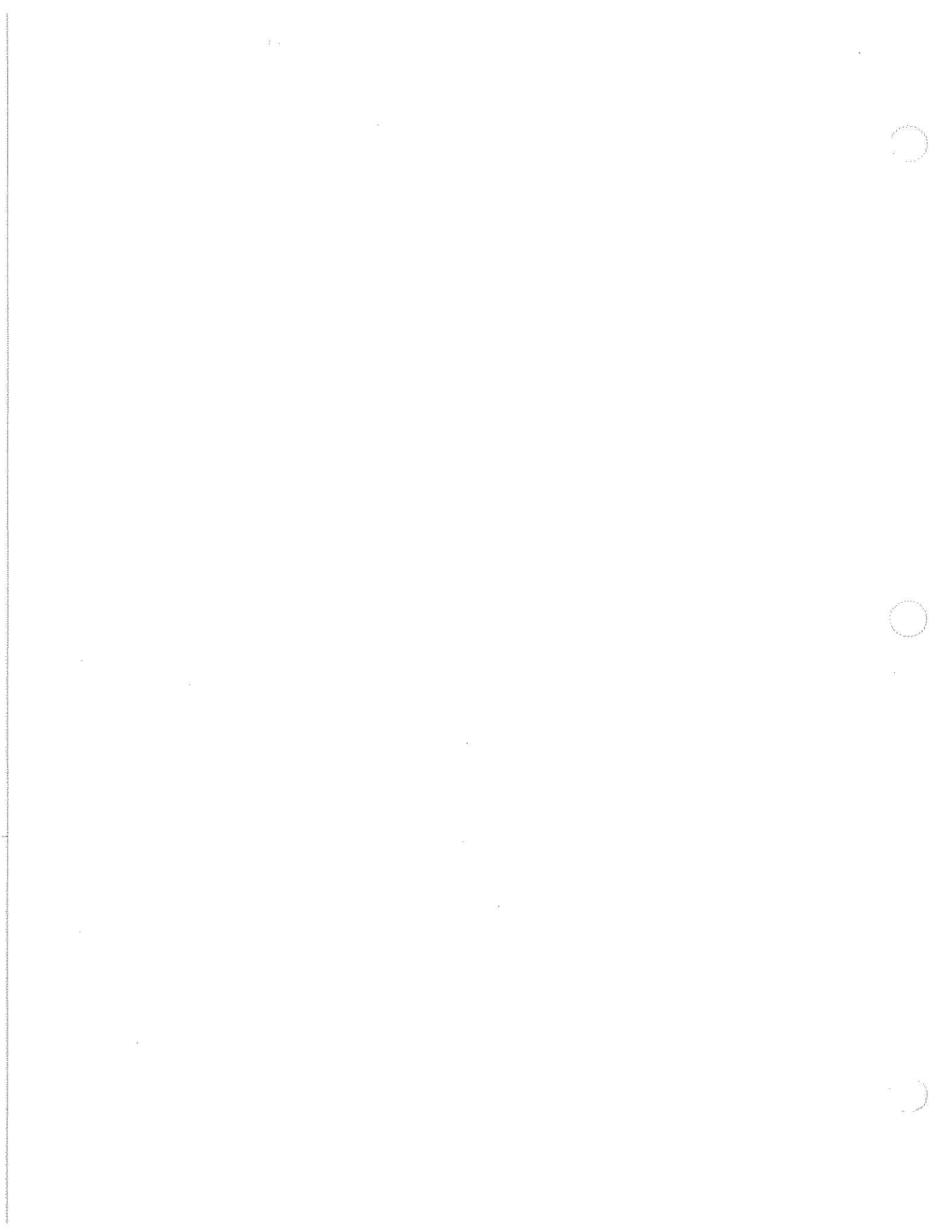
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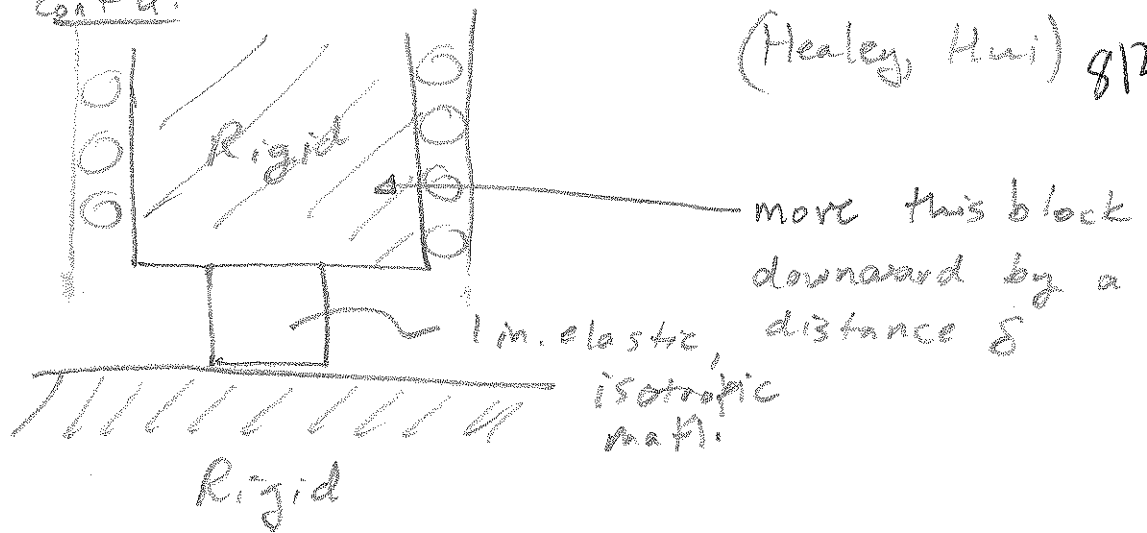
Now also consider p large enough such that



Now state BC.'s such that we can solve the problem for $y(x)$ (and d).



3.



Set up everything you need to solve the problem
 possibly
 (stress-strain, strain-disp., equil, compatibility,
 boundary conditions)

- for two cases:
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What will the deformed block look like in each case. What if $\nu = 0$?
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(1) $\sin A = A - \frac{A^3}{3!} \dots$ A is a matrix.

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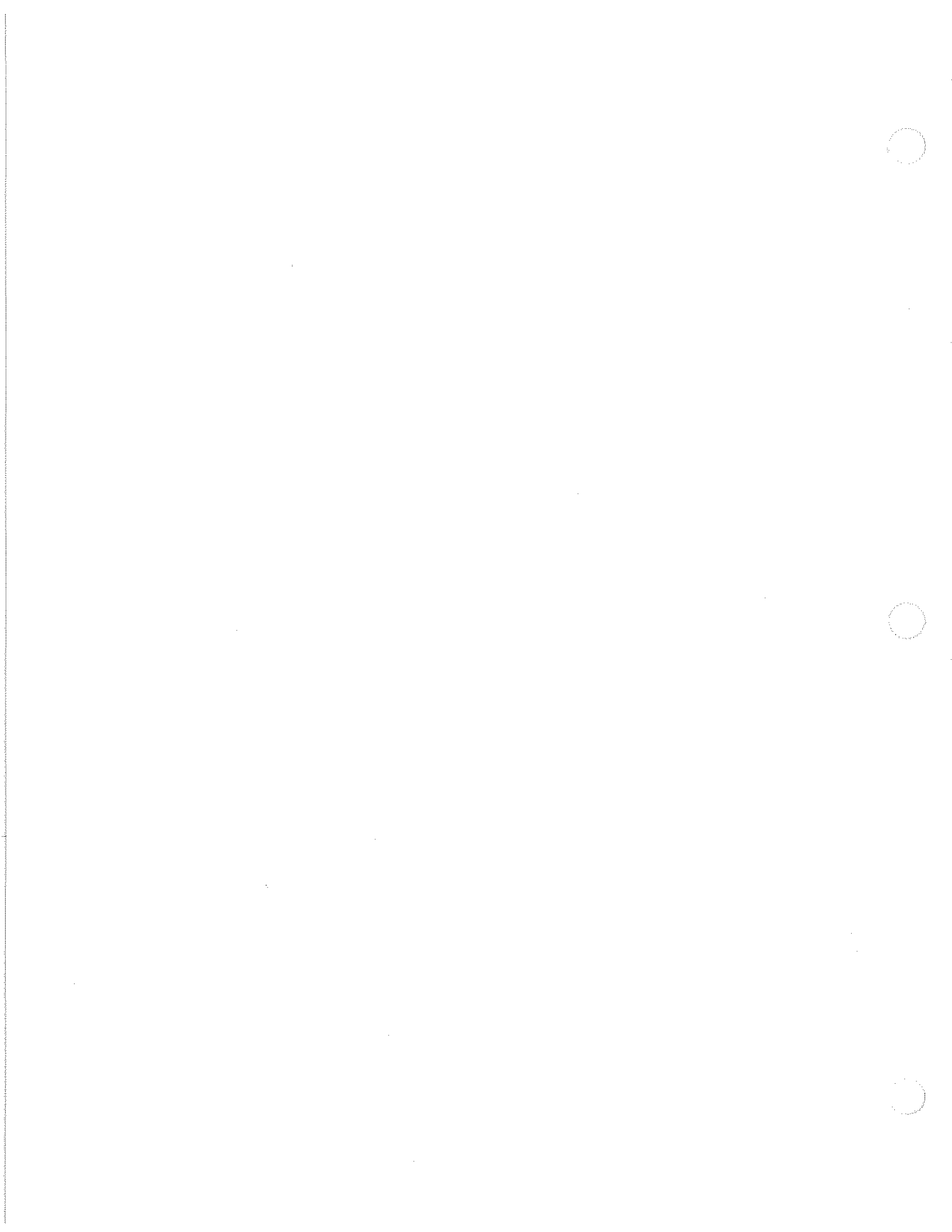
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How to solve numerically?



