

Multi-Dof continued, Vibration Absorption, Normal Modes (see diagram from last class)

Guess: $\vec{x} = \vec{X} e^{i\omega t}$ $\rightarrow [-\omega^2 M + K] \vec{X} = \vec{0}$

A complicated solution is the sum of simple solutions



$$\begin{bmatrix} m & 0 & 0 \\ 0 & m & 0 \\ 0 & 0 & m \end{bmatrix} \begin{bmatrix} \ddot{x}_1 \\ \ddot{x}_2 \\ \ddot{x}_3 \end{bmatrix} + \begin{bmatrix} 2K & -K & 0 \\ -K & 2K & -K \\ 0 & -K & 2K \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

guess one of the mode shapes: $\vec{X} = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$ \rightarrow middle mass is stationary
left and right mass move opposite each other

$$\omega_1 = \sqrt{\frac{2K}{m}}$$

guess 2: $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ bad! masses cannot move together in the same direction

guess 3: $\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$ bad! effective stiffness is not equal for all 3 masses

Variable guess: $\begin{bmatrix} a \\ a \\ a \end{bmatrix}$ check: is $\frac{K}{m}$ effective for block 1 = $\frac{K}{m}$ effective for block 2

$$\frac{F/dl}{m_1} = \frac{Fa/da}{ma} \rightarrow \frac{(ak-ak)}{m_1} = \frac{ak(a-1)}{m_1}$$

$$(2-a)a = 2(a-1)$$

$$2a - a^2 = 2a - 2$$

$$a^2 = 2 \rightarrow a = \pm \sqrt{2}$$

$$\vec{x}_2 = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}, \vec{x}_3 = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{bmatrix} \quad \omega_1 = \sqrt{\frac{k}{m}(2-\sqrt{2})}, \omega_2 = \sqrt{\frac{k}{m}(2+\sqrt{2})}$$

Now add in forcing: $M\ddot{\vec{x}} + K\vec{x} = \vec{F}_0 \sin(\omega t)$

assume $\vec{x}_h(t \rightarrow \infty) = \vec{0}$, homogeneous solution decays in time due to damping

We need the particular solution: guess $\vec{x}(t) = \vec{x} \sin(\omega t) \rightarrow$ synchronous with the forcing

$$M\ddot{\vec{x}} + K\vec{x} = \vec{F}_0 \sin(\omega t)$$

$$\underbrace{(-\omega^2 M + K)}_A \vec{x} = \vec{F}_0$$

Assume $\omega \neq \omega_1 \rightarrow$ modal solution

$$\vec{x} = (-\omega^2 M + K)^{-1} \vec{F}_0$$

Force the system sinusoidally ($\sin(\omega t)$), eventually it shakes sinusoidally