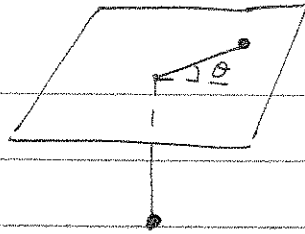
Applied Math

8/24/01

(Rand)

(5) State the Fredholm Alternative.

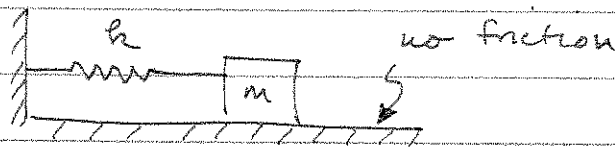




Problem 1.

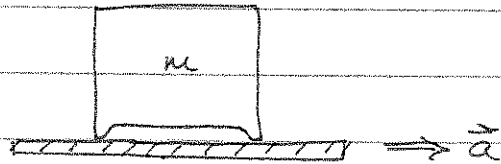
- How many degrees of freedom?
- Are there any conserved quantities?
- Find the equations of motion.

Problem 2.



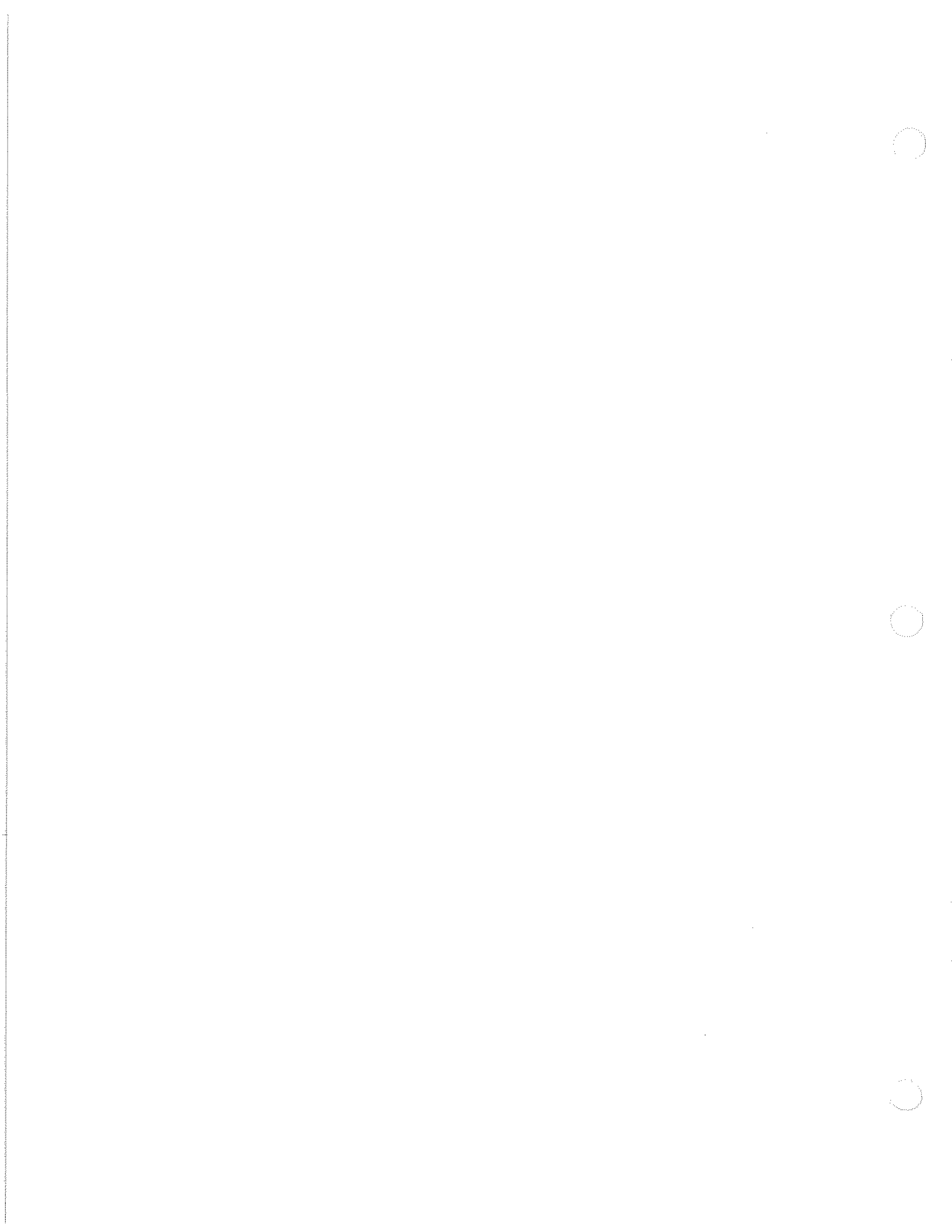
- What is the natural frequency?
- Now, suppose the spring has mass M , what is the new natural frequency?
- Some other stupid questions...

Problem 3.

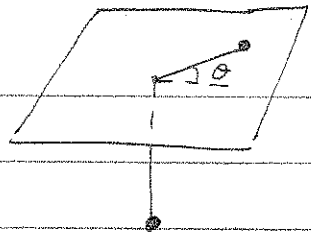


Floor has constant acceleration \vec{a} , block is at rest at $t=0$

- What happens?

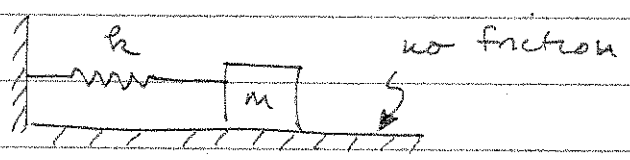


Problem 1



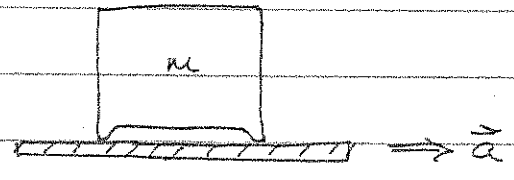
- a) How many degrees of freedom?
- b) Are there any conserved quantities?
- c) Find the equations of motion.

Problem 2



- a) What is the natural frequency?
- b) Now, suppose the spring has mass M , what is the new natural frequency?
- c) Some other stupid questions...

Problem 3



floor has constant acceleration \vec{a} , block is at rest at $t=0$

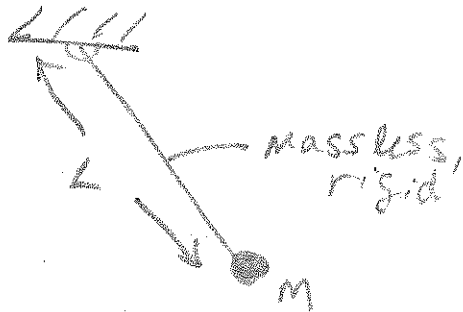
- a) What happens?

Dynamics

8124101

1. Derive eq(s) w/ Lagrange:

(Burns)

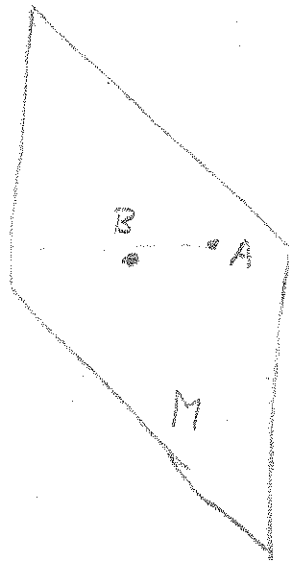


Describe 2 other ways to derive eq(s) of motion.

2.

(Rhina)

Particle collides and sticks at A.



Is L conserved?

Is A conserved?

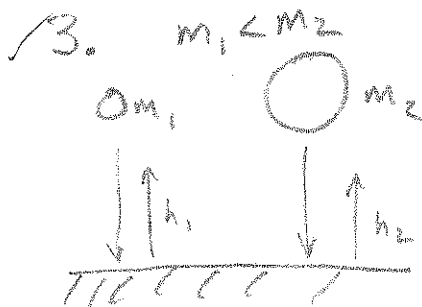
Is E conserved?

About what points?
for what systems? (particle, plate, or particle + plate)



Setup the problem to solve for the subsequent motion.

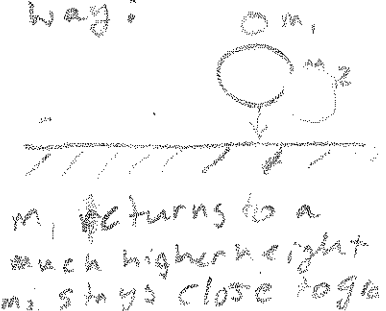
(Zehnder)



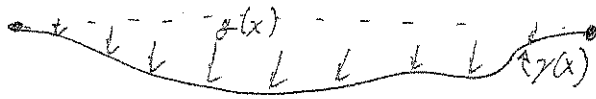
When m_1 and m_2 bounce they return to heights h_1, h_2 respectively. (Approximately the same.)

Explain \rightarrow

When dropped this way:



1) $\frac{dy}{dx^2} = g(x)$ on $0 \leq x \leq 1$ $y(0) = y(1) = 0$



- What can you say about the existence of a solution?
- Now suppose the boundary conditions did not exist, when does a solution exist?
- How do these restrictions on $g(x)$ relate to mechanics?

- 2) Given square matrix \underline{A} and \underline{B} both have distinct (but not equal) eigenvalues and they share the same eigenvasis.
- Show $\underline{A}\underline{B} = \underline{B}\underline{A}$
 - Show that $\underline{A}\underline{B} = \underline{B}\underline{A}$ implies statements above.

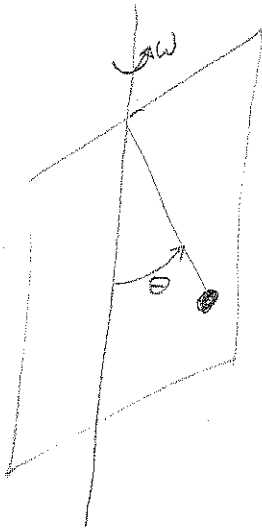
3) Heat diffusion in a ring
 $u_{xx} = \alpha u_t$ $T(\theta, 0) = \sin(2\theta)$
 At what time is $\max_{\theta} |T(\theta, t)| - \min_{\theta} |T(\theta, t)| = \frac{1}{2}$?

4) Given $I = \int_0^1 [(\psi')^2 - 1]^2 + \psi^2 dx$ $y(0) = y(1) = 0$

- Find Euler equation for this functional
- Does this minimize I ? Maximize I ?
- Can you find a $y(x)$ that gives an I less than your first solution?
 Hint: C^1 continuous...



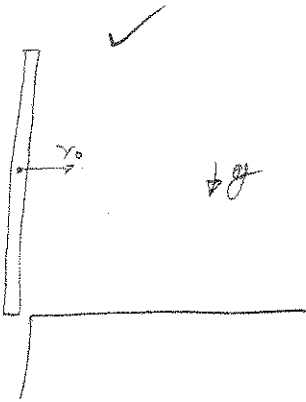
1



PENDULUM CONFINED TO A PLANE
ROTATING AT ANGULAR VELOCITY ω .

FIND EQUATIONS OF MOTION USING LAGRANGE.

2



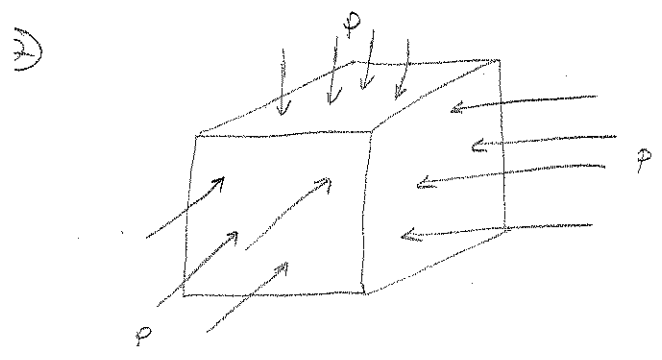
A THIN ROD MOVING HORIZONTALLY WITH
VELOCITY v_0 BARELY STRIKES A TABLE
IN AN INELASTIC COLLISION - THEN
ROTATES ABOUT THE IMPACT POINT
UNDER INFLUENCE OF GRAVITY.

WHAT IS THE FINAL MOTION OF THE ROD?

3

✓ WRITE OUT EQUATIONS OF MOTION FOR A
RIGID BODY ROTATING ABOUT ITS
CENTRE OF MASS.

- ①
- a) WHAT IS THE DIFFERENCE BETWEEN A SOLID AND A LIQUID?
 - b) WRITE DOWN A CONSTITUTIVE MODEL FOR A SOLID.
 - c) WRITE DOWN A CONSTITUTIVE MODEL FOR A LIQUID (STATIC),
 - d) WRITE DOWN A CONSTITUTIVE MODEL FOR A LIQUID (DYNAMIC).
 - e) WRITE DOWN THE MOST GENERAL CONSTITUTIVE MODEL YOU CAN THINK OF.



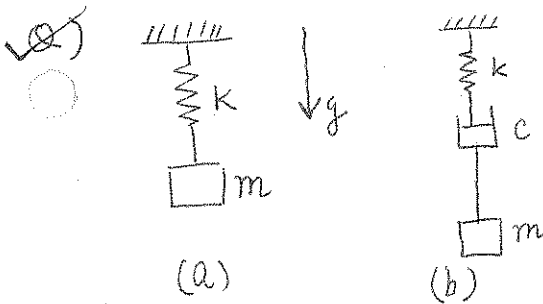
SAME PRESSURE ON
ALL SIX SIDES OF CUBE
3D ELASTICITY

- a) FIND THE DISPLACEMENT FIELD
- b) IS THE ANSWER UNIQUE?
- c) WHAT ASSUMPTIONS DID YOU MAKE IN ADDITION TO 3D ELASTICITY?
- d) IS THE ANSWER THE SAME IF THE BODY HAD A DIFFERENT SHAPE?
- e) WHAT IF THERE WAS A HOLE IN IT?
- f) SUPPOSE THERE ARE TWO MATERIALS - ONE INSIDE THE OTHER - CAN YOU COME UP WITH A RESTRICTION ON E, ν SUCH THAT THE DISPLACEMENT FIELD REMAINS THE SAME?
- g) HOW WOULD YOU GET RID OF THE NON-UNIQUE TERMS IN THE DISPLACEMENT FIELD TO SOLVE IT ON THE COMPUTER?

DYNAMICS

Q Summer '0

Manish
Brian ~~Bryan~~
Joshua



(a) Find the equⁿ of motion of the mass

for 1) $kx = F$ and

2) $F = kx(1-x)$

compare the two situations will 2) be a periodic motion

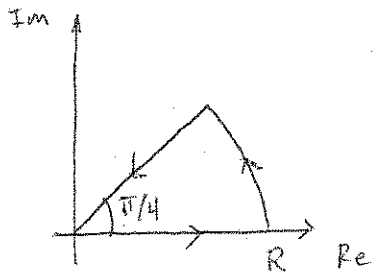
(b) what effect does the damper have on the motion of m . derive the equation

Q) ✓ A stone is dropped from the top of empire state bld. ($h = 1250$ ft) find the distance it falls away from the base (due to rotation of earth)

Ans 4"

Q) derive the equⁿ of motion for a rocket with initial mass m_0 , emission rate $= v$ (constant) and the discharge has relative velocity u w^ot rocket.

1) Use e^{ix^2} and contour in fig. A to evaluate $\int_0^{\infty} \cos(x^2) dx$



$$\int_0^{\infty} \sin(x^2) dx$$

2)
$$\frac{x^{100}}{(x-1)(x-2)\dots(x-101)} = \frac{A_1}{x-1} + \frac{A_2}{x-2} + \dots + \frac{A_{101}}{x-101}$$

Find A_n

3) $L(A) = A + A^T$ A is $n \times n$ real matrix

a) find eigenvalues of L

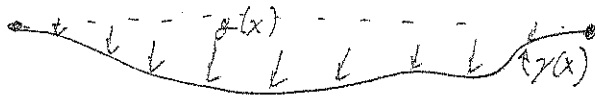
4) a) Find Taylor's expansion of $f(x)$ about $x=a$

b) give t. expansion of two functions (say $\sin x, e^x$)

c) $f_{b^+}(x) - f_{b^-}(x) = h$ $b \in [a, c]$

find expansion of f about a .

3) $\frac{d^2 y}{dx^2} = g(x)$ on $0 \leq x \leq 1$ $y(0) = y(1) = 0$



- WHAT CAN YOU SAY ABOUT THE EXISTENCE OF A SOLUTION?
- NOW SUPPOSE THE BOUNDARY CONDITIONS DID NOT EXIST, WHEN DOES A SOLUTION EXIST?
- HOW DO THESE RESTRICTIONS ON $g(x)$ RELATE TO MECHANICS?

4) GIVEN SQUARE MATRIX \underline{A} AND \underline{B}
BOTH HAVE DISTINCT (BUT NOT EQUAL) EIGENVALUES
AND THEY SHARE THE SAME EIGENBASIS.

a) SHOW $\underline{AB} = \underline{BA}$

b) SHOW THAT $\underline{AB} = \underline{BA}$ IMPLIES STATEMENTS ABOVE.

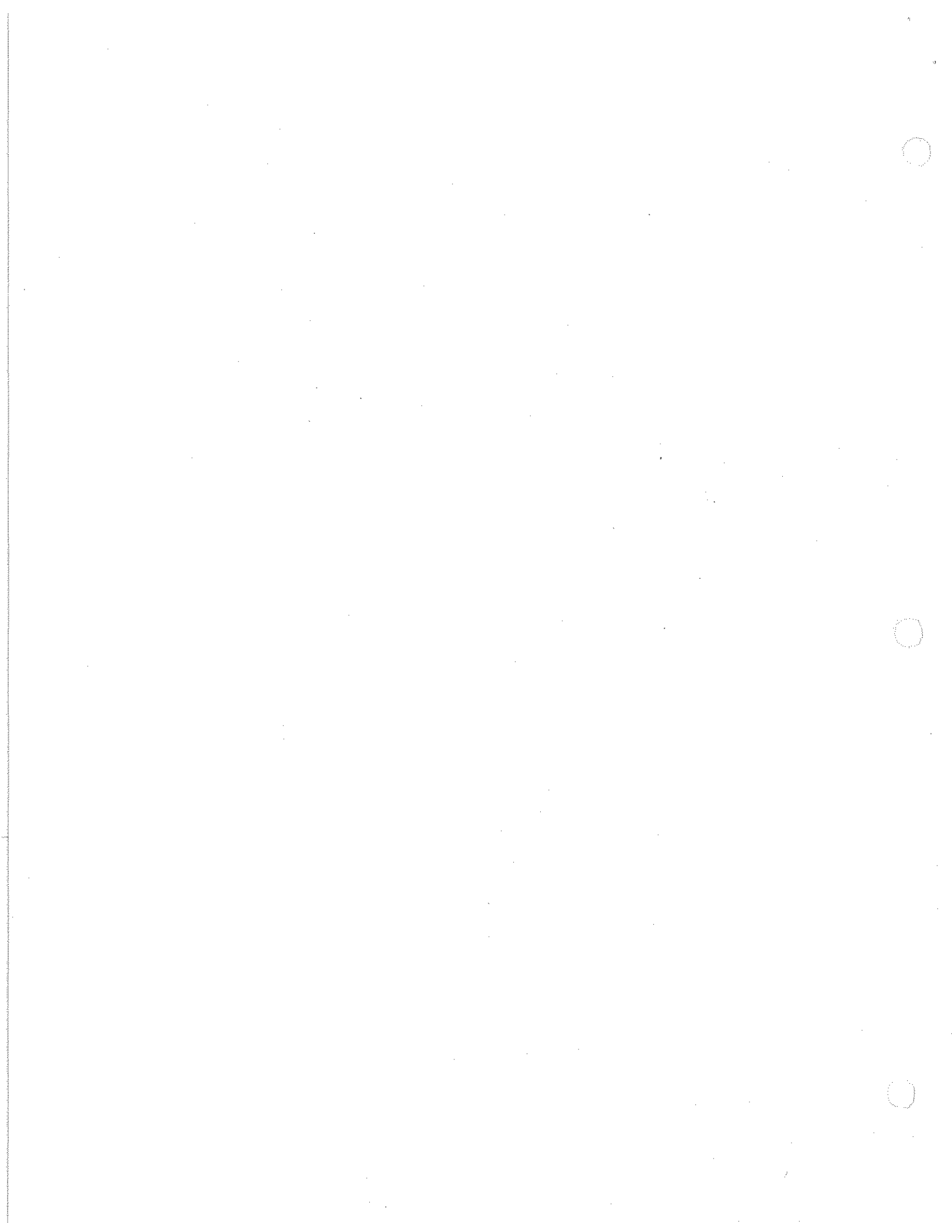
5) HEAT DIFFUSION IN A RING

$u_{xx} = \alpha u_t$ $T(\theta, 0) = \sin(2\theta)$

AT WHAT TIME IS $\max_{\theta} |T(\theta, t)| - \min_{\theta} |T(\theta, t)| = \frac{1}{2}$?

6) GIVEN $I = \int_0^1 [(y')^2 - 1]^2 + y^2 dx$ $y(0) = y(1) = 0$

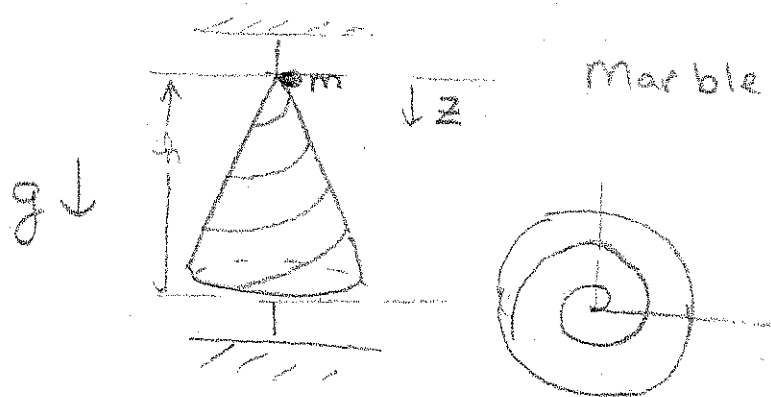
- FIND EULER EQUATION FOR THIS FUNCTIONAL
- DOES THIS MINIMIZE I ? MAXIMIZE I ?
- CAN YOU FIND A $y(x)$ THAT GIVES AN I LESS THAN YOUR FIRST SOLUTION?
HINT: C^1 CONTINUOUS...



DYNAMICS

January, 2000

①



Marble mass m

$$r = z = 0$$

marble travels through a frictionless tube

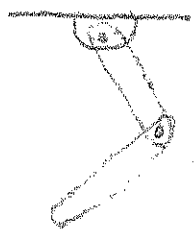
a) find velocity when marble reaches bottom of cone

b) the cone can spin do (a) again

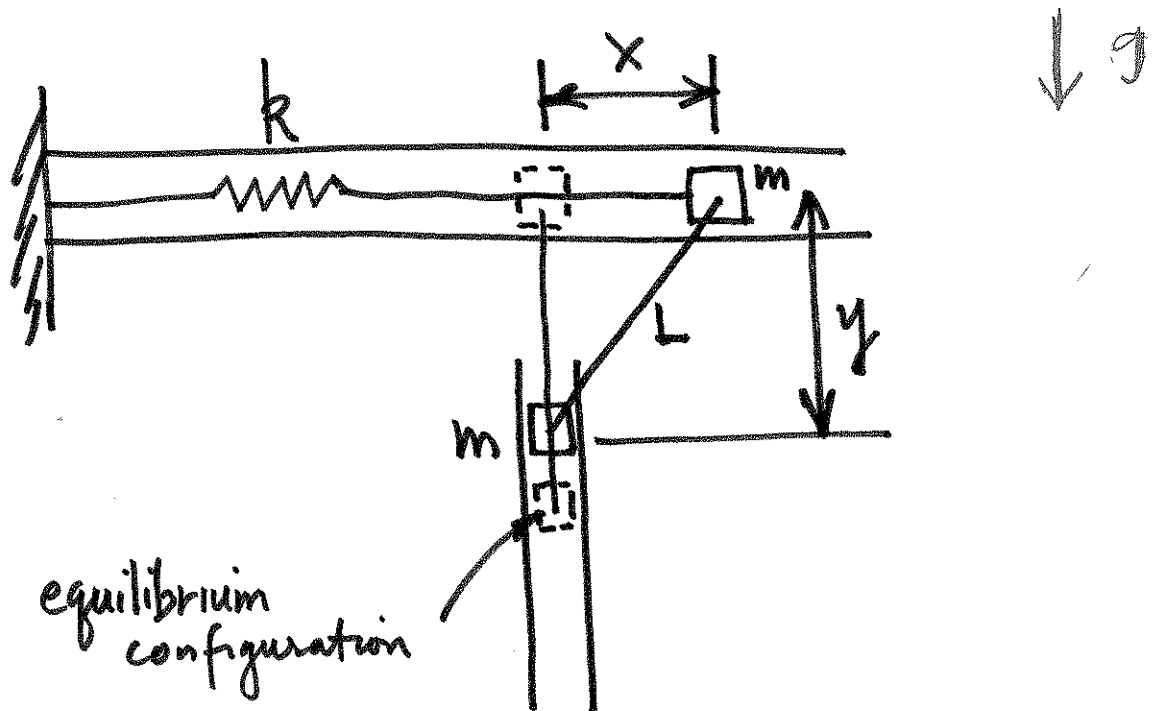
②

double pendulum

derive equations of motion







Derive the equation of motion.

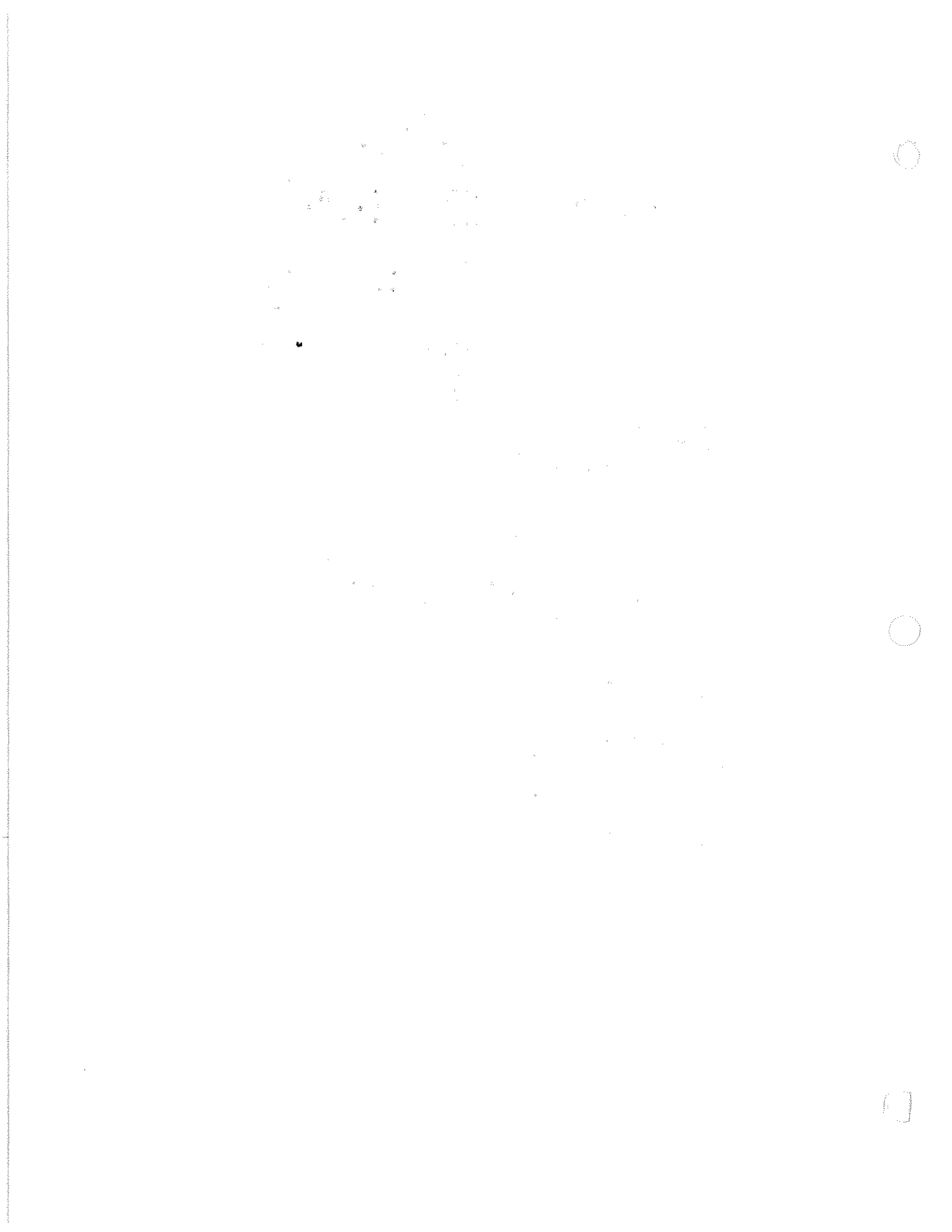
Assumptions

$L =$ rigid rod

neglect friction

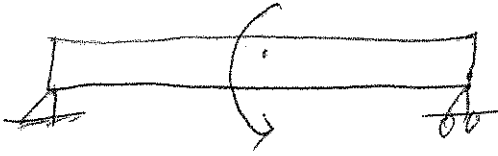
include gravity

Use any method you like.



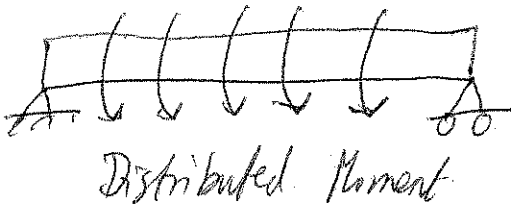
SOLID MECHANICS

1) a)



Shear & Moment Diagram.

b)

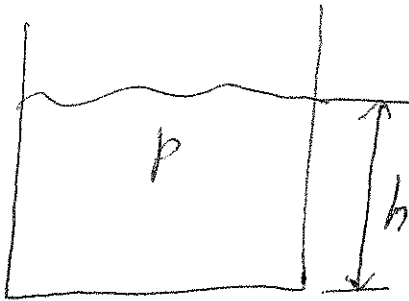


Distributed Moment

2. a) What is Stress (Traction etc.)

b) Compare stress state in a fluid vs. Solid

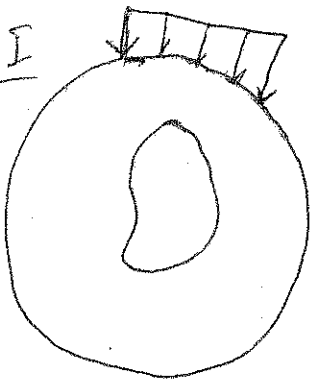
c)



Find stress tensor at every point.

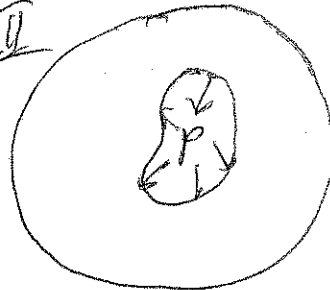
3)

Prob I



p constant

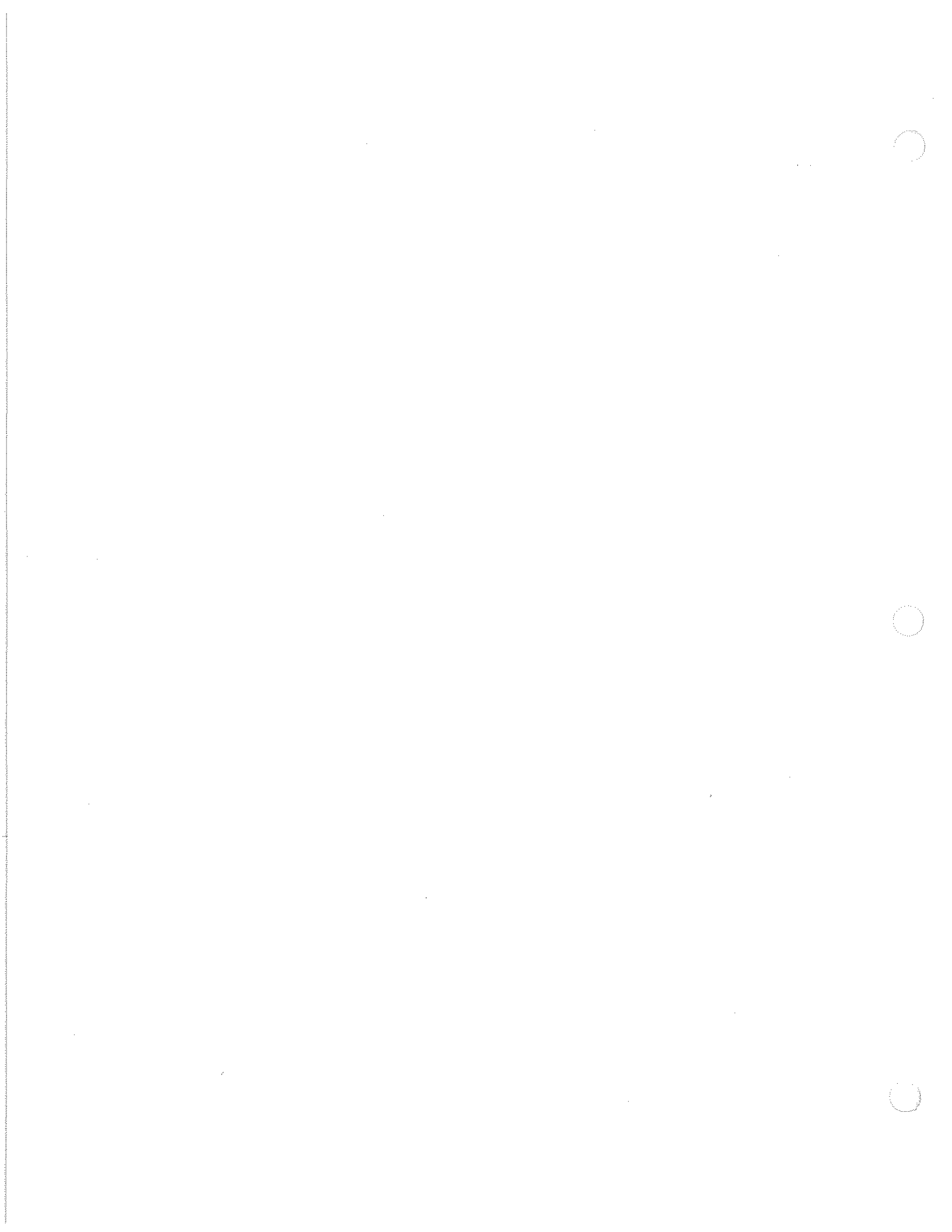
Prob II

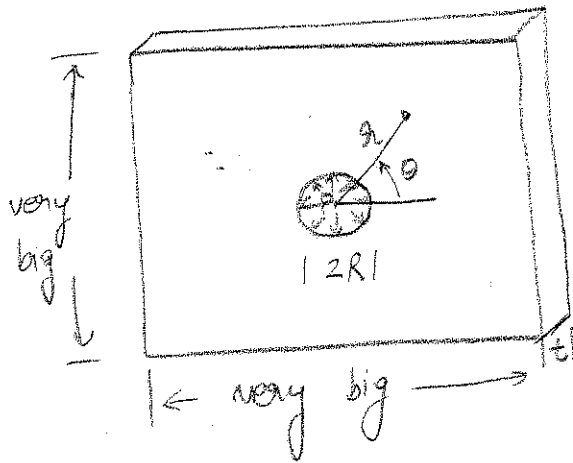


1. Number of solutions for Problem I

2. I known, find soln. to II

3. What happens if matl. is inhomogeneous?

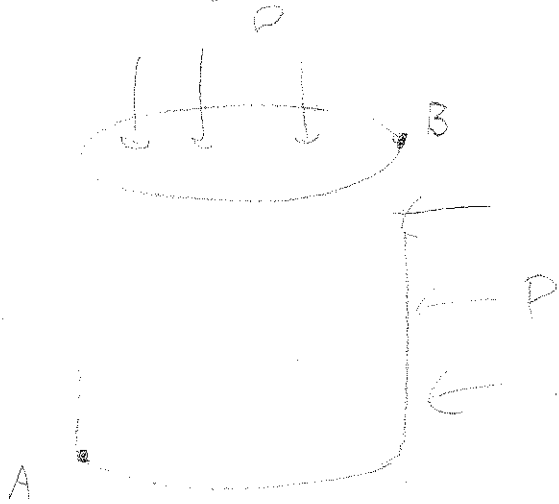




Pressure ' p ' in hole with
radius ' R ' in a thin
linear-isotropic elastic plate

Q-EXAM - AUG. 20, 1999

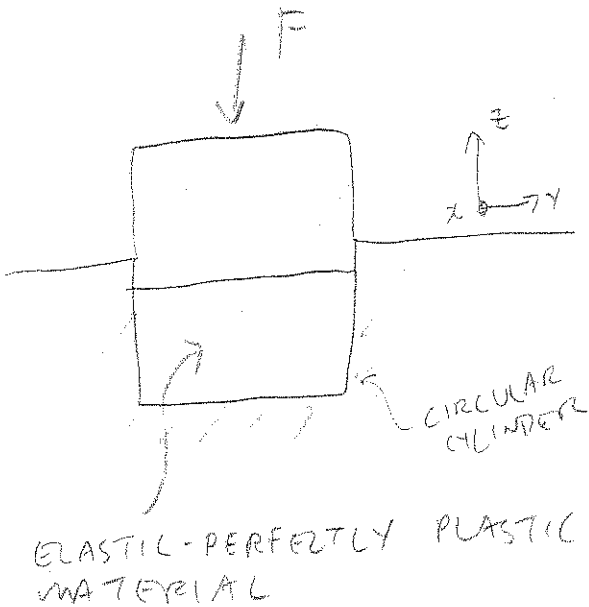
SOL 75 (RUINA-MODERATOR, JENKINS, ZEHNDER, BAKER)
CONWAY



SOLID CYLINDER
UNDER UNIFORM
PRESSURE P.

FIND CHANGE (IN LENGTH)
BETWEEN ~~AA~~
POINTS A & B.

2)



a) MAKE A PLOT OF σ_{zz} VS ?

SOMETHING ABOUT TRESCA'S
YIELD CRITERION

c) WE DIDN'T GET VERY
FAR ON THIS

3) SHOW
$$\oint_{\Gamma} (w_{,j} - t_{ij} u_{ij}) d\Gamma = 0$$

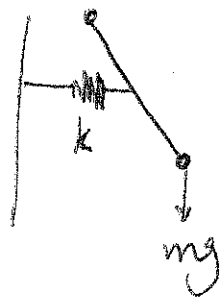
FOR ANY CLOSED CURVE Γ IN x, y PLANE

W = strain energy

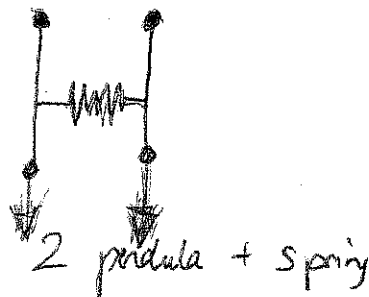
Jan 98.

Dynamics:

(1)



spring + pendulum.



2 pendula + spring

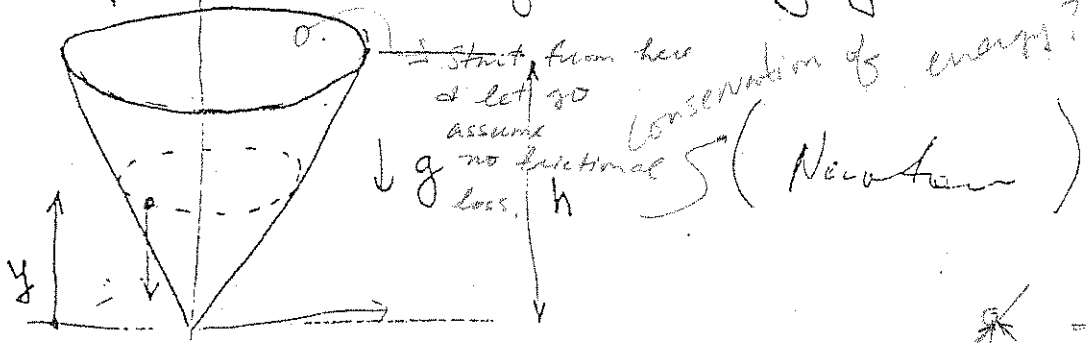
(2) $\dot{x} = x^2 - xy$?
 $\dot{y} = xy + y^2$?

DISCUSS - if linearize, stability, phase plane diagram integrable?

(3) pure elastic collision of 2 balls (no gravity)

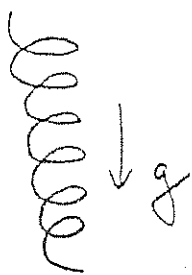
Use conservation of momentum or ... ?

- 9) A particle travels in a circular path on the inside of a cone. Find its speed v as a function of θ .



1

- 10) A particle travels along a helical spring, until it reaches the end of the spring and falls off. What is its trajectory?



$$\begin{aligned}
 \vec{r} &= \rho \cos t \hat{i} + \rho \sin t \hat{j} + at \hat{k} \\
 \dot{\vec{r}} &= -\rho \sin t \hat{i} + \rho \cos t \hat{j} + a \hat{k} \\
 \ddot{\vec{r}} &= -\rho \cos t \hat{i} - \rho \sin t \hat{j} \\
 \Rightarrow \vec{F} &= -\rho (\cos t \hat{i} + \sin t \hat{j}) \\
 \vec{F} &= -\rho (\cos t \hat{i} + \sin t \hat{j}) - g \hat{k} \\
 &= -\rho \cos t \hat{i} - \rho \sin t \hat{j} - g \hat{k} \text{ constant}
 \end{aligned}$$

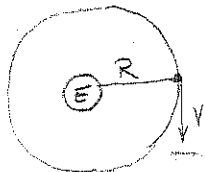
1

1

- 11) a) State Newton's 3 laws.
 b) D'Alembert's Principle (Notes)
 1st law = particle at rest remain at rest unless acted upon by external forces.
 2nd law = change in \vec{p} particle when acted upon by external force is $F = \frac{d\vec{p}}{dt}$
 3rd law = equal & opposite forces.
 D'Alembert's principle = reaction forces or force of constraints does no work under virtual displ.

- 12) Find the altitude of a geosynchronous orbit.

2

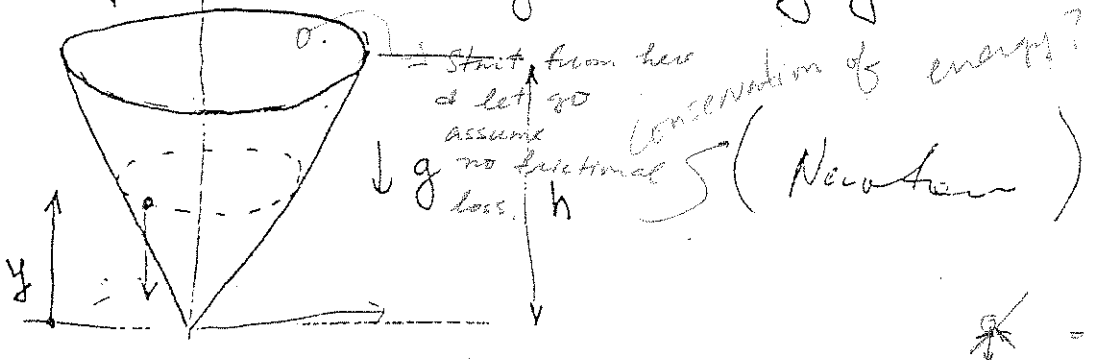


geosynchronous

$$\frac{mv^2}{R} = G \frac{mM_e}{R^2} \quad R\dot{\theta} = v \quad \dot{\theta} \Delta t = 360 \text{ sideral da}$$

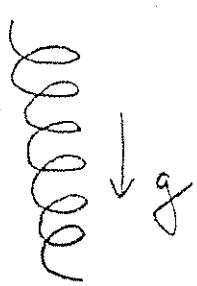
Note: Geosynchronous orbit is a circular orbit that completes one full revolution about the earth in one sideral day.

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$$\vec{a} = -\phi \cos t \hat{i} - \phi \sin t \hat{j}$$

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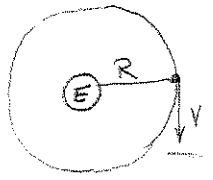
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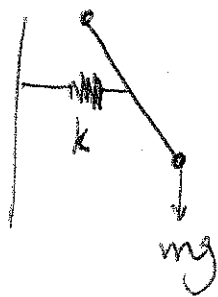
1

2

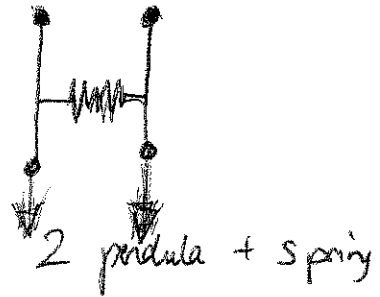
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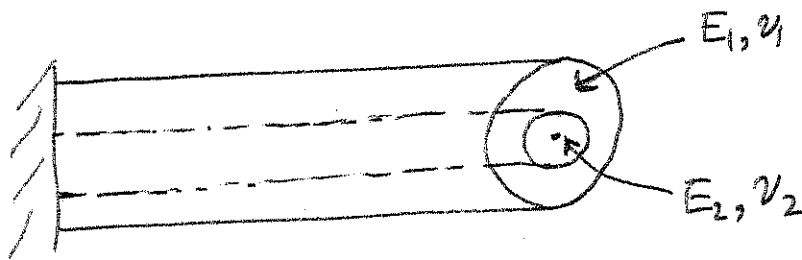
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What about a material like wood?

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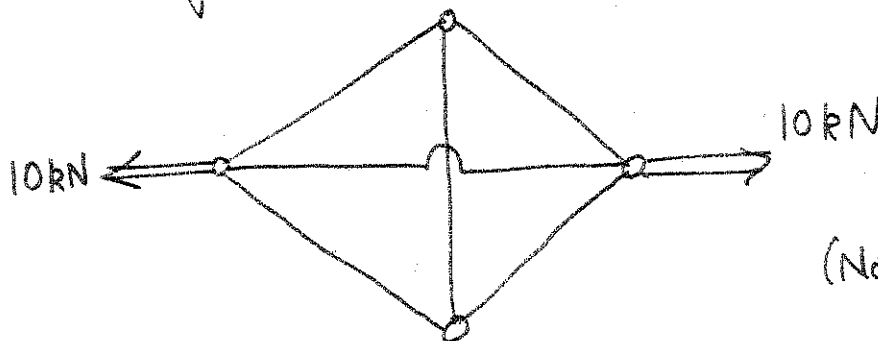
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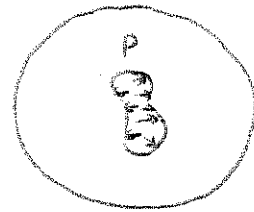
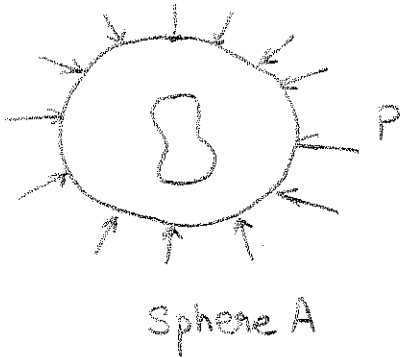


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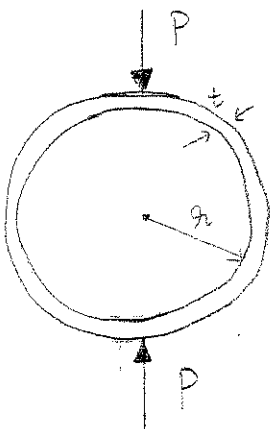
27



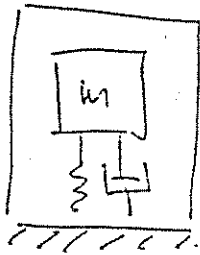
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37



Set up the free body diagram for a ring loaded by identical forces P . Use body symmetries to eliminate certain terms. What are the required boundary conditions?



53

Puls hammer? Discus!
 How to measure the force?
 Equation of the mechanism inside
 the hammer?

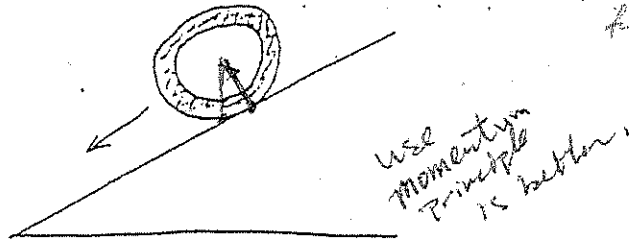
2

54

What is constraint? Limitation placed on
 the degrees of freedom
 a system can have.
 Usually, it has the form of
 an equation relating the different
 degrees of freedom. Hence reducing
 the # of independent degrees of
 freedom.

1

55

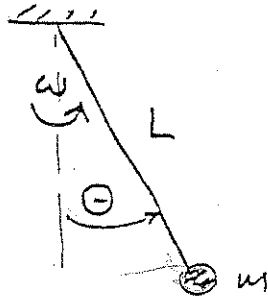


1

- a) Solve the problem:
- (i) with slippage
 - (ii) without slippage

- b) What are restrictions on $\vec{T} = \frac{d\vec{L}}{dt}$
 fixed pt in space or CM.
- c) Where is the above equation derived
 from? $\vec{F} = m\vec{a}$

50. Spherical pendulum ($\dot{\theta} = 0$)
 Given an I.C. on ψ , find the period.
 If the mass is given a slight disturbance
 ($\dot{\theta}$ no longer = 0), find the period!

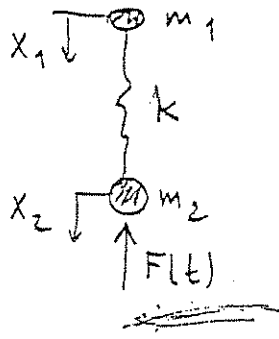


1

$$T = \sqrt{\frac{g}{R}} 2\pi$$

$$EOM: \ddot{\theta} + \frac{g}{R} \sin\theta \cos\theta = 0$$

51



Set up eqs of motion.
 Given $(\dot{x}_1 - \dot{x}_2)$ how would you find $F(t)$?

1

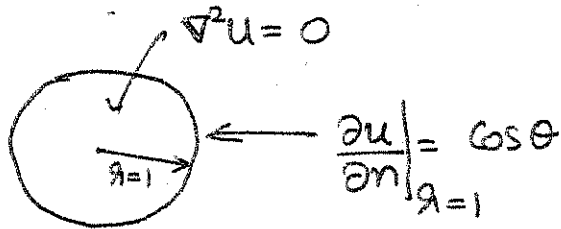
$$\left. \begin{aligned} m_1 \ddot{x}_1 - k(x_2 - x_1) &= 0 \\ m_2 \ddot{x}_2 + k(x_2 - x_1) &= F(t) \end{aligned} \right\}$$

52

What is the difference between LE and NE's?

1

1) (Andy Ruina) Laplace's Equation on a unit disk. 19th Jan '96



What is

$u(r, \theta)$ or $u(x, y) = ?$

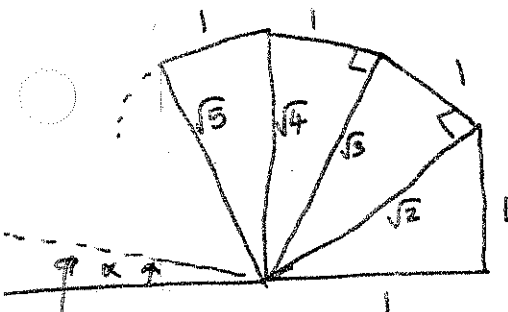
2) (Hui) Solve the following equation:

$$\frac{dy}{dx} = \int_0^x y(t) dt$$

$y(0) = 1$

What is $y(x) = ?$

3) (Strogatz)



Does this converge?

1) 17) What is Euler's constant, γ ?

Show $\lim_{n \rightarrow \infty} \left[1 + \frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{n} - \log(n) \right]$ converges. give a

bound on this limit.

2) How do you solve the Cauchy-Euler equation.

$$x^2 y'' + xy' - y = 0?$$

How do you solve the in-homogeneous case:

$$x^2 y'' + xy' - y = f(x)?$$

3) What is $\text{curl}(f \underline{a})$? $f: \mathbb{R}^3 \rightarrow \mathbb{R}$

4) State Residue Theorem.

5) Define the derivative of a complex function.

6) Give a brief lecture on Fourier Series.

7) What can you say about the following:

$$L(u) + \alpha u = 0$$

$$u(0) = u_0$$

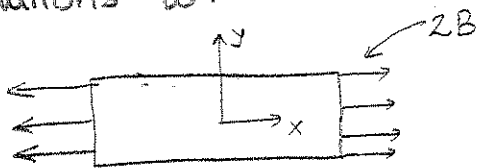
$$u(a) = u_1$$

'L' is a linear operator.

8) Evaluate: $\int_C \frac{dz}{z^{2n} + 1}$ where C is: $|z| = 3$

137 Derivation of the governing equations:

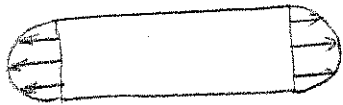
a) solutions to:



$$\phi = By^2$$

$$\sigma_x = \frac{\partial^2 \phi}{\partial y^2} = 2B$$

b) Solution to:



$$\phi = S \left(\frac{y^2}{2} - \frac{y^4}{12b^2} \right) + \dots$$

↑ need additional terms. So, that $\nabla^2 \nabla^2 \phi = 0$ is satisfied.

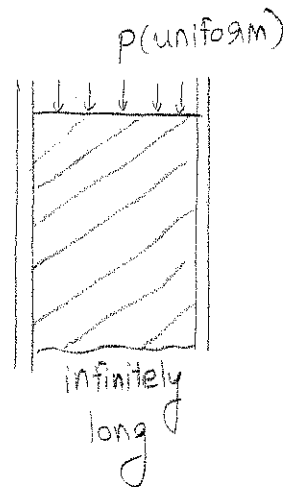
$$\sigma_x = S \left(1 - \frac{y^2}{b^2} \right)$$

147 Given a tube of paper which is then subjected to torsion. At what angle will the paper buckle & why?

157 Find the stress?

a) No friction on the walls?

b) Now with friction. state the shearing stress distribution on the walls.



167 Why does buckling not come under the classical theory of Elasticity? — (Ans.: by the assumption of smallness).

177 What are compatibility equations? What do they mean?

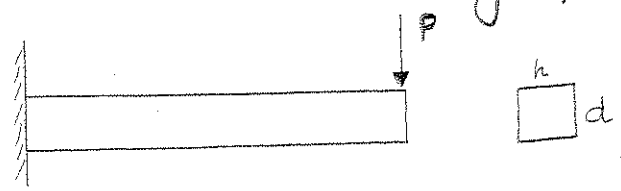
187 Given the displacement field $w = f(x, y)$? $u = v = 0$.

What are the governing equations.

Which of ϵ ; γ are zero!

How do you measure E & G experimentally?

19> Consider the following problem:



a> Draw the shape of the transverse cross-section of the beam after it has been loaded.

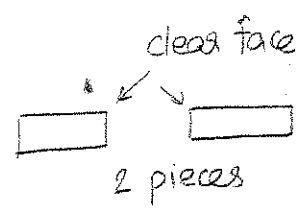
b> What assumptions are being made? In which region of the beam is the kinematic constraint approximation of beam theory good. Are there regions where the cross-section warps?

c> What is the relation between the anti-elastic radius of curvature & the bending radius of curvature? Is there a value of ν (Poisson's ratio that immediately tells you what the relation should be?)

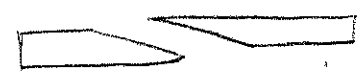
20> A piece of chalk (a brittle material) fails when subjected to loading:



=>



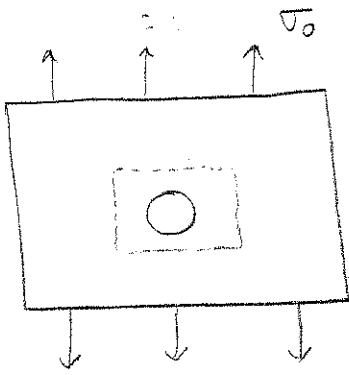
=>



Failure criterion: Max. normal stress.

Explain different failure modes.

Consider a circular hole in a large plate subjected to tensile loads.



a) How would you formulate the problem as a problem in linear elasticity?

b) Wants to know if one uses stress function to solve it.

c) What are the B.C.'s?

d) Is the solution for the displacement unique?

e) How would you use this solution to check the accuracy of a code that solves the problem of a large hole

in a plate (dotted rectangle)?

f) Is this solution good if the radius of the hole is of the order of the thickness of the plate?

2) The well known formula for beam stress is:

$$\sigma = -\frac{My}{I} \quad *$$

a) Very briefly describe the meaning of this equation.

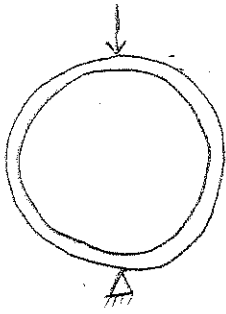
b) What are the conditions under which * is accurate?

What materials?

What shapes?

What loads?

the stress distribution on the surface of cut.



24) Define ν .

How could you measure ν . More than one way if you can think of them?

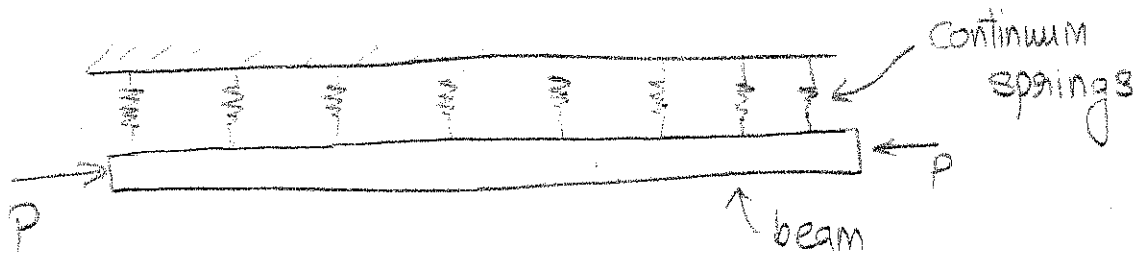
What are the biggest & smallest values of ν ? and why?

What are the biggest & smallest values of ν for materials you know about?

When $\nu = 0.5$ a material is "incompressible." How would you describe a material with $\nu = -1$?

25) Beam on an elastic foundation:

$$P_{\text{buckle}} = ?$$



Ench + Deepak's Q exam! 1996. August.

Q Applied Math! Convey Eule eqn

$$1) x^2 y'' + xy' + ay = 0$$

$$x'(0) = 0$$

$$x'(1) = 0$$

$$\text{(sub } y = x^k)$$

- discuss solution for various values of A - unique?)

✓ A linear symmetric pd. $A: \mathbb{R}^n \rightarrow \mathbb{R}^n$.

Use Eule decomposition of A

$\langle v, w \rangle =$ inner product

$$\min \langle Av, v \rangle \quad \text{subject to } \langle v, v \rangle = 1$$

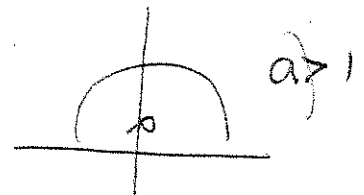
2.3) $\int_{-\infty}^{\infty} \frac{a^{iz}}{z^2+1} dz \quad a \in \mathbb{R} \quad 1 > a > 0.$

Use Jordan's lemma

$$= \int_{-\infty}^{\infty} \frac{e^{i \ln a z}}{z^2+1} dz$$

$$\int_{\mathbb{C}^+} \rightarrow 0 \quad \text{as } R \rightarrow \infty$$

(Hint: Consider different contours?)



C. Applied Math

1. i^i


2. Prove if $\lim_{z \rightarrow 0} f(z) = 0$ & $|g(z)| \leq M$ in some neighborhood of $z=0$
then $\lim_{z \rightarrow 0} f(z)g(z) = 0$

3. \underline{A} $n \times n$ has eigenvalues $\lambda_1, \dots, \lambda_n$

3.1 What are the eigenvalues of \underline{A}^{-1} ?

3.2 Prove it.

4. 4.1 Write down wave equation (1-Dimensional)

4.2. Given initial conditions, if the system is a circular string . What are the boundary conditions

4.3 solve it

4.4 Any other way to solve the equation?

4.5 How can a traveling wave represent a standing wave?

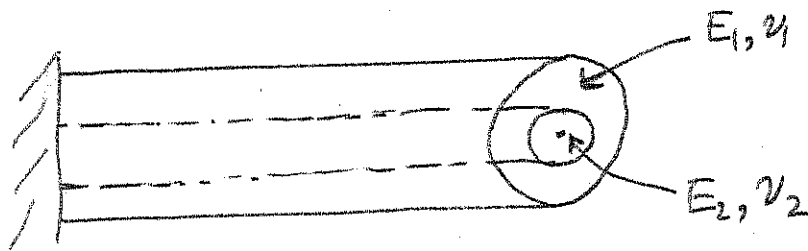
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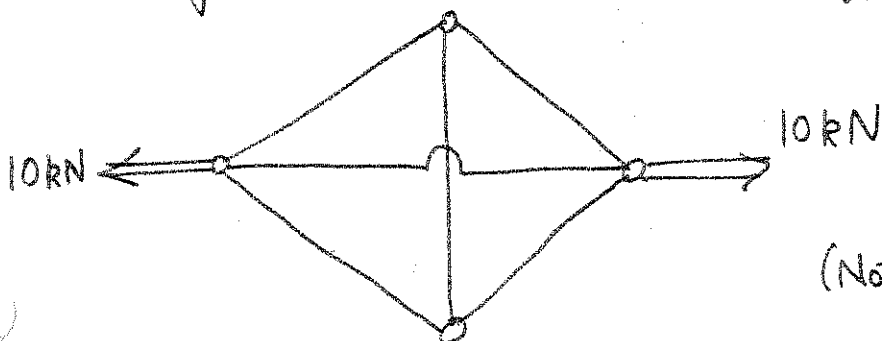
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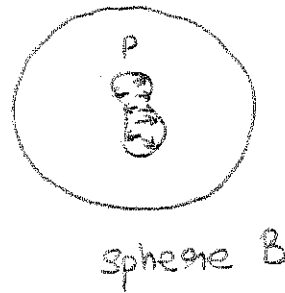
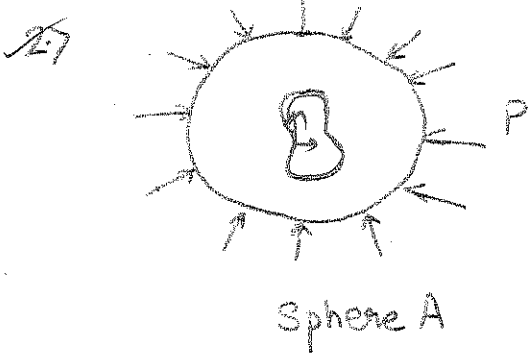
3) (Conway)



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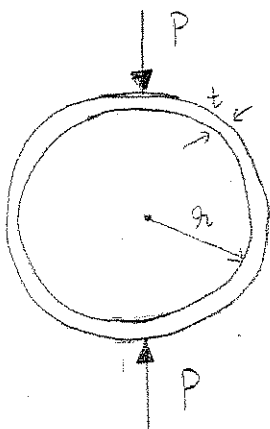
